



Model-Free Data-Driven Science: Cutting out the Middleman

$$\inf_{y \in D} \inf_{z \in E} \|y - z\| = \inf_{z \in E} \inf_{y \in D} \|y - z\|$$

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Oberseminar "Mathematische Modelle"
Fakultät für Mathematik (M6)
Technische Universität München
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Outline

- Background and motivation:
 - *New emerging paradigm: **Data-Driven Science***
 - *How does Data Science intersect with the **physical sciences**? With **experimental science**?*
 - *Why Data-Driven science now? **What has changed**?*
 - *What are **Model-Free Data-Driven problems**?*
 - ***Theory vs. practice**: Solvers, fast search algorithms, set-oriented machine learning, data mining, data repositories, data management...*
- Analysis: **Data-Driven problems in elasticity**:
 - Existence and uniqueness of solutions
 - The topology of data convergence
 - Data-Driven relaxation
 - Extension to finite kinematics

The anatomy of field theories

- Focus on problems in the *physical sciences* (as opposed to finance, marketing, social sciences...)
- Problems in the physical sciences deal with *field theories*
- All field theories have a *common structure*:

Field	Potential	Conservation	Material law
Gravitation	$g = -\nabla\phi$	$\nabla \cdot f + 4\pi\rho = 0$	$f = g/G$ (Newton)
Electrostatics	$E = -\nabla V$	$\nabla \cdot D = 4\pi\rho$	$D = \epsilon E$
Electromagnetics	$B = \nabla \times A$	$\nabla \times H = J$	$H = B/\mu$
Diffusion	$g = -\nabla c$	$\nabla \cdot J + s = 0$	$J = D g$ (Fick)
Heat transfer	$g = -\nabla T$	$\nabla \cdot J + s = 0$	$J = \kappa g$ (Fourier)
Elasticity	$\epsilon = \text{sym} \nabla u$	$\nabla \cdot \sigma + f = 0$	$\sigma = \mathbb{C} \epsilon$ (Hooke)
General	$\epsilon = \delta u$	$\partial \sigma + f = 0$??

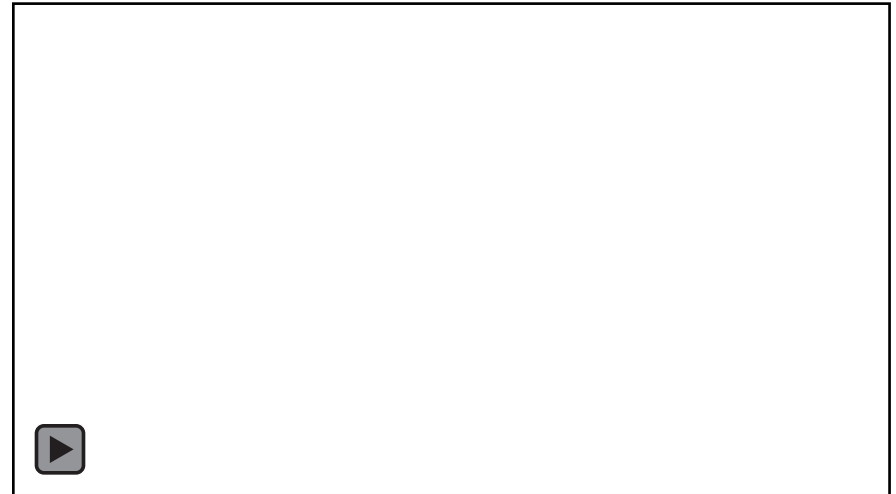
- Potential relations and conservation laws are *universal*!
- *Material laws need to be defined empirically!*

The new data-rich world...

- Material *data is currently plentiful* due to dramatic advances in experimental science (DIC, EBSD, microscopy, tomography...) and multiscale computing (DFT → MD → DDD → SM → Hom)



3D tomographic reconstruction
of particles in battery electrode



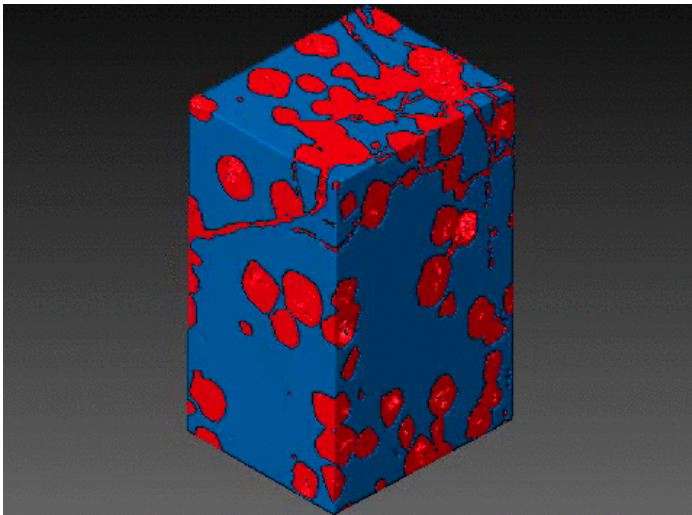
3D DIC-measured
internal-strain full-field
compressed PDMS sample

John Lambros, UIUC,
<https://lambros.ae.illinois.edu/moviesimages/>

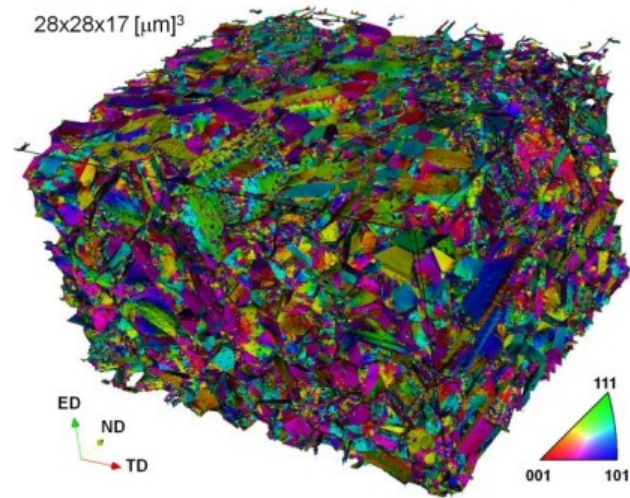
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Two-phase μ CT analysis of Ti₂AlC/Al composite¹



3D EBSD microstructure in Cu-0.17wt%Zr after ECAP²

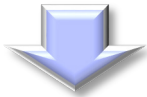
¹Hanaor *etal*, *Mater Sci Eng A*, **672** (2019) 247.

²Khorashadizadeh, *Adv Eng Mater*, **13** (2011) 237.

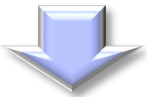
Adapting to a new data-rich world...

Classical Model-Based Computational Science...

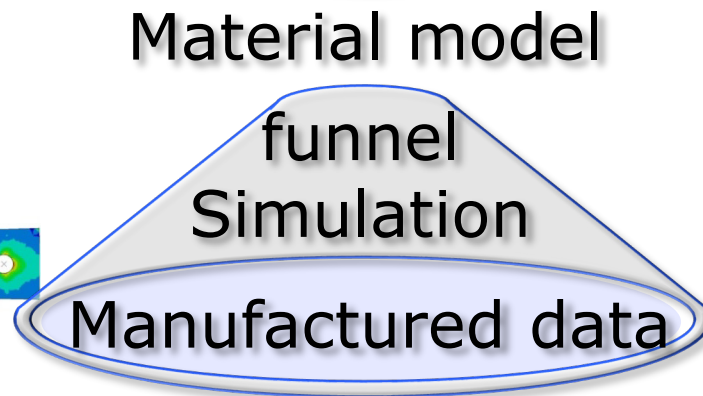
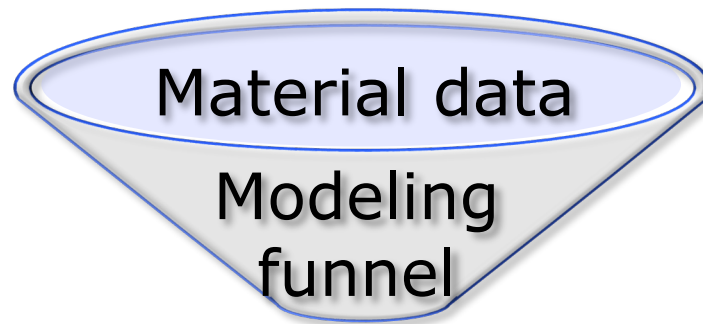
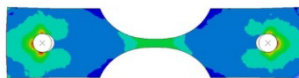
Modern
microscopy
generates
massive
data sets



$$\sigma = \mathbb{C}\epsilon$$



*Modelling
entails
massive
loss of
information!*



Adapting to a new data-rich world...

- *Modeling* = Any operation that changes the data set
- Modeling usually entails *massive loss of information* from material data sets, *epistemic uncertainty...*
- Material modeling is *ad hoc, open ended, ill-posed*
- There is *no theory* that determines material models from first principles to a desired level of accuracy
- Modeling requires *heuristics and intuition*: Models are *only as good as the modeler's* physical intuition
- Example of modeling: *Deep Learning = piecewise-linear regression* (cf., e.g., Gilbert Strang, 2019), requires *ad hoc guessing* of effective variables (a.k.a. 'features')
- *Direct connection between data and prediction?* Goal:

Classical inference: Data \rightarrow Model \rightarrow Prediction

Model-Free Data-Driven inference: Data \longrightarrow Prediction

(cut out the middleman!)

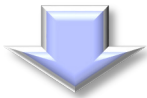
Adapting to a new data-rich world...

Classical Model-Based
Computational Science...

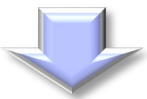


*Alternative:
Model-Free
Data-Driven
Computing!*

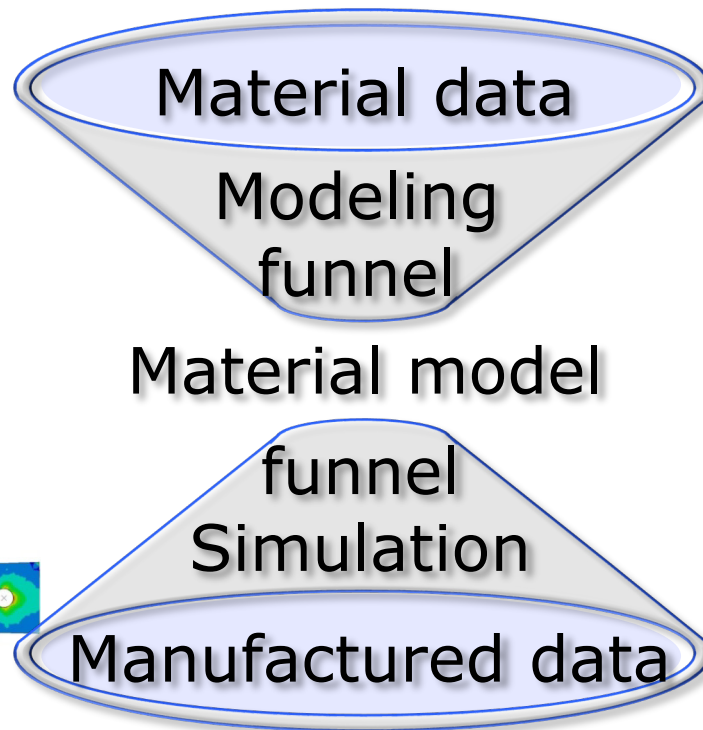
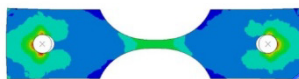
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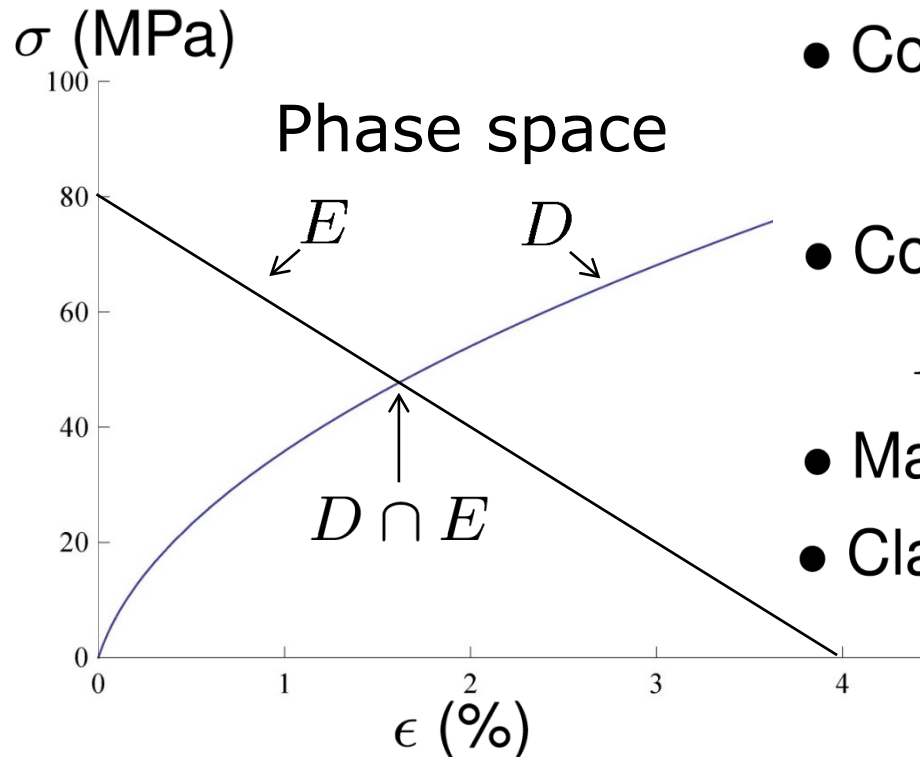
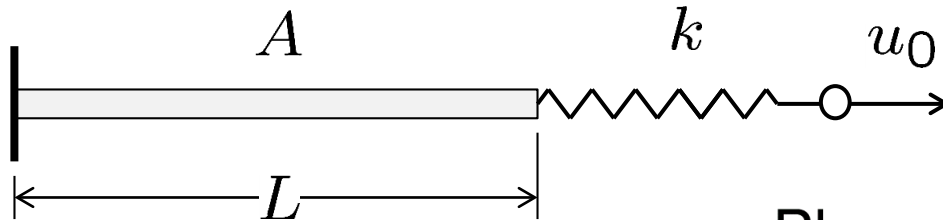


Set/solve
problems
directly
from data!

*Eliminate
modeling
bottleneck!*

How?

Elementary example: Bar and spring



- Phase space: $\{(\epsilon, \sigma)\} \equiv Z$

- Compatibility + equilibrium:

$$\sigma A = k(u_0 - \epsilon L)$$

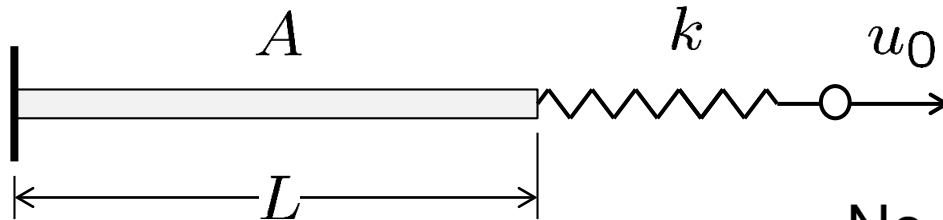
- Constraint set:

$$E = \{\sigma A = k(u_0 - \epsilon L)\}$$

- Material data set: $D \subset Z$

- Classical solution set: $D \cap E$

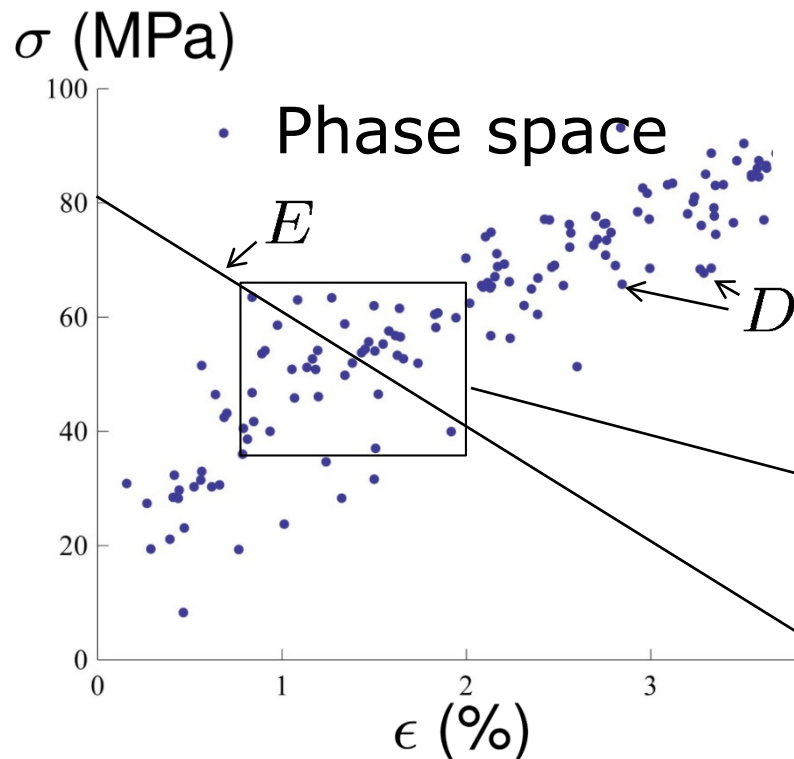
Elementary example: Bar and spring



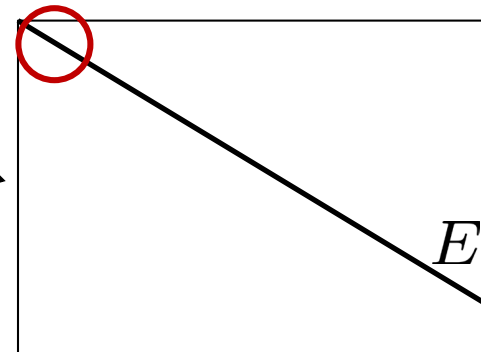
- No classical solutions!

$$D \cap E = \emptyset$$

- Data-driven solution:



$$\min_{z \in E} \text{dist}(z, D)$$



Model-Free Data-Driven paradigm

- The *Model-Free Data-Driven paradigm*¹: Given,
 - $D = \{\text{fundamental material data}\},$
 - $E = \{\text{compatibility} + \text{equilibrium}\},$

$$\inf_{y \in D} \inf_{z \in E} \|y - z\| = \inf_{z \in E} \inf_{y \in D} \|y - z\|$$

- *Aim of Model-Free Data-Driven problems is to find the admissible state (compatibility and equilibrium) in phase space (stress, strain) closest to the material data set*
- Raw *fundamental material data* (stress and strain) is used (unprocessed) in the formulation of the problems
- *No material modeling, no biasing, no loss of information:
The data, all the data, nothing but the data!*

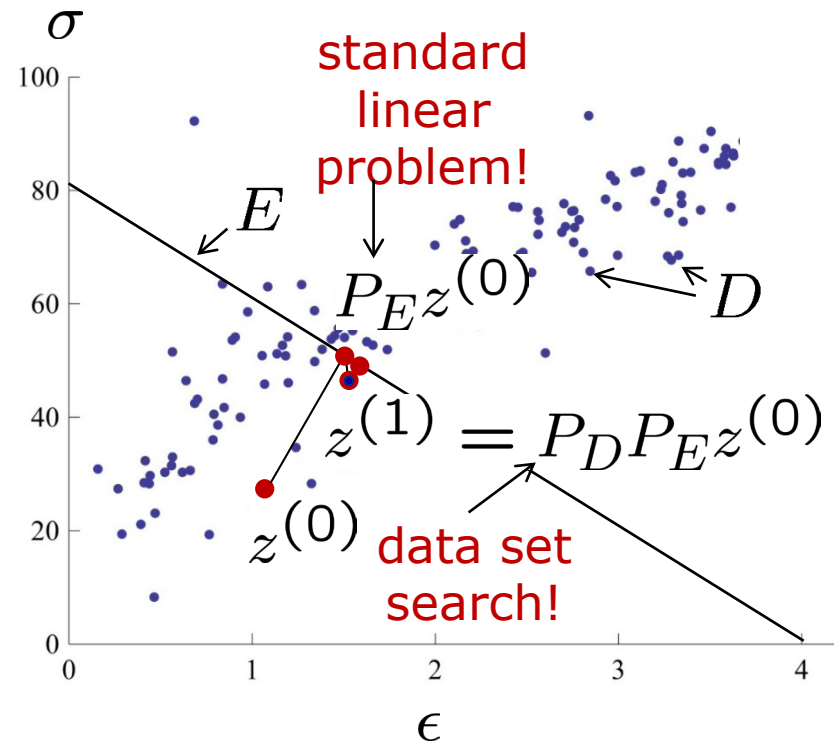
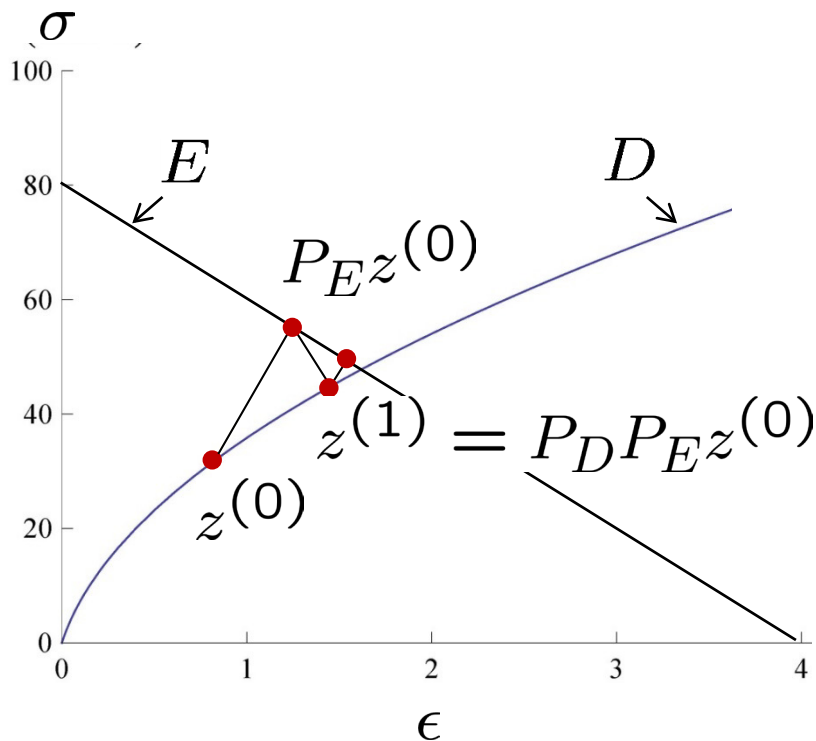


¹T. Kirchdoerfer and M. Ortiz (2015) arXiv:1510.04232.

¹T. Kirchdoerfer and M. Ortiz, *CMAME*, **304** (2016) 81–101

DD solvers: Fixed-point iteration

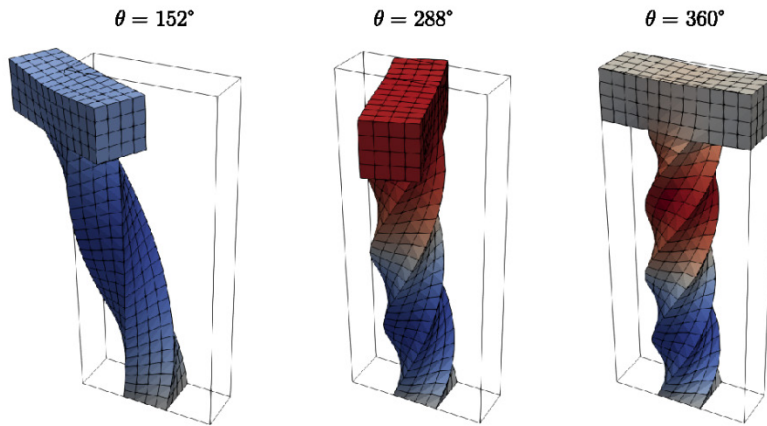
- Closest-point projections to E and D : P_E , P_D
- *Fixed-point iteration*: $z^{(k+1)} = P_E P_D z^{(k)}$



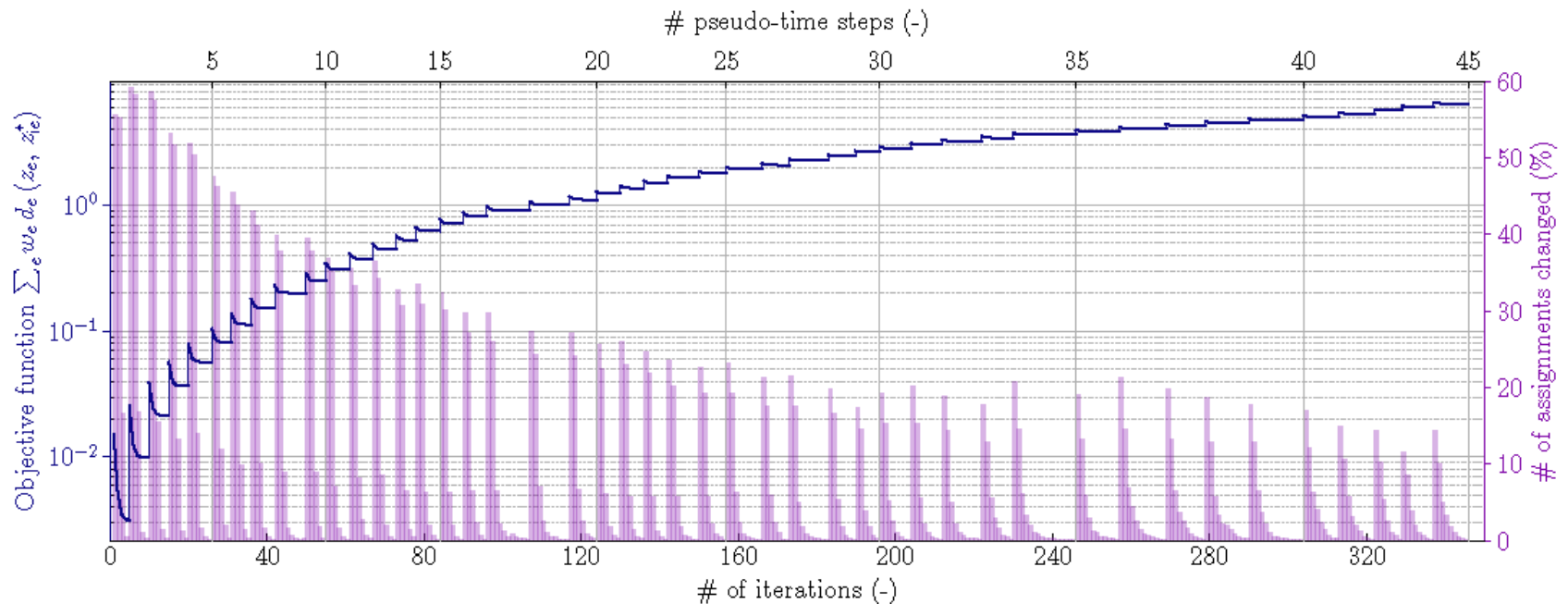
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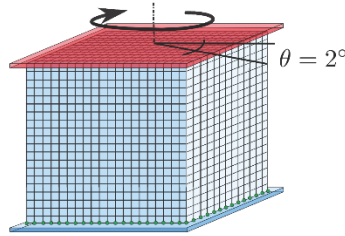
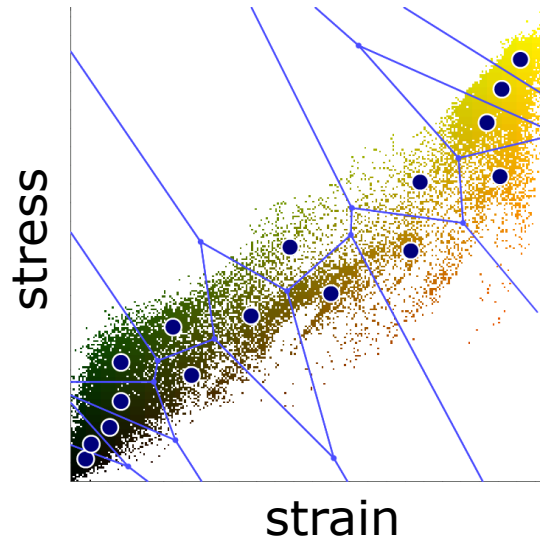
DD solvers: Fixed-point iteration



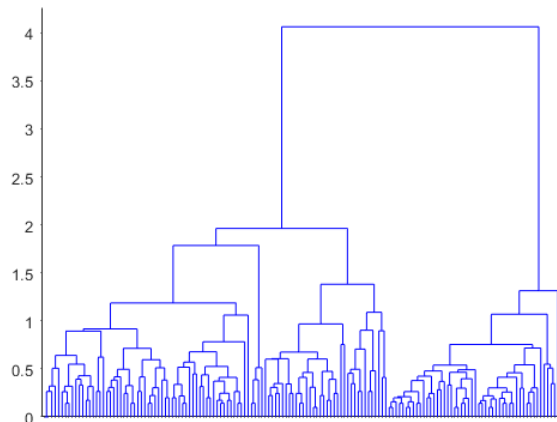
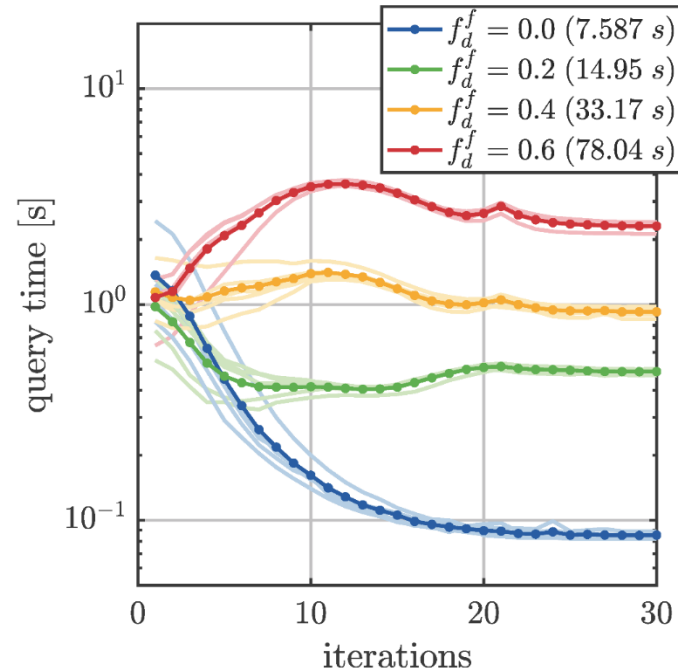
- Twisting of isotropic-elastic rod
- Randomized Green-Saint Venant
- 10,000,000 data points
- Linear convergence of fixed-point iteration wrt number of iterations
- Convergence with respect to data set size (uniform approximation)



Connection with Machine Learning



Test problem:
Torsion of
20x20x20 cube
64000 mat pts

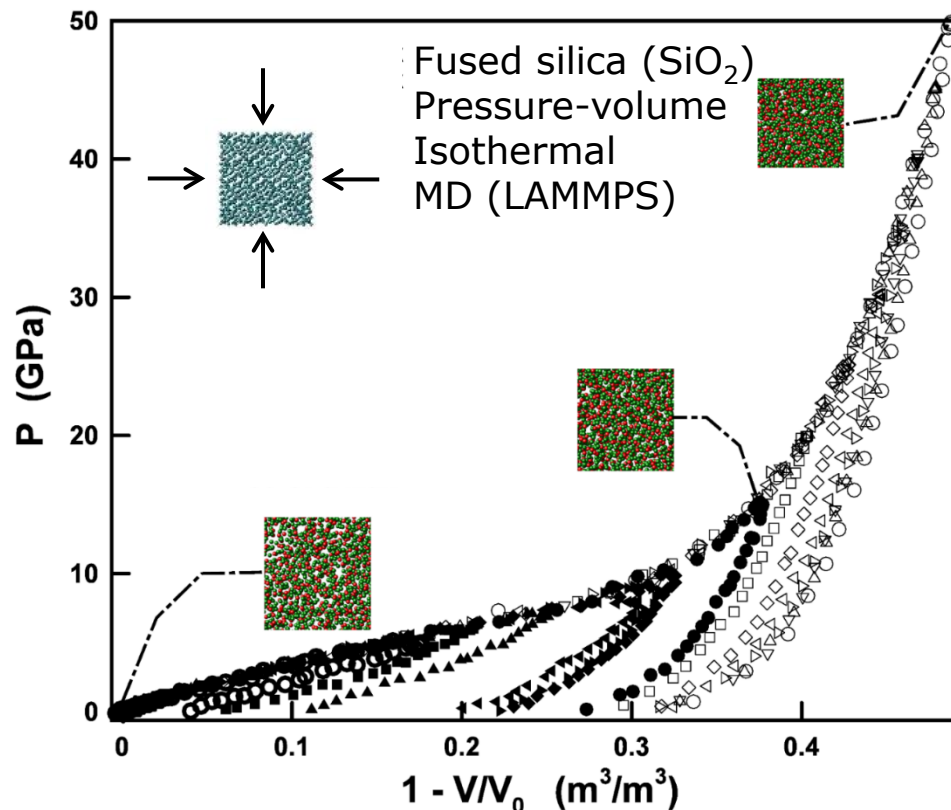


K-means hierarchical structure

- Material data set: *1 billion points*
- Approx k-means search, 0.1 secs
- *Set-oriented machine learning!*
- We learn the *structure of the data set*
- No regression, *no loss of information!*
- *The data, all the data, nothing but the data!*

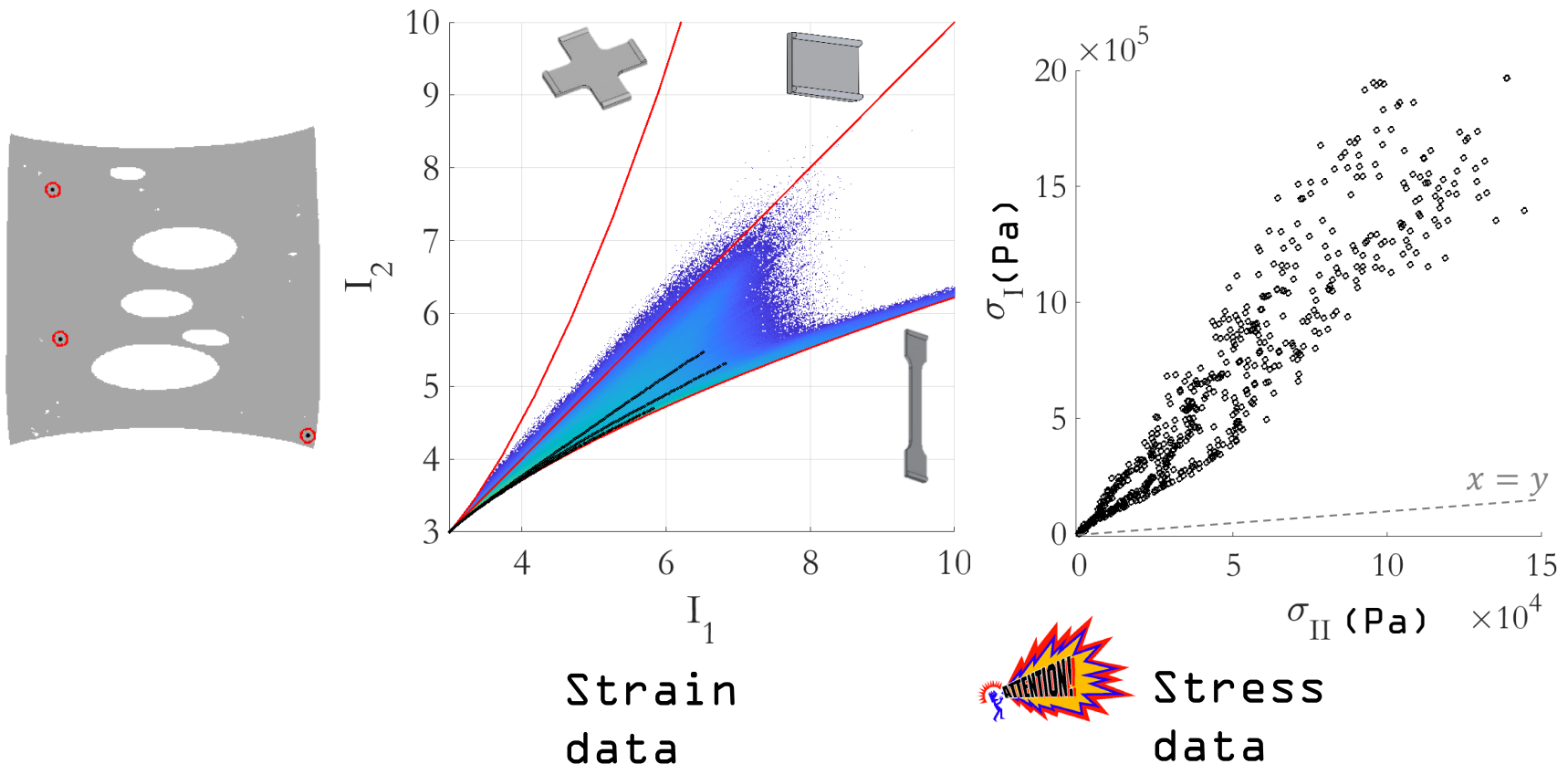
Connection with multiscale analysis

- Generate *material data* from microscale *RVE calculations*
- *Upscale data directly to macroscale (no effective model!)*



Connection with experimental science

- Generate full-field microscopy data using DIC
- *Infer stresses from inverse Data-Driven problem!*



M. Dalémat, M. Coret, A. Leygue and E. Verron,
Mechanics of Materials, **136** (2019) 103087.

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Data-Driven problems – Analysis

Problem (General Data-Driven problem)

Given:

- Phase space \mathcal{Z} (determined by field equations)
- Material-data set $\mathcal{D} = \{y \in \mathcal{Z} : \text{observed}\}$ (measured, *ab initio*)
- Constraint set $\mathcal{E} = \{z \in \mathcal{Z} : \text{field equations}\}$ (from field theory)

Minimize: $d(z, \mathcal{D}) + I_{\mathcal{E}}(z)$, or $d^2(y, z) + I_{\mathcal{D}}(y) + I_{\mathcal{E}}(z)$

- Well-posedness? (existence, uniqueness)
- Convergence with respect to data?
- Relaxation, weak convergence?
- Extension to finite kinematics?

Conti, S., Müller, S. & MO. Data-Driven Problems in Elasticity. *ARMA* **229**, 79–123 (2018).

Conti, S., Müller, S. & MO. Data-Driven Finite Elasticity. *ARMA* **237**, 1–33 (2020).

Data-Driven (small-strain) elasticity

$\Omega \subset \mathbb{R}^n$ open, bounded, Lipschitz boundary

$\partial\Omega = \bar{\Gamma}_D \cup \bar{\Gamma}_N$, Γ_D , Γ_N sufficiently regular, $\mathcal{H}^{n-1}(\Gamma_D) \neq 0$

Phase space: $\mathcal{Z} = \{(\epsilon, \sigma) : \epsilon \in L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n}), \sigma \in L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n})\}$

Constraint set $\mathcal{E} \subset \mathcal{Z}$ consists of pairs (ϵ, σ) which satisfy:

- i) Compatibility: $\epsilon = 1/2(Du + Du^T)$, $u = g$ on Γ_D .
- ii) Equilibrium: $\text{div } \sigma + f = 0$, $\sigma \nu = h$ on Γ_N .

Material data set $\mathcal{D} = \{(\epsilon, \sigma) \in \mathcal{Z} : (\epsilon(x), \sigma(x)) \in \mathcal{D}_{\text{loc}} \text{ a. e.}\}$

Hooke's law: $\mathcal{D}_{\text{loc}} = \{(\epsilon, \sigma) \in \mathcal{Z}_{\text{loc}} = \mathbb{R}_{\text{sym}}^{n \times n} \times \mathbb{R}_{\text{sym}}^{n \times n} : \sigma = \mathbb{C}\epsilon\}$

Distance on \mathcal{Z} , $d(y, z) = \|y - z\|$,

$$\|z\|^2 = \int_{\Omega} \frac{1}{2} \left(\mathbb{C}\epsilon \cdot \epsilon + \mathbb{C}^{-1}\sigma \cdot \sigma \right) dx, \quad z = (\epsilon, \sigma), \quad \mathbb{C} > 0$$

NB: *Universal field equations* and *material-specific data* (field-theories of physics, rational mechanics, Truesdell, Noll, ..., Tartar'70s)

Classical solutions are subsumed within DD solutions

Theorem

Assume: $f \in L^2(\Omega; \mathbb{R}^n)$, $g \in H^{1/2}(\partial\Omega; \mathbb{R}^n)$, $g \in H^{-1/2}(\partial\Omega; \mathbb{R}^n)$. Let \mathcal{E} be the constraint set and let

$$\mathcal{D} = \{(\epsilon, \sigma) \in \mathcal{Z} : \sigma(x) = \mathbb{C}\epsilon(x), \text{ a. e.}\}, \quad \mathbb{C} > 0,$$

be the material data set for Hooke's law. Then, the Data-Driven problem

$$\min\{d(z, \mathcal{D}), \ z \in \mathcal{E}\},$$

has a unique solution in \mathcal{Z} . Furthermore, the Data-Driven solution satisfies

$$\sigma = \mathbb{C}\epsilon.$$

NB: Similarly for $\mathcal{D}_{\text{loc}} = \{(\epsilon, \sigma) \in \mathcal{Z}_{\text{loc}} : \sigma = \hat{\sigma}(\epsilon)\}$ with $\hat{\sigma}$ uniformly monotone (using div-curl Lemma of Murat-Tartar)

Classical solutions are subsumed within DD solutions

Distance identity: $d^2(z, \mathcal{D}) = \int_{\Omega} \frac{1}{4} \mathbb{C}^{-1}(\sigma - \mathbb{C}\epsilon) \cdot (\sigma - \mathbb{C}\epsilon) \, dx.$

Lemma (Power identity)

$$(\epsilon, \sigma) \in \mathcal{E} \Rightarrow \int_{\Omega} \sigma(x) \cdot \epsilon(x) \, dx = \int_{\Omega} f(x) \cdot u(x) \, dx + \int_{\Gamma_D} \sigma(x) \nu(x) \cdot g(x) \, d\mathcal{H}^{n-1}(x) + \int_{\Gamma_N} h(x) \cdot u(x) \, d\mathcal{H}^{n-1}(x).$$

Lemma (Tensor Helmholtz decomposition)

$$M = \{e(u), \, u \in H^1(\Omega; \mathbb{R}^n), \, u = 0 \text{ on } \Gamma_D\}, \\ N = \{\sigma \in L^2(\Omega; \mathbb{R}_{\text{sym}}^{n \times n}), \, \operatorname{div} \sigma = 0, \, \sigma \nu = 0 \text{ on } \Gamma_N\},$$

are strongly (and weakly) closed in $L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n})$, $L^2(\Omega; \mathbb{R}_{\text{sym}}^{n \times n}) = M \oplus N$ and the decomposition is orthogonal.

Classical solutions are subsumed within DD solutions

Proof.

Apply direct method of the CoV to $F(z) = d^2(z, \mathcal{D}) + I_{\mathcal{E}}(z)$.

i) *Lower-semicontinuity*: By the tensor Helmholtz decomposition lemma and Hahn-Banach, \mathcal{E} is weakly closed in \mathcal{Z} and $I_{\mathcal{E}}(z)$ is weakly lower-semicontinuous. By the convexity of \mathcal{D} , $d^2(z, \mathcal{D})$ is also weakly lower-semicontinuous in \mathcal{Z} .

ii) *Compactness*: With $z = (\epsilon, \sigma)$, we have the identity

$$\|z\|^2 = 2d^2(z, \mathcal{D}) - \int_{\Omega} \sigma \cdot \epsilon \, dx$$

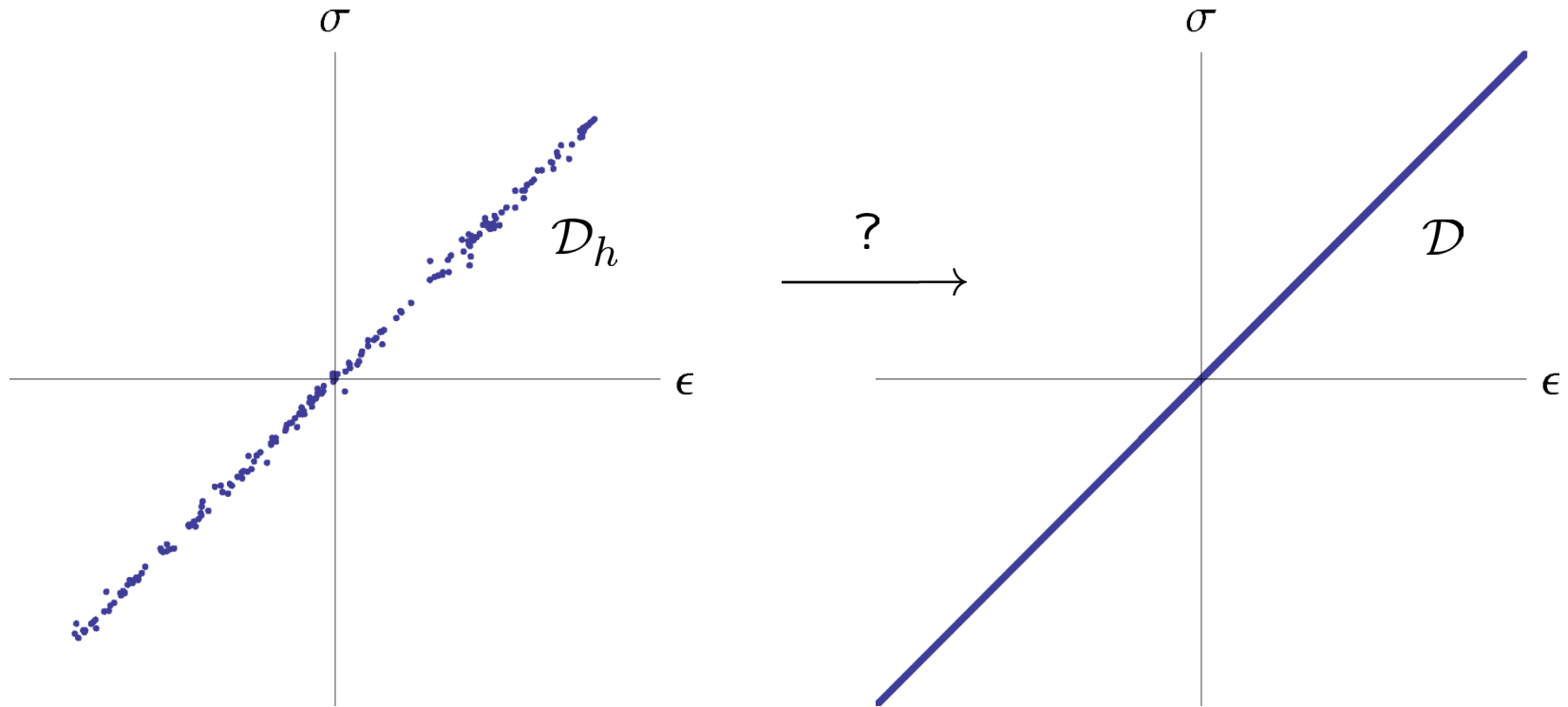
By the power identity, Korn, Poincaré and trace theorems, with $z \in \mathcal{E}$,

$$\|z\|^2 \leq 2d^2(z, \mathcal{D}) + C\|z\| \Rightarrow \text{coercivity}$$

iii) *Uniqueness* follows from convexity and $\sigma = \mathbb{C}\epsilon$ from the Euler-Lagrange equations.



The topology of data convergence



- We are given a *sequence* of material data sets (sampling)
- The sequence *approximates* a *limiting material data set*
- What *topology of convergence* of material data sets ensures convergence of the corresponding Data-Driven solutions?
- *Two cases*: Limiting material data set is: i) weakly closed; ii) not weakly closed.

The topology of data convergence

Definition (Mosco convergence of functions and sets)

A sequence (F_h) of functions from a Banach space X to $\overline{\mathbb{R}}$ converges to $F : X \rightarrow \overline{\mathbb{R}}$ in the sense of Mosco, or $F = M\text{-}\lim_{h \rightarrow \infty} F_h$, if

- i) For every sequence (x_h) converging weakly to x in X ,
 $\liminf_{h \rightarrow \infty} F_h(x_h) \geq F(x)$.
- ii) For every $x \in X$, there is a sequence (x_h) converging strongly to x in X such that $\lim_{h \rightarrow \infty} F_h(x_h) = F(x)$.

A sequence (\mathcal{E}_h) of subsets of X converges to $\mathcal{E} \subset X$ in the sense of Mosco, or $\mathcal{E} = M\text{-}\lim_{h \rightarrow \infty} \mathcal{E}_h$, if $I_{\mathcal{E}} = M\text{-}\lim_{h \rightarrow \infty} I_{\mathcal{E}_h}$.

Lemma

Every Mosco limit functional F is weakly sequentially lower semicontinuous. In particular, every Mosco limit set \mathcal{E} is weakly sequentially closed and $\mathcal{E} = M\text{-}\lim_{h \rightarrow \infty} \mathcal{E}$ if and only if \mathcal{E} is weakly sequentially closed.

The topology of data convergence

Theorem

Let Z be a reflexive, separable Banach space, \mathcal{D} and (\mathcal{D}_h) subsets of Z , \mathcal{E} a weakly sequentially closed subset of Z . Suppose:

- i) (Mosco convergence) $\mathcal{D} = M\text{-}\lim_{h \rightarrow \infty} \mathcal{D}_h$ in Z .
- ii) (Equi-transversality) There are constants $c > 0$ and $b \geq 0$ such that, for all $y \in \mathcal{D}_h$ and $z \in \mathcal{E}$,

$$\|y - z\| \geq c(\|y\| + \|z\|) - b.$$

Then, $I_{\mathcal{E}}(\cdot) + d^2(\cdot, \mathcal{D}) = \Gamma\text{-}\lim_{h \rightarrow \infty} \left(I_{\mathcal{E}}(\cdot) + d^2(\cdot, \mathcal{D}_h) \right)$, with respect to the weak topology of Z .

NB Mosco convergence supplies the right topology for sequences of material data sets when the limiting set is weakly continuous.

The topology of data convergence

Proof.

i) *Equi-coercivity*. With $F_h(z) = I_{\mathcal{E}}(z) + d^2(z, \mathcal{D}_h)$, by transversality,

$$\sqrt{F_h(z)} \geq I_{\mathcal{E}}(z) + \inf_{y \in \mathcal{D}_h} \|z - y\| \geq \inf_{y \in \mathcal{D}_h} c(\|y\| + \|z\|) - b \geq c\|z\| - b.$$

ii) *Limsup inequality*. Let $z \in \mathcal{E}$. By lemma, \mathcal{D} is weakly closed and $d(z, \mathcal{D}) = \|y - z\|$. By Mosco, there is $y_h \rightarrow y$, $y_h \in \mathcal{D}_h$. Hence,

$$\limsup_{h \rightarrow \infty} d(z, \mathcal{D}_h) \leq \limsup_{h \rightarrow \infty} \|z - y_h\| \leq \|z - y\| = d(z, \mathcal{D}).$$

iii) *Liminf inequality*. Let $z_h \rightharpoonup z$, can take $z_h \in \mathcal{E}$. Let $y_h \in \mathcal{D}_h$ s. t. $\lim_{h \rightarrow \infty} d^2(z_h, \mathcal{D}_h) = \lim_{h \rightarrow \infty} \|y_h - z_h\|^2$. By equi-transversality and Mosco, there is $y \in \mathcal{D}$ s. t. $y_h \rightharpoonup y$. Hence,

$$\liminf_{h \rightarrow \infty} F_h(z_h) = \liminf_{h \rightarrow \infty} \|z_h - y_h\|^2 \geq \|z - y\|^2 \geq d^2(z, \mathcal{D}) = F(z).$$

□

The topology of data convergence

Theorem (Uniform approximation)

Suppose that $\mathcal{D}_h = \{z \in Z : z(x) \in \mathcal{D}_{\text{loc},h} \text{ a. e. in } \Omega\}$, for some sequence of local material data sets $\mathcal{D}_{\text{loc},h} \subset \mathbb{R}_{\text{sym}}^{n \times n} \times \mathbb{R}_{\text{sym}}^{n \times n}$. Let $\mathcal{D} = \{z \in Z : z(x) \in \mathcal{D}_{\text{loc}} \text{ a. e. in } \Omega\}$, where $\mathcal{D}_{\text{loc}} = \{\sigma = \mathbb{C}\epsilon\}$. Assume:

- i) (Fine approximation) There is a sequence $\rho_h \downarrow 0$ such that $d(\xi, \mathcal{D}_{\text{loc},h}) \leq \rho_h, \forall \xi \in \mathcal{D}_{\text{loc}}$.
- ii) (Uniform approximation) There is a sequence $t_h \downarrow 0$ such that $d(\xi, \mathcal{D}_{\text{loc}}) \leq t_h, \forall \xi \in \mathcal{D}_{\text{loc},h}$.

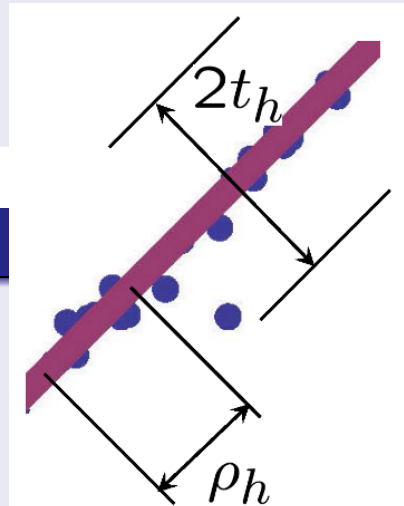
Then, $\mathcal{D} = M\text{-}\lim_{h \rightarrow \infty} \mathcal{D}_h$ in Z .

Proof.

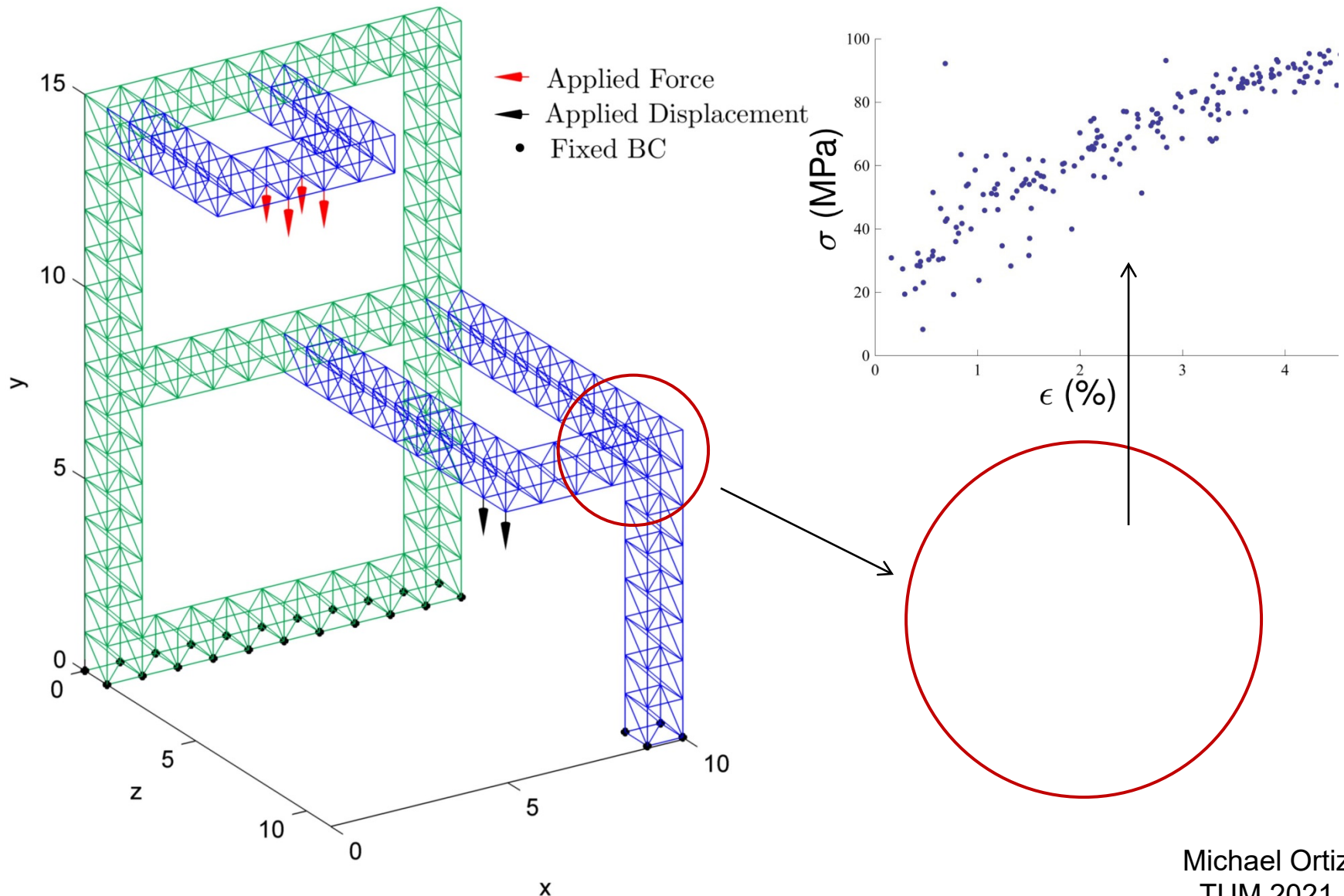
Equi-coercivity from (ii) and coercivity of the limit.

Lower bound from weak closedness of \mathcal{D} and (ii).

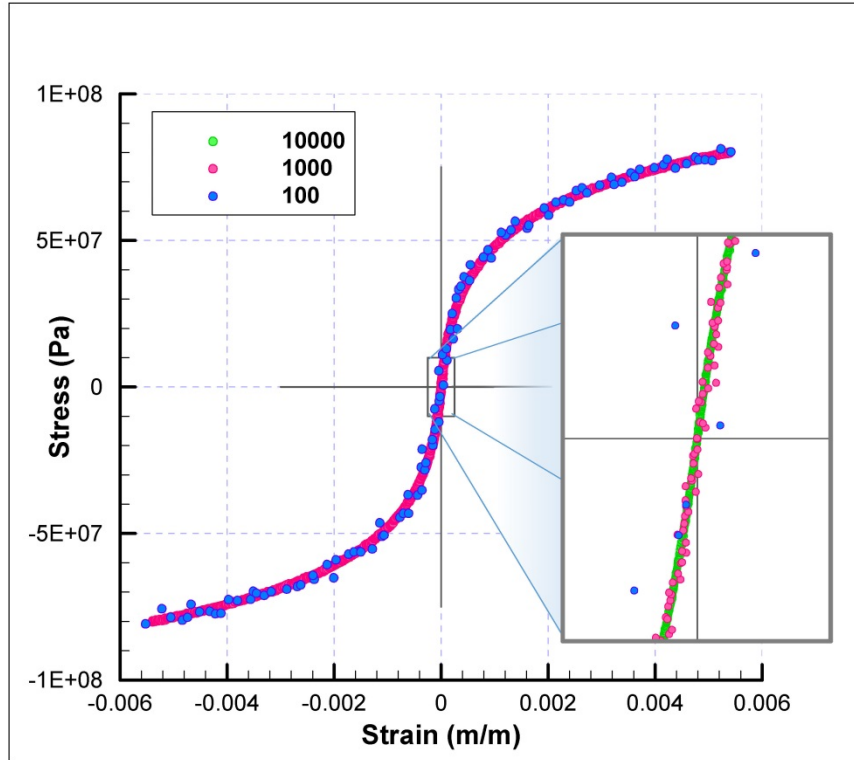
Recovery sequence from (i).



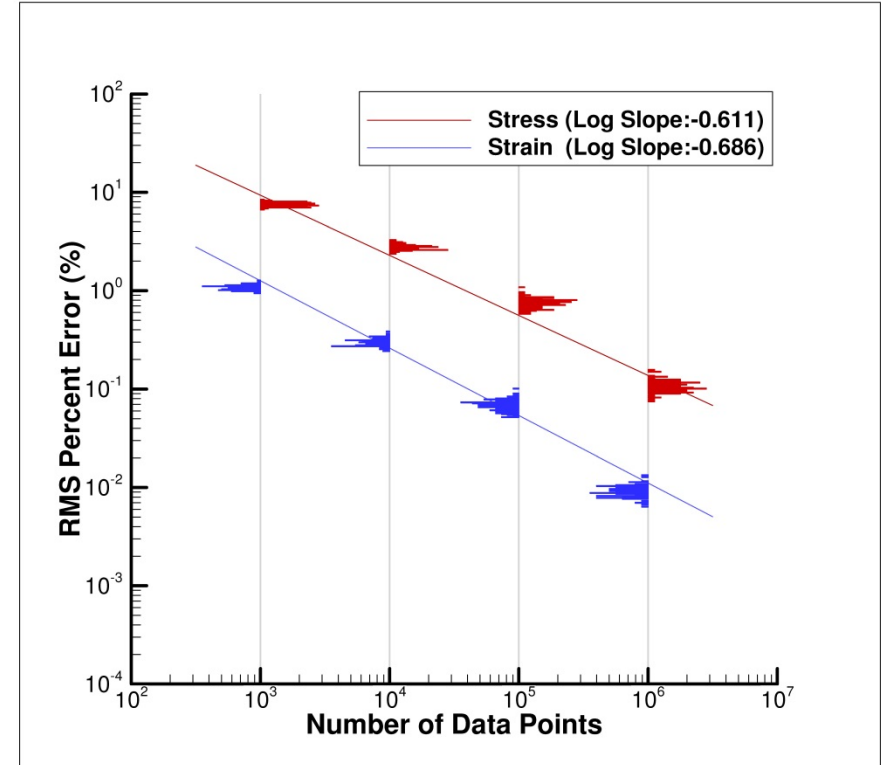
Numerical example: 3D Truss structure



Numerical example: 3D Truss structure

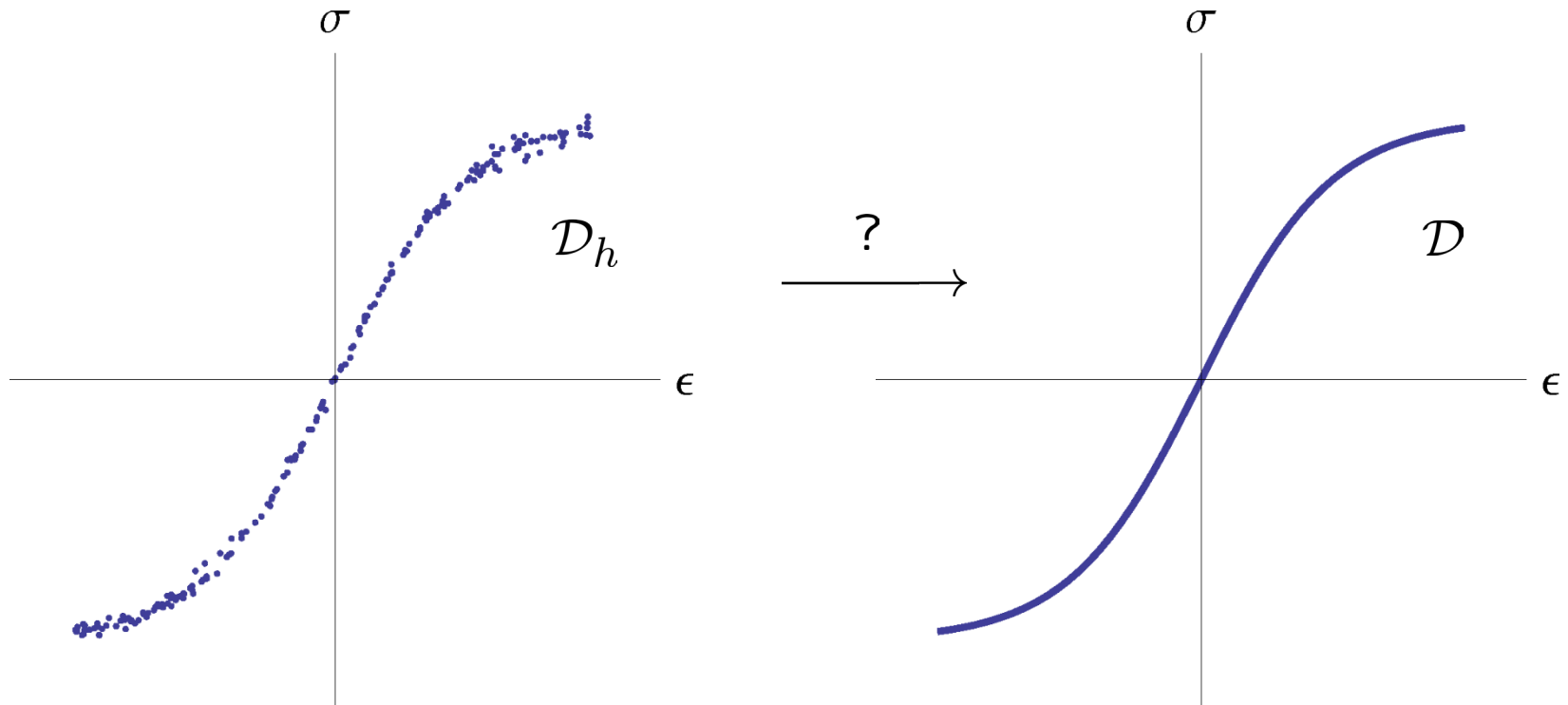


Randomized material-data
sets of increasing size
and decreasing scatter



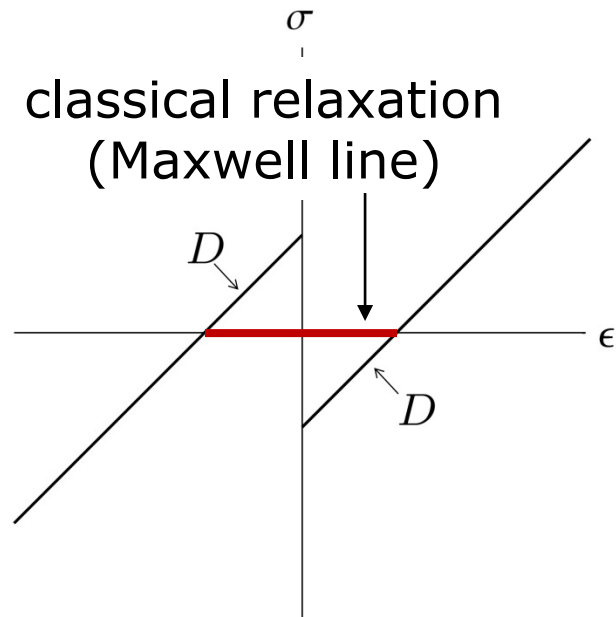
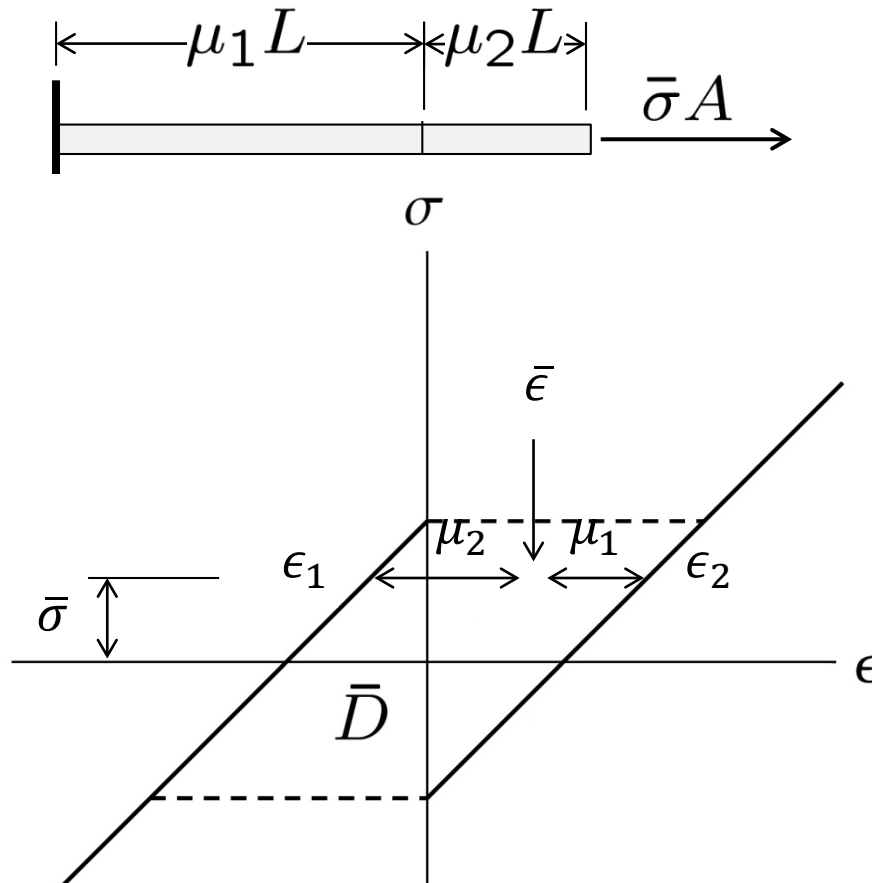
Convergence with
respect to data set
size

The topology of Δ -convergence



- Suppose now that the limiting set is *not weakly closed*
- Infimum of the distance may not be attained: *Relaxation*
- What *topology* describes material data set relaxation?
- What are the *relaxed material data sets*?

Data-Driven elasticity - Relaxation



Conjecture (DD relaxation)

$$D \equiv \{double\ well\} \Rightarrow \{(\bar{\epsilon}, \bar{\sigma})\} = \bar{D}.$$

The topology of Δ -convergence

Henceforth: \mathcal{Z} reflexive separable Banach space; \mathcal{E} weakly-closed subset.

Definition (Δ convergence)

A sequence (y_h, z_h) in $\mathcal{Z} \times \mathcal{Z}$ is said to converge to $(y, z) \in \mathcal{Z} \times \mathcal{Z}$ in the Δ topology, denoted $(y, z) = \Delta\text{-}\lim_{h \rightarrow \infty} (y_h, z_h)$, if $y_h \rightharpoonup y$, $z_h \rightharpoonup z$ and $y_h - z_h \rightarrow y - z$.

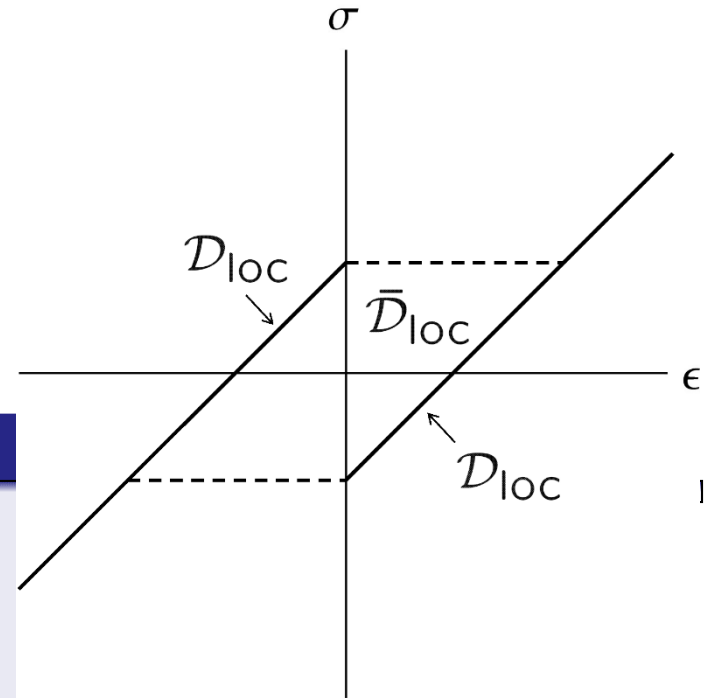
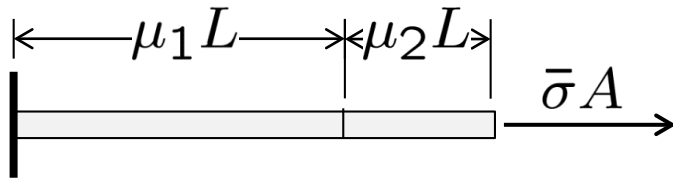
NB: We denote by $\Gamma(\Delta)\text{-}\lim_{h \rightarrow \infty} F_h$ the Γ -limit of sequences (F_h) of functions over $\mathcal{Z} \times \mathcal{Z}$ in the Δ -topology, and by $K(\Delta)\text{-}\lim_{h \rightarrow \infty} \mathcal{A}_h$ the Kuratowski-limit of sequences (\mathcal{A}_h) of subsets of $\mathcal{Z} \times \mathcal{Z}$.

Theorem (One-dimensional bistable material)

Let $\mathcal{Z} = L^2(0, 1) \times L^2(0, 1)$, $\mathcal{E} \subset \mathcal{Z}$ as before, \mathcal{D}_{loc} bistable and $\overline{\mathcal{D}}_{\text{loc}}$ the corresponding flag. Then, $\overline{\mathcal{D}} \times \mathcal{E} = K(\Delta)\text{-}\lim_{h \rightarrow \infty} \mathcal{D} \times \mathcal{E}$.

NB: Can be extended to 3D bistable materials (CMO'2018)

The topology of Δ -convergence



Proof.

Need to show that $\bar{F} = \Gamma(\Delta) - \lim_{h \rightarrow \infty} F_h$,
 $F_h(y, z) = d^2(y, z) + I_{\mathcal{D}}(z) + I_{\mathcal{E}}(z)$ and
 $\bar{F}(y, z) = d^2(y, z) + I_{\bar{\mathcal{D}}}(z) + I_{\mathcal{E}}(z)$.

Main idea: σ_h does not oscillate. Can add arbitrary oscillations in ϵ_h .

Lower bound: Let $(y_h, z_h) \xrightarrow{\Delta} (y, z)$. By strong convergence, have $y_h \sim z_h \sim (\epsilon_h, \sigma_h) \in \mathcal{E} \cap \mathcal{D}$. Then, $\sigma_h \sim \bar{\sigma}$ and $\epsilon_h \rightharpoonup \bar{\epsilon}$, $(\bar{\epsilon}, \bar{\sigma}) \in \bar{\mathcal{D}}$.

Upper bound: By strong convergence, enough to consider $y \sim z \sim (\epsilon, \sigma) \in \bar{\mathcal{D}}$. Then $\sigma = \bar{\sigma}$. Add piecewise-constant oscillations to ϵ to obtain $\epsilon_h \rightharpoonup \epsilon$, with $(\epsilon_h, \bar{\sigma}) \in \mathcal{E} \cap \mathcal{D}$.

Equi-transversality: Follows from $\sigma \sim \bar{\sigma}$, $|\sigma(x) - \mathbb{C}\epsilon(x)| \leq \sigma_0$. □

The topology of Δ -convergence

Connection between convergence of data sets and DD solutions?

Let: $F_h(y, z) = I_{\mathcal{D}_h}(y) + I_{\mathcal{E}}(z) + \|y - z\|^2 = I_{\mathcal{D}_h \times \mathcal{E}}(y, z) + \|y - z\|^2$.

Theorem

Let \mathcal{D} and (\mathcal{D}_h) be subsets of a reflexive separable Banach space \mathcal{Z} , \mathcal{E} a weakly sequentially closed subset of \mathcal{Z} . For $(y, z) \in \mathcal{Z} \times \mathcal{Z}$. Suppose:

- i) (Data convergence) $\mathcal{D} \times \mathcal{E} = K(\Delta) - \lim_{h \rightarrow \infty} (\mathcal{D}_h \times \mathcal{E})$.
- ii) (Equi-transversality) There are constants $c > 0$ and $b \geq 0$ such that, for all $y \in \mathcal{D}_h$ and $z \in \mathcal{E}$, $\|y - z\| \geq c(\|y\| + \|z\|) - b$.

Then:

- a) If $F_h(y_h, z_h) \rightarrow 0$, there exists $z \in \mathcal{D} \cap \mathcal{E}$ such that, up to subsequences, $(z, z) = \Delta - \lim_{h \rightarrow \infty} (y_h, z_h)$.
- b) If $z \in \mathcal{D} \cap \mathcal{E}$, there exist a sequence (y_h, z_h) in $\mathcal{Z} \times \mathcal{Z}$ such that $(z, z) = \Delta - \lim_{h \rightarrow \infty} (y_h, z_h)$ and $F_h(y_h, z_h) \rightarrow 0$.

The topology of Δ -convergence

Proof.

a) Since $F_h(y_h, z_h) \rightarrow 0$, it follows that $y_h \in \mathcal{D}_h$, $z_h \in \mathcal{E}$, $\|y_h - z_h\| \rightarrow 0$. By (ii), (y_h) and (z_h) are bounded. Therefore, there are $y \in \mathcal{Z}$ and $z \in \mathcal{Z}$ such that $y_h \rightharpoonup y$ and $z_h \rightharpoonup z$ up to subsequences. By the weak closedness of \mathcal{E} , $z \in \mathcal{E}$. By weak lower-semicontinuity, $y = z$ and $(y, z) = \Delta\text{-}\lim_{h \rightarrow \infty} (y_h, z_h)$. By (i), $y \in \mathcal{D}$.

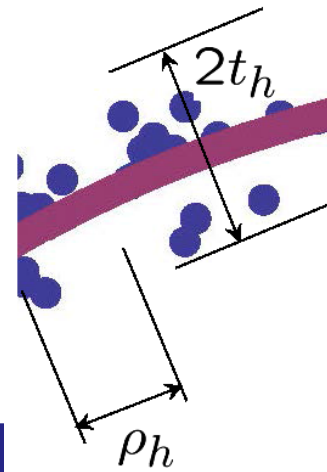
b) Let $z \in \mathcal{D} \cap \mathcal{E}$. Then, by (i) there exists a sequence $(y_h, z_h) \in \mathcal{D}_h \times \mathcal{E}$ with limit $(z, z) = \Delta\text{-}\lim_{h \rightarrow \infty} (y_h, z_h)$. In particular, we have $y_h - z_h \rightarrow z - z = 0$. Hence, by continuity of the norm,

$$\lim_{h \rightarrow \infty} F_h(y_h, z_h) = \lim_{h \rightarrow \infty} \left(I_{\mathcal{D}_h}(y_h) + I_{\mathcal{E}}(z_h) + \|y_h - z_h\|^2 \right) = 0,$$

as required. □

The topology of Δ -convergence

Example of Delta-convergence of sets



Theorem (Uniform set convergence)

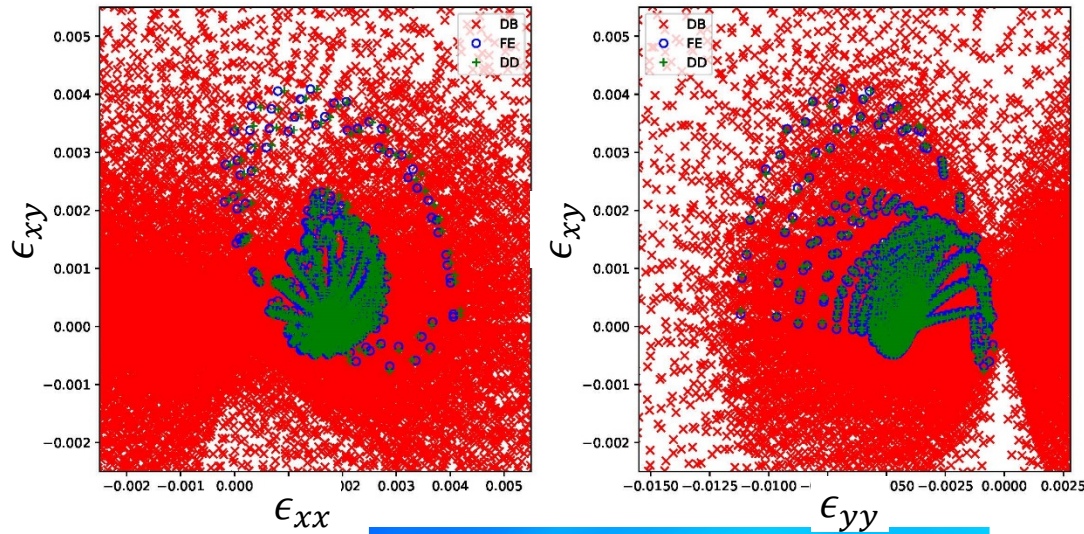
Let $\mathcal{E} \subset \mathcal{Z}$ be weakly sequentially closed, $\mathcal{D}, \overline{\mathcal{D}} \subset \mathcal{Z}$. Suppose:

- i) (Data convergence) $\overline{\mathcal{D}} \times \mathcal{E} = K(\Delta) - \lim_{h \rightarrow \infty} (\mathcal{D} \times \mathcal{E})$.
- ii) (Fine approximation) There is a sequence $\rho_h \downarrow 0$ such that $d(\xi, \mathcal{D}_{\text{loc},h}) < \rho_h, \forall \xi \in \mathcal{D}_{\text{loc}}$.
- iii) (Uniform approximation) There is a sequence $t_h \downarrow 0$ such that $d(\xi, \mathcal{D}_{\text{loc}}) < t_h, \forall \xi \in \mathcal{D}_{\text{loc},h}$.
- iv) (Transversality) There are constants $c > 0$ and $b \geq 0$ such that, for all $y \in \mathcal{D}$ and $z \in \mathcal{E}$, $\|y - z\| \geq c(\|y\| + \|z\|) - b$.

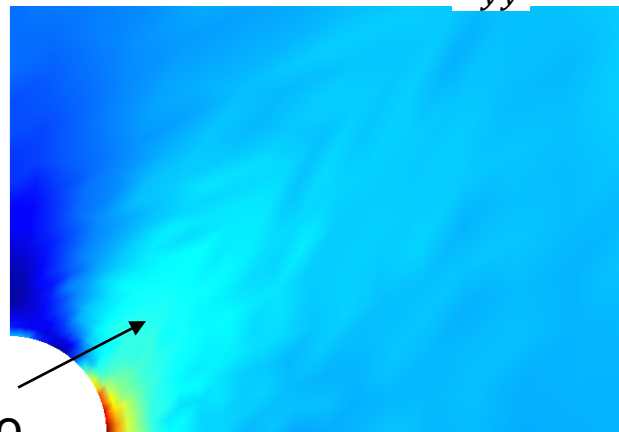
Then, $\overline{\mathcal{D}} \times \mathcal{E} = K(\Delta) - \lim_{h \rightarrow \infty} (\mathcal{D}_h \times \mathcal{E})$.

DD relaxation – Finite elements

strain coverage



Gauss-point to
Gauss-point
oscillations!



Stress (DD)

2.08e+08 63e+09



Stress (FE)

2.28e+08 .8e+09



Nonlinear elasticity – set-up

Phase space: For $p \in (1, \infty)$, $\frac{1}{p} + \frac{1}{q} = 1$

$$Z = X_{p,q} := \{(F, P) \in L^p(\Omega; \mathbb{R}^{n \times n}) \times L^q(\Omega; \mathbb{R}^{n \times n})\},$$

Constraint set: \mathcal{E}_0 consists of $(F, P) \in X_{p,q}$ s.t. $\exists u \in W^{1,p}$

$$F = Du \quad \text{in } \Omega, \quad u = g_D \quad \text{on } \Gamma_D,$$

$$\operatorname{div} P + f = 0 \quad \text{in } \Omega, \quad P\nu = h_N \quad \text{on } \Gamma_N.$$

$$\mathcal{E} := \{(F, P) \in \mathcal{E}_0 : FP^T \text{ symmetric a.e.}\} \quad (\text{angular momentum})$$

Local data sets:

$$\mathcal{D} = \{(F, P) \in X_{p,q} : (F(x), P(x)) \in \mathcal{D}_{\text{loc}} \text{ a.e.}\}.$$

Deviation function measures distance from the data set

$$\psi_{\mathcal{D}_{\text{loc}}}(F, P) := \inf \left\{ \frac{1}{p} |F - F'|^p + \frac{1}{q} |P - P'|^q : (F', P') \in \mathcal{D}_{\text{loc}} \right\}$$

$$J(F, P) = \int_{\Omega} \psi_{\mathcal{D}_{\text{loc}}}(F, P) \, dx$$

Goal: minimize J in \mathcal{E}

$$\psi_{\mathcal{D}_{\text{loc}}}(F, P) := \inf \left\{ \frac{1}{p} |F - F'|^p + \frac{1}{q} |P - P'|^q : (F', P') \in \mathcal{D}_{\text{loc}} \right\}$$

$$J(F, P) = \int_{\Omega} \psi_{\mathcal{D}_{\text{loc}}}(F, P) dx, \quad \mathcal{E} \text{ equilibrium set}$$

Theorem

Assume $\inf_{\mathcal{E}} J = 0$. If \mathcal{D}_{loc} is (p, q) coercive and *div-curl closed* then the infimum is attained by $(F, P) \in \mathcal{E} \cap \mathcal{D}$.

(p, q) -coercive:

$$\exists c > 0 \quad \forall (F, P) \in \mathcal{D}_{\text{loc}} \quad F \cdot P \geq \frac{1}{c} |F|^p + \frac{1}{c} |P|^q - C$$

(p, q) *div-curl closed*: $(F_k, P_k) \rightharpoonup (F_*, P_*)$, $(F_k, P_k) \in \mathcal{D}_{\text{loc}}$ a.e.,
 $\text{curl } F_k$ compact in $W^{-1,p}$, $\text{div } P_k$ compact in $W^{-1,q}$
 $\implies (F_*, P_*) \in \mathcal{D}_{\text{loc}}$ a.e.

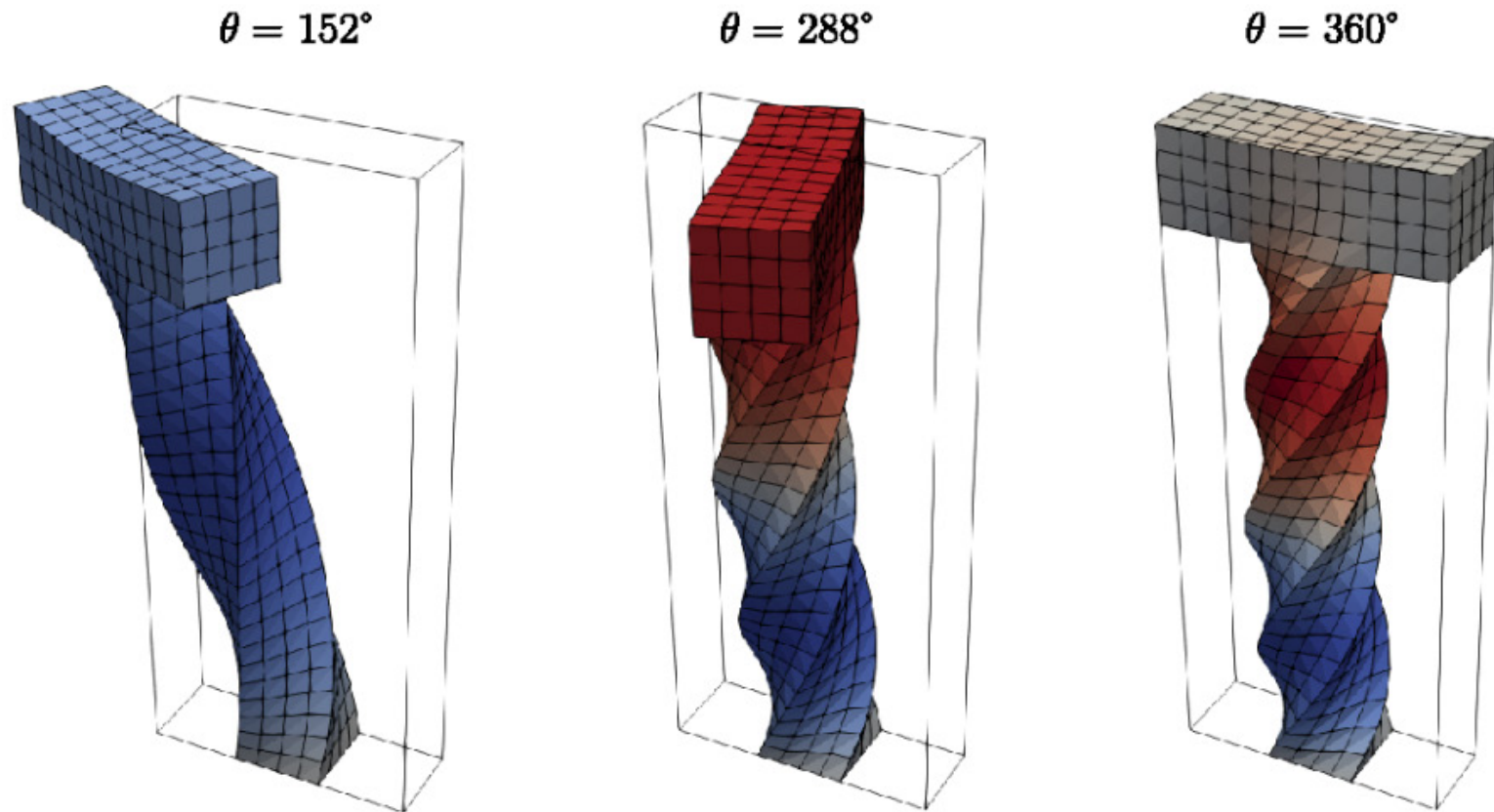
There are interesting *examples* for \mathcal{D}_{loc} of the form

$$\{(F, DW(F)) : F \in \mathbb{R}^{n \times n}\}$$

with $W : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$ which satisfies $\min W = W(\text{Id})$

and $W(QF) = W(F)$ for all $Q \in SO(n)$.

DD finite elasticity - Numerics



Concluding remarks

- *Model-Free Data-Driven computing: The data, all the data, nothing but the data!*
- New class of variational problems in phase space
- New natural notion of convergence of data sets and relaxation (different from relaxation of the energy)
- Connections with compensated compactness, A-quasiconvexity, G-closure in homogenization
- Natural connections with div-curl quasiconvexity, quasimonotonicity (K. Zhang), polymonotonicity
- *Data-driven computing is likely to be a growth area in an increasingly data-rich world and to change the way in which data is mined, stored, exchanged, disseminated and utilized in science and in industry!*

Concluding remarks

Thank you!