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Model-Free, Internal-Variable-Free, **Data-Driven Plasticity**

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Data-Driven Science: Taxonomy

- The emerging paradigm: Data-Driven Science:
 - Model-based methods: Identify model from data
 - Model-free methods: Make predictions from data
- Data-Driven Computational Mechanics:
 - Deterministic problems:
 - History-independent (elasticity, dynamics...)
 - History-dependent (viscoelasticity, plasticity...)
 - Stochastic problems
- Data-Driven plasticity:
 - Internal-variable formulations
 - Internal-variable-free formulations (path based)
- Praxis: Data mining, path sampling, phase space coverage, accuracy, convergence...

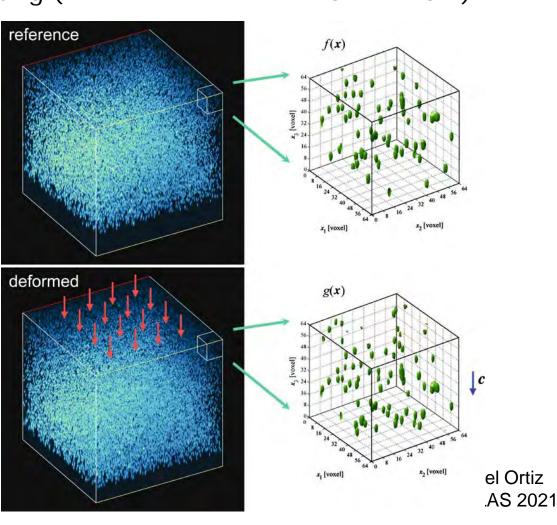
 Material data is currently plentiful due to dramatic advances in experimental science (DIC, EBSD, microscopy, tomography...) and multiscale computing (DFT → MD → DDD → SM → Hom)

Digital Volume Correlation
(DVC): Two confocal volume images of an agarose gel with randomly dispersed fluorescent particles before and after mechanical loading. The full displacement vector field is measured using 3D volume correlation methods.

C. Franck, S. Hong, S.A. Maskarinec, D.A. Tirrell & G. Ravichandran, *Experimental Mechanics*, **47** (2007) 427–438.

Data-Driven Identification:

A. Leygue, M. Coret, J. Réthoré, L. Stainier & E. Verron, *IJNME*, **331** (2018) 184-196.

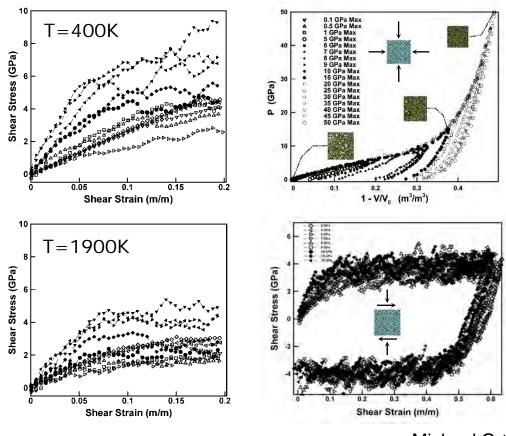


- Material data can also be generated in large volumes from high-fidelity micromechanical calculations (DFT, MD, DD...)
- New role for multiscale analysis: Data generation

Amorphous SiO₂ glass:

LAMMPS MD calculations of amorphous silica glass under *pressure-shear* loading over a range of *temperatures* and *strain rates*. RVEs are quenched from the melt, then analyzed using the BKS potential with Ewald summation.

Schill, W., Heyden, S., Conti, S.
& MO, *JMPS*, 113 (2018) 105-125.
Schill, W., Mendez, J.P., Stainier, L.
& MO, *JMPS*, 140 (2020) 103940.



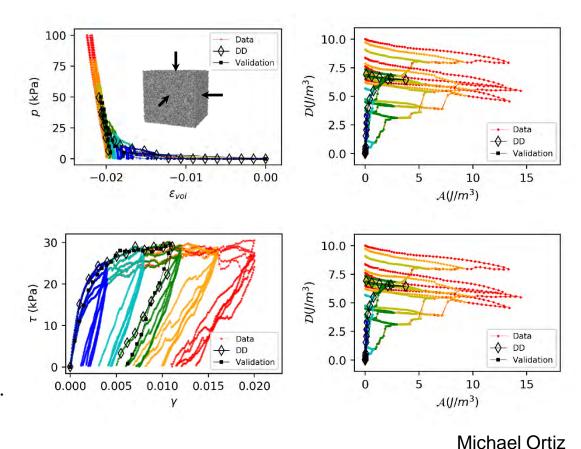
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- Material data can also be generated in large volumes from high-fidelity micromechanical calculations (DFT, MD, DD...)
- New role for multiscale analysis: Data generation

Granular matls. (dry sand):
Level-Set Discrete Element
Method (LS-DEM) simulation
of granular material samples.
3D irregular rigid particles
interact through frictional
contact. Particle morphology
described by level-set
functions. Note calculation of
dissipation and free energy.

Karapiperis, K., Harmon, J., And, E., Viggiani, G. & Andrade, J.E., *JMPS*, **144** (2020) 104103.

Karapiperis, K., Stainier, L., Ortiz, M. & Andrade, J.E., *JMPS*, **147** (2021) 104239.



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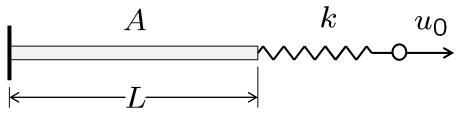
- The unprecedented abundance of material data presents new challenges and opportunities
- Two main strategies:
 - Model the data, use models in BVP calculations
 - Embed the data directly into BVP calculations

Model-Based: Data → Model → Prediction

Model-Free: Data → Prediction

- Critique of Model-Based computing: Modeling results in loss of information, introduces biases, modeling error, epistemic uncertainty, is open-ended, ad hoc...
- Model-Free computing: Cut out the middle man!

The data, all the data, nothing but the data



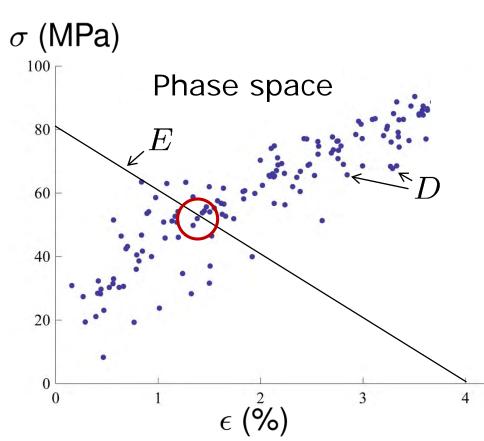
<u>Problem:</u> Bar actuated by loading device

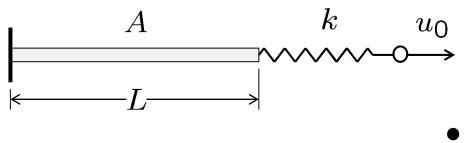
- Phase space: $\{(\epsilon, \sigma)\} \equiv Z$
- Compatibility + equilibrium: $\sigma A = k(u_0 \epsilon L)$
- Constraint set:

$$E = \{ \sigma A = k(u_0 - \epsilon L) \}$$

- Material data set: $D \subset Z$
- Data-Driven solution:

$$\min_{z \in E} \mathsf{dist}(z, D)$$





outlier!

 ϵ (%)

Phase space

 σ (MPa)

100

60

40

20

0

Problem: Bar actuated by loading device



Compatibility + equilibrium:

 $\sigma A = k(u_0 - \epsilon L)$

Constraint set:

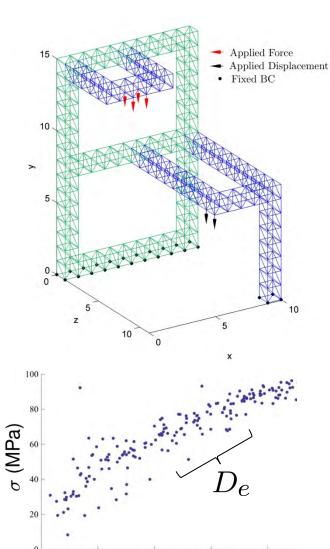
$$E = \{ \sigma A = k(u_0 - \epsilon L) \}$$

- Material data set: $D \subset Z$
- With outliers (k-means):

$$\min_{z \in E} \left(-\frac{1}{\beta} \log \sum_{i=1}^{N} \mathrm{e}^{-\beta \operatorname{dist}^2(y_i,z)} \right)$$

T. Kirchdoerfer and M. Ortiz, *CMAME*, **326** (2017) 622–641

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 ϵ (%)

<u>Problem:</u> Structure under applied loads and displacements

- Phase space: $\{(\epsilon_e, \sigma_e)_{e=1}^m\} \equiv Z$
- Compatibility + equilibrium:

$$\epsilon = Bu, \quad B^T \sigma = f$$

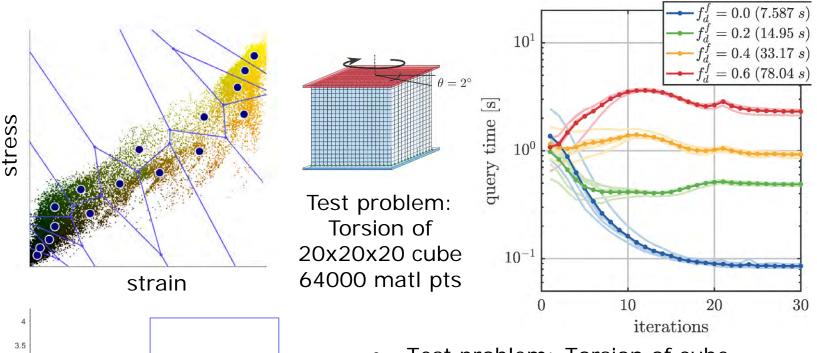
Constraint set:

$$E = \{(\epsilon, \sigma) : \epsilon = Bu, B^T \sigma = f\}$$

- Material data set: $D \subset Z$
- Data-Driven solution:

$$\min_{z \in E} \mathsf{dist}(z, D)$$

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4 3.5 3 2.5 2 1.5

K-means hierarchical structure

- Test problem: Torsion of cube
- Mesh: 20x20x20, 64000 matl pts
- Material data set: 1 billion points
- Approx k-means search, 0.1 secs
- Set-oriented machine learning!
- We learn the structure of the data set
- No regression, no loss of information!

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- History-independent Data-Driven problems can be extended to the *PDE* (*infinite-dimensional*) setting: Linear elasticity¹, finite elasticity^{2,3}...
- Well-established existence and uniqueness properties^{1,2} of solutions of Data-Driven BVPs
- Relaxation, approximation, Γ-convergence^{1,2}
- Convergence with respect to data, deterministic^{1,2} or stochastic (maximum likelihood⁴, inference⁵)
- History-independent Data-Driven problems are in good shape. History-dependent materials?

¹Conti, S., Müller, S. & Ortiz, M., ARMA, **229** (2018) 79-123.

²S. Conti, S. Müller and M. Ortiz, *ARMA*, **237** (2020) 1–33.

³A. Platzer, A. Leygue, L. Stainier and M. Ortiz, CMAME, 379 (2021) 113756.

⁴T. Kirchdoerfer and M. Ortiz, *CMAME*, **326** (2017) 622-41.

⁵S. Conti, F. Hoffmann and M. Ortiz, *arXiv* (2021) 2106 02728.

History-dependent materials

 Goal: Extend the Data-Driven paradigm to inelastic materials whose response is *history dependent*.

"The characteristic property of inelastic solids which distinguishes them from elastic solids is the fact that the stress measured at time t depends not only on the instantaneous value of the deformation but also on the entire history of deformation¹."

- The theory of materials with memory furnishes the most general representation of inelastic materials.
- Alternative: Replace history by the effects of history, the current *microstructure* (internal state)
- Variables used to describe that microstructure, within a *continuum thermodynamics* framework, are referred to as internal variables

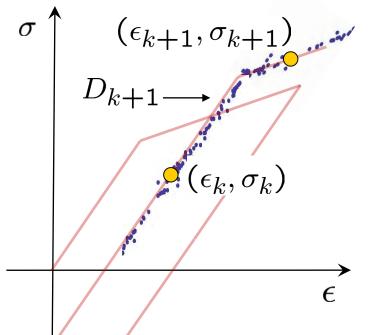
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A critique of internal variables

- The concept of *internal variables* was introduced into thermodynamics by Onsager (1931), applied to continuum mechanics by Eckart (1948), others...
- Kestin and Rice (1967): The internal variable formalism cannot represent materials with continuous relaxation spectrum (e.g., polymers)
- Phenomenological models: The choice of internal variables is often ad hoc, no notion of convergence
- Internal variables can be redundant and defined up to reparametrizations only (no intrinsic meaning)
- Instead: Develop Data-Driven representations that are internal-variable-free (path-based)! How?

• Incremental material set: Set of points in phase space accessible from (ϵ_k, σ_k) given prior history:

$$D_{k+1} = \{(\epsilon_{k+1}, \sigma_{k+1}) : (\epsilon_k, \sigma_k), \text{ history}\}\$$



• Data-driven problem:

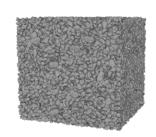
$$\min_{z \in E_{k+1}} d(z, D_{k+1})$$

- Need material history data! (from material testing along selected loading paths...)
- History data must provide adequate path coverage...
- How do we generate, store, structure, path data?

R. Eggersmann, T. Kirchdoerfer, L. Stainier, S. Reese and M. Ortiz, *CMAME*, **350** (2019) 81-99.

- How do we generate, store, structure, path data?
- What is the intrinsic structure of history-dependent (path) data for plastic materials?
- Need to revisit the differential geometry of incremental plasticity in phase space:
 - Non-integrable differential or Pfaffian forms...
 - Maximum-dissipation connections...
 - History data: Directed graphs in phase space!
- How do we provide adequate path coverage?
 Object-oriented path sampling, accuracy control, feedback...

- Geometry of phase-space trajectories?
- What neighboring points can be accessed incrementally along trajectories?



- Assume continuum thermodynamics with fully resolved internal state (micromechanical system)
- Free energy $A(\epsilon,\theta,q)$ convex, dual $A^*(\sigma,\eta,p)$ $\begin{vmatrix} \downarrow & \downarrow \\ \downarrow & \text{internal variables} \\ \text{temperature} & \text{temperature} \\ \text{strain} & \text{stress} \end{vmatrix}$
- By convexity and the Fenchel-Young theorem, the Coleman-Noll equilibrium relations are equivalent to

$$A + A^* - \sigma \cdot \epsilon + \eta \theta + p \cdot q = 0$$

- Geometry of phase-space trajectories?
- By convexity and the Fenchel-Young theorem, the Coleman-Noll equilibrium relations are equivalent to

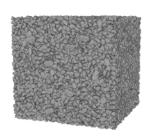
$$A + A^* - \sigma \cdot \epsilon + \eta \theta + p \cdot q = 0$$

- Assume rate-independent Onsager kinetics:
 - Elastic domain C, convex (by second law)
 - Dual dissipation potential: $\psi(\xi) = \sup\{p \cdot \xi : p \in C\}$
- By convexity and the Fenchel-Young theorem, the flow rule and yield condition are equivalent to:

$$\psi(dq) - p \cdot dq = 0$$
 and $p + dp \in C$

- Summary of governing equations:
 - Coleman-Noll equilibrium relations,

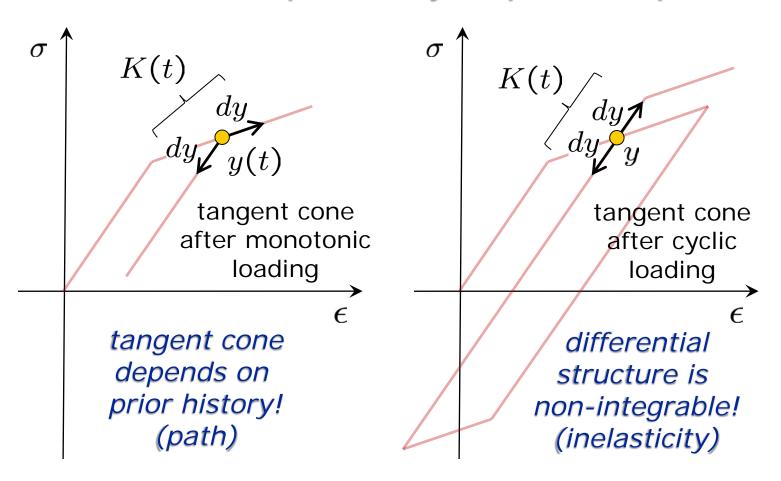
$$d(A + A^* - \sigma \cdot \epsilon + \eta \theta + p \cdot q) = 0$$



Incremental kinetic relations,

$$\psi(dq) - p \cdot dq = 0$$
 and $p + dp \in C$

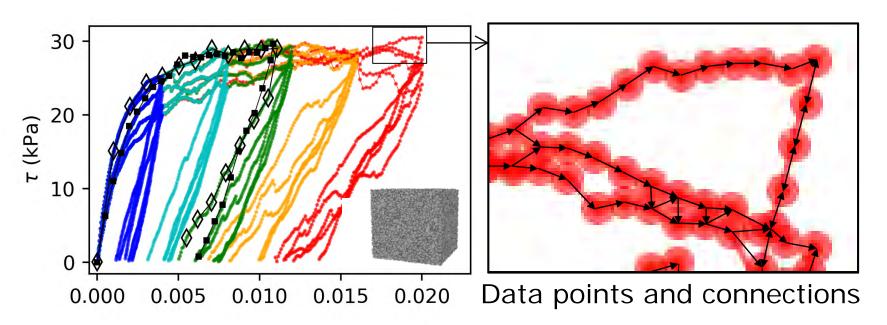
- Eliminate $(dq, dp) \Rightarrow$ tangent cone $K(t) = \{ dy = (d\epsilon, d\theta; d\sigma, d\eta) \text{ 'out of } y(t) ' \}$
- Tangent cone: Collection of possible connections between neighboring points in phase space
- Defines a (non-integrable) differential form
- Solutions are the *integral curves* (trajectories)



 Differential view of plasticity: Points in phase space and 'connections' between neighboring points defining possible incremental moves...

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Building path data from micromechanics

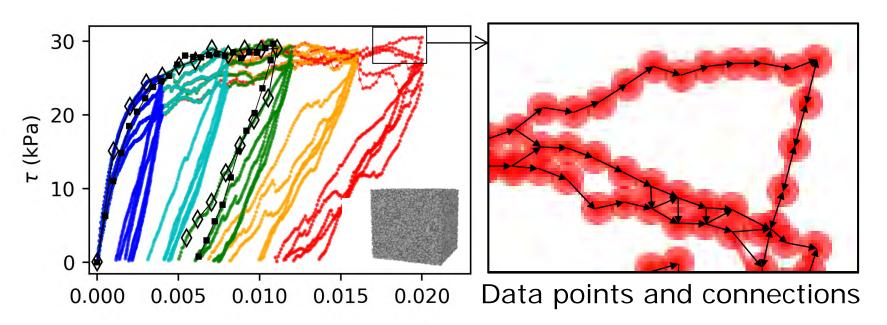


- i) Evaluate RVE for selected loading paths
- ii) Record $(\epsilon_i, \theta_i; \sigma_i, \eta_i)$, connect points i and j if

$$\psi(q_j - q_i) - \langle \frac{p_i + p_j}{2}, q_j - q_i \rangle \leq \mathsf{TOL}$$

iii) Discard internal state (q_i, p_i) (int. var. free!)

Building path data from micromechanics

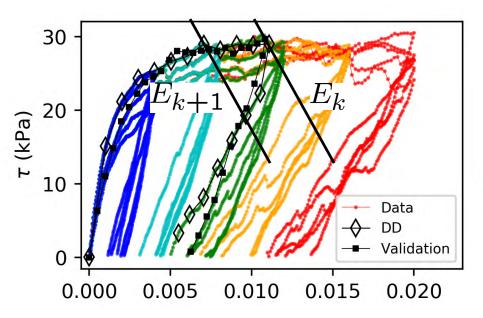


- i) Evaluate RVE for selected loading paths
- ii) Record $(\epsilon_i, \theta_i; \sigma_i, \eta_i)$, connect points i and j if

$$Diss_{i \to j} + A_j - A_i - \langle \frac{\sigma_i + \sigma_j}{2}, \epsilon_j - \epsilon_i \rangle \leq \mathsf{TOL}$$

iii) Discard internal state (q_i, p_i) (int. var. free!)

Incremental Data-Driven plasticity problem





Direct shear test device

- Material data set: Directed graphs in phase space!
- Incremental material data set:

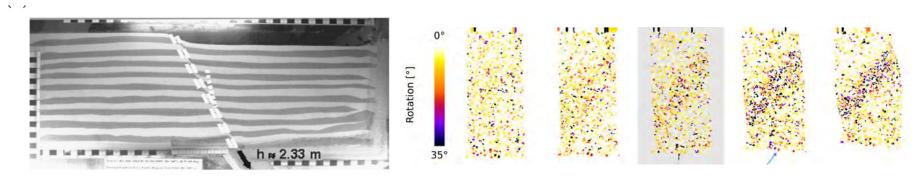
$$D_{k+1} = \{(\epsilon_{k+1}, \sigma_{k+1}) : \text{accessible from } (\epsilon_k, \sigma_k)\}$$

• Data-driven problem: $\min_{z \in E_{k+1}} d(z, D_{k+1})$

$$\min_{z \in E_{k+1}} d(z, D_{k+1})$$

Path dependence, loading/unloading irreversibility!

Test case – Data-Driven sand mechanics



Fault rupture experiment in sandbox configuration.
Sand is pluviated into a 10m x 30m container.
A piston forces right half to subside, inducing fault rupture at 30° to horizontal

¹Anastasopoulos, I., *et al.*, *J. Geotech. Geoenviron. Eng.*, **133** (2007) 943–958.

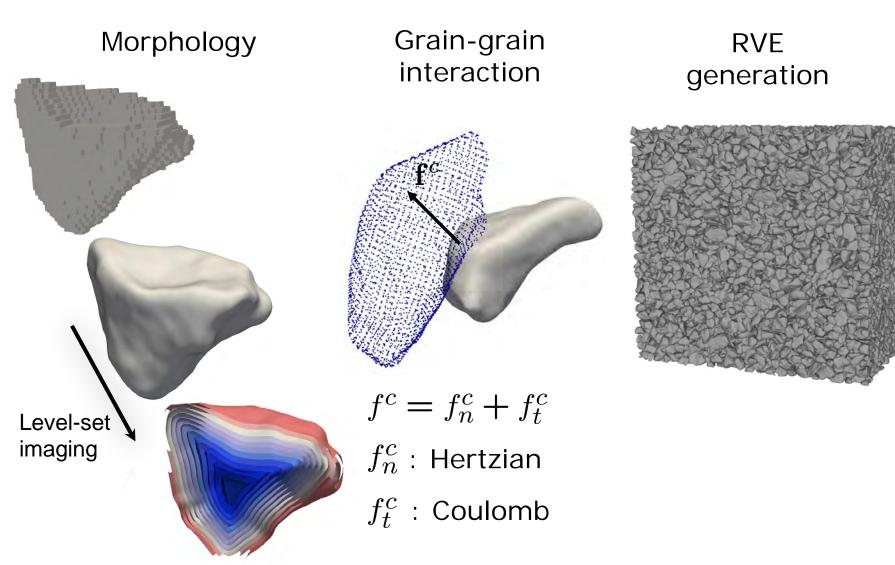
Triaxial compression test,²
angular Hostun sand,
100 kPa confining pressure,
11 mm x 22 mm samples
in latex membrane.
Particles tracked by XRMT.
Failure occurs by
shear banding

²Andò, E., *et al.*, *Acta Geotech.*, **7** (2012) 1-13.

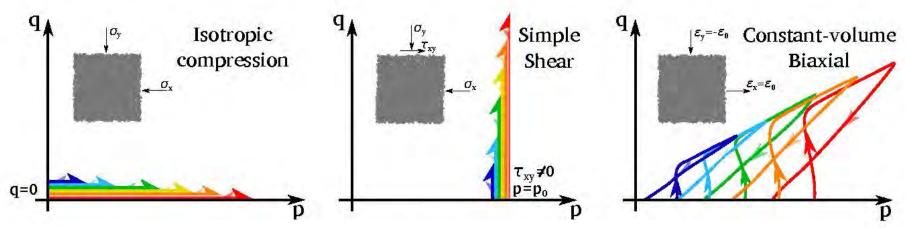
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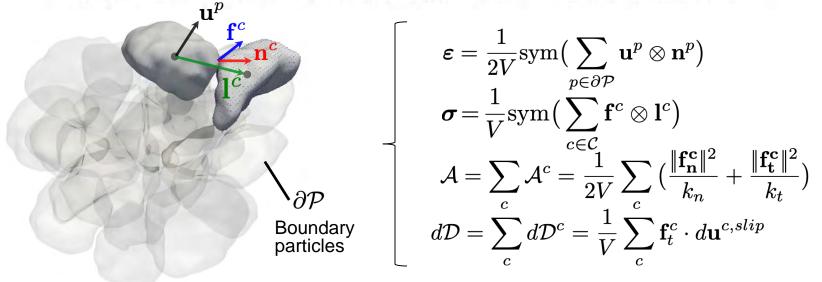
Virtual experiments with LS-DEM



Hastun angular sand – Path sampling



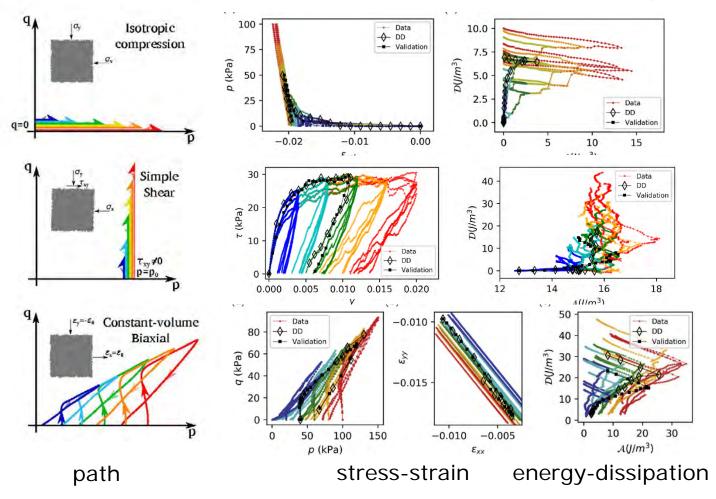
Selected paths for building the material data repository



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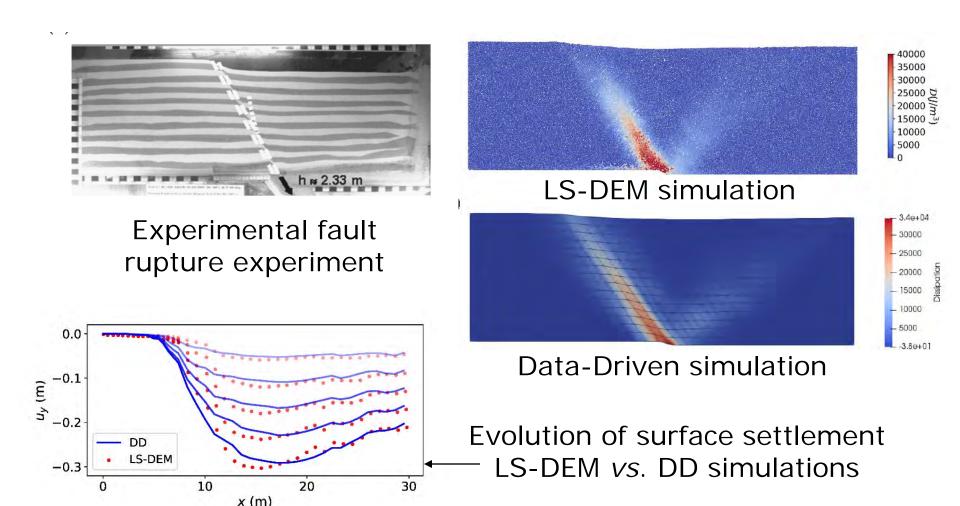
K. Karapiperis, L. Stainier, M. Ortiz, J.E. Andrade, JMPS, (2020) 104239.

Hastun angular sand – Path sampling



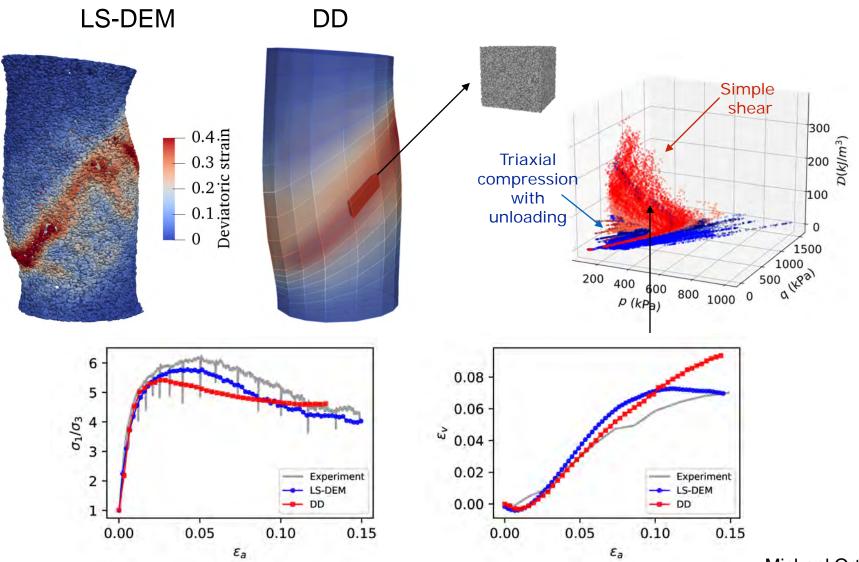
Compilation of path data for Hatsun angular sand computed from RVEs using LS-DEM

Sand mechanics – Fault rupture experiment



Anastasopoulos, I., et al., J. Geotech. Geoenviron. Eng., 133 (2007) 943–958. Michael Ortiz K. Karapiperis, L. Stainier, M. Ortiz, J.E. Andrade, JMPS, (2020) 104239. COMPLAS 2021

Data-Driven – Fault rupture experiment



K. Karapiperis, L. Stainier, M. Ortiz, J.E. Andrade, JMPS, (2020) 104239.

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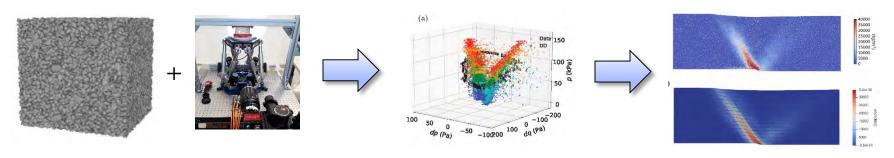
Path selection, coverage, convergence

- Path coverage must be goal oriented (tailored to specific problems)
- Main path types are often known beforehand for specific problems (initial path-data repository)
- Monitor local path-distance error at individual material points
- Evaluate RVEs for local paths that are farther from the existing path repository than a given tolerance
- Add new RVE path data to repository
- Iterate till convergence

Karapiperis, Konstantinos (2021) <u>Multiscale, Data-Driven</u> <u>and Nonlocal Modeling of Granular Materials.</u> Dissertation (Ph.D.) California Institute of Technology. doi:10.7907/7rtg-x780. https://resolver.caltech.edu/CaltechTHESIS:12182020-181342301

Concluding remarks

- It is possible to formulate DD approximation schemes for history-dependent materials that are model-free and internal-variable free
- Path data for rate-independent plasticity has the structure of directed graphs in phase space
- DD sets forth new opportunities for synergism between experimental science and scientific computing, new multiscale analysis paradigm



 Model-free DD mechanics represents a paradigm shift in material data management and exchange in the mechanics of materials community

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Concluding remarks

Thank you!