

Multiscale Modeling of Energetic Materials

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with: E. Gurses, J. Rimoli,

New Frontiers in the Mathematics of Solids
Multiscale Models in Solid Mechanics

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High-Explosives Detonation Sensitivity

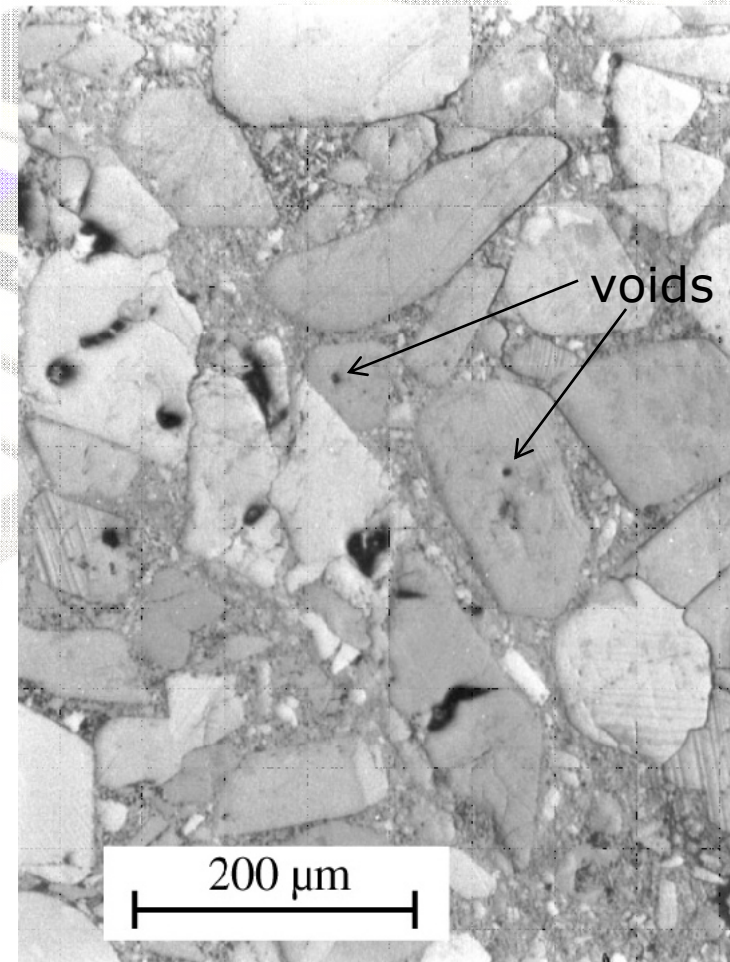


- Detonation sensitivity:
Ease with which an explosive can be detonated
- What factors determine detonation sensitivity?
 - *Pressure*
 - *Temperature*
 - *Density*
 - *Grain size*
 - *Composition...*

Detonation of
high-explosive
(RDX, PETN, HMX)

High-Explosives - Initiation

- In high explosives (HE) localized hot spots cause detonation initiation
- The hot spots are often assumed to arise at extended crystal defects such as voids
- Shock-induced void collapse is often modeled at single-crystal level using hydrocodes or continuum (mean-field) single-crystal plasticity

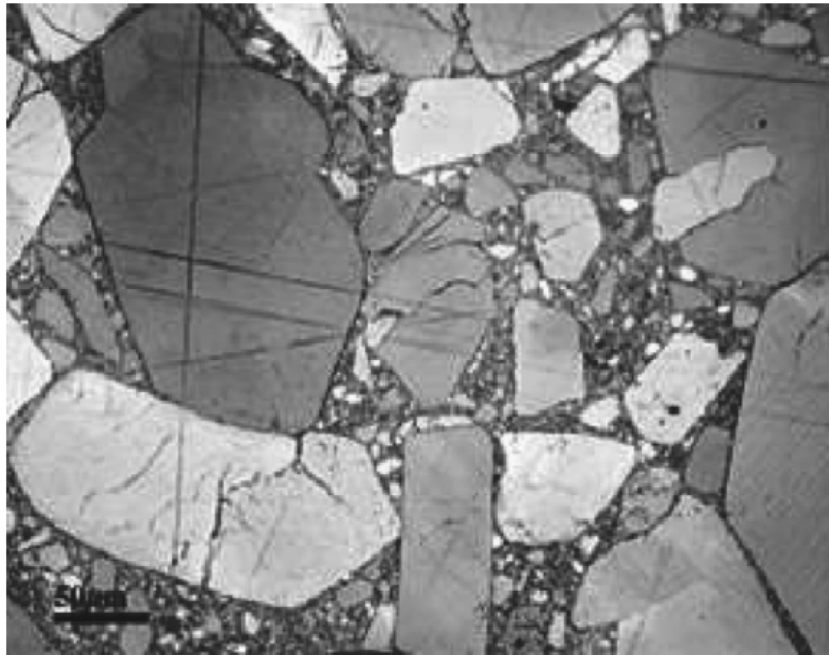


H. Tan, iMechanica, 2008

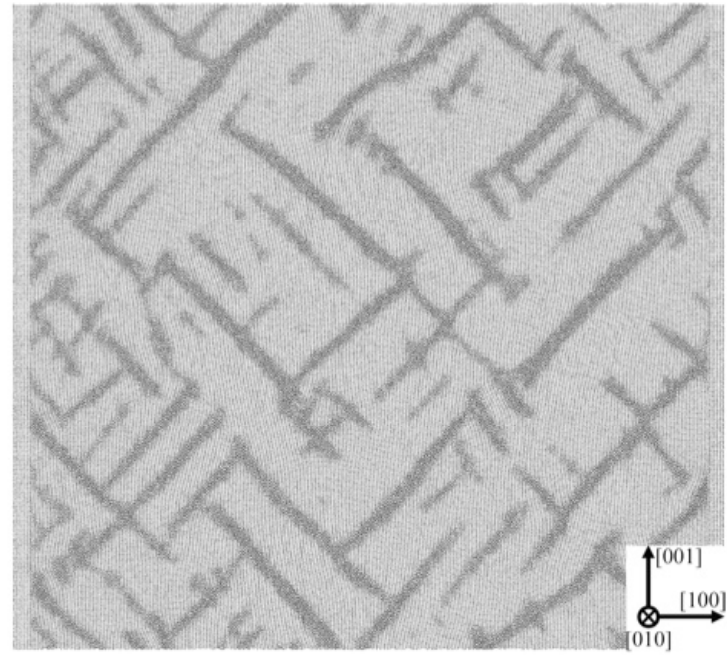


High-Explosives - Initiation

- But: Hot-spots can be nucleated homogeneously due to **heterogeneous** plastic deformation (slip line formation) and stress risers such as triple points in the polycrystalline structure



PBX 9501 (C.B. Skidmore, LANL)

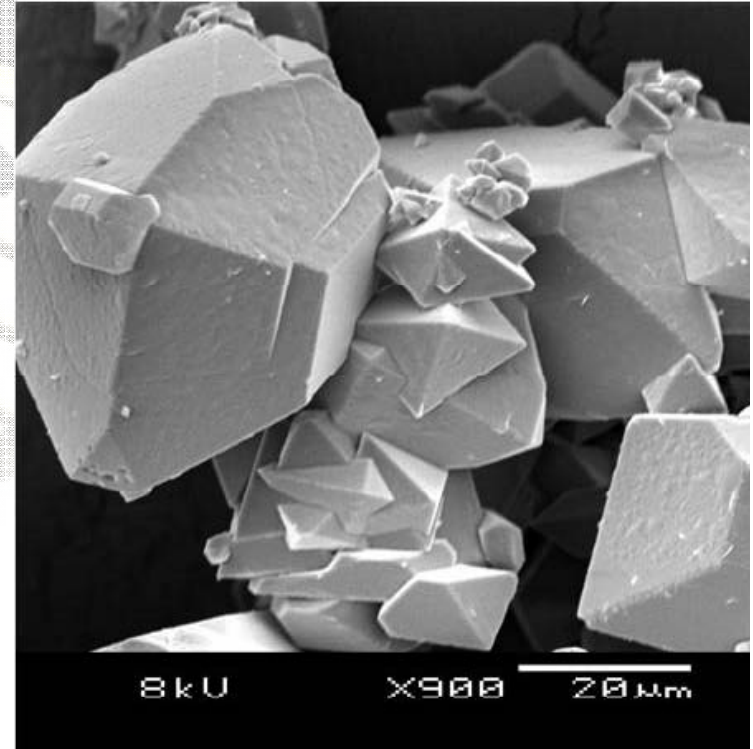


Tommy Sewell (2008)



High-Explosives - Initiation

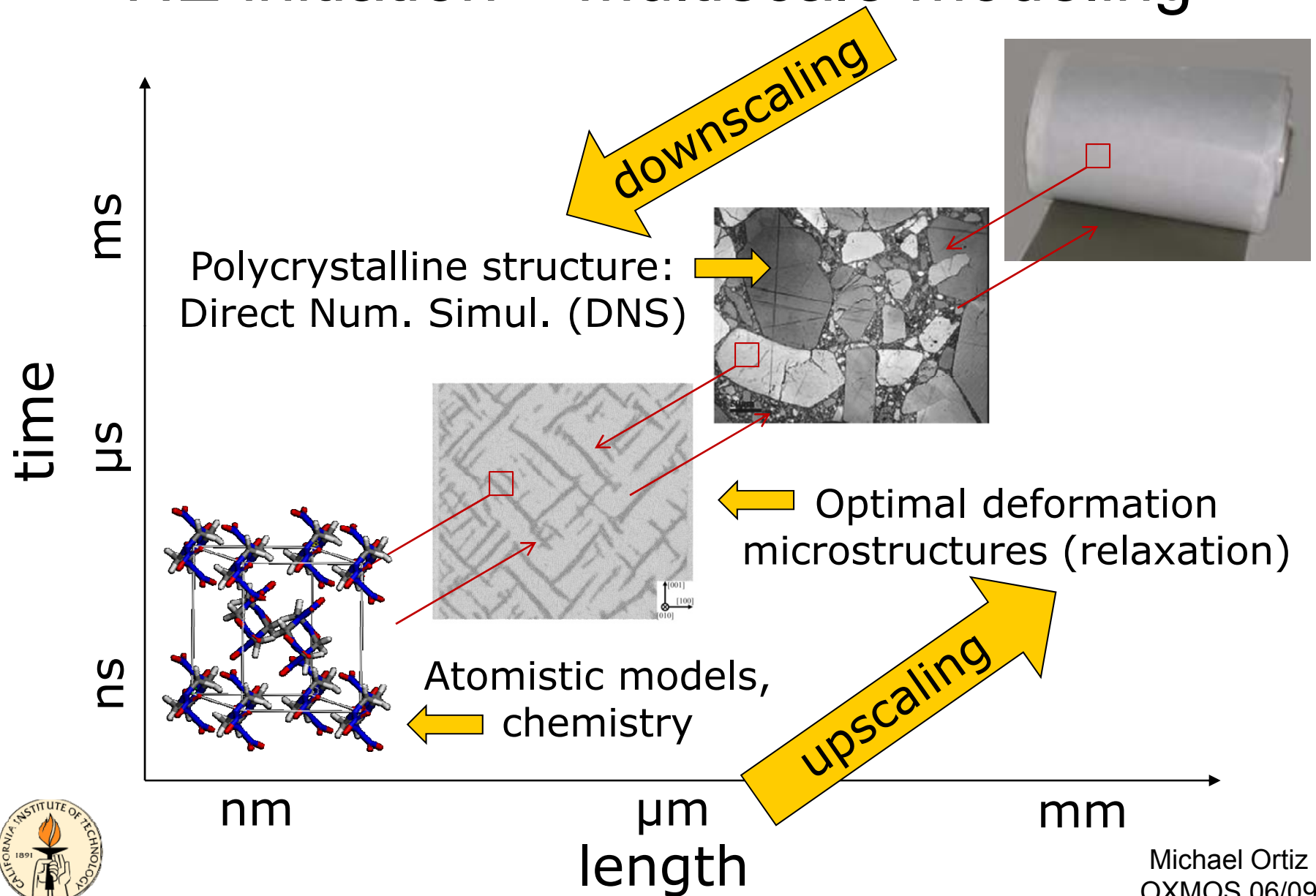
- Can hot spots arise as a result of localized plastic deformation?
- Can small-scale details of the deformation pattern (partially) explain detonation sensitivity?
- Need to predict deformation microstructures, extreme events! (not just average behavior)



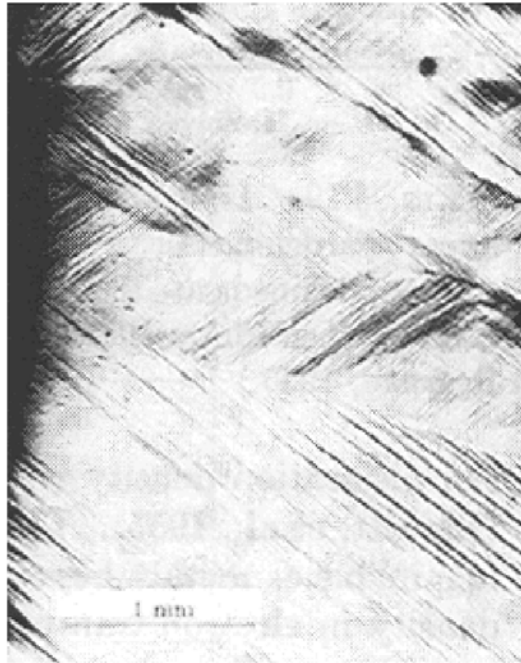
SEM image of RDX
(Kline *et al.*, 2003)



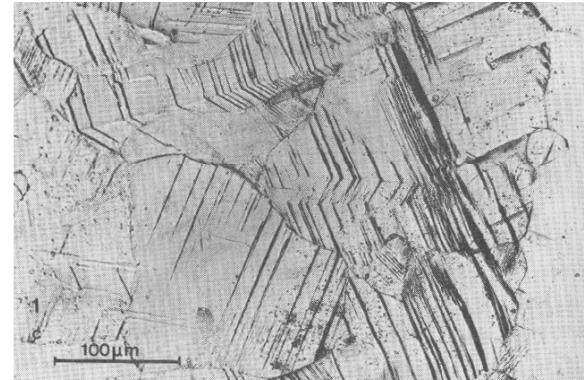
HE initiation – Multiscale modeling



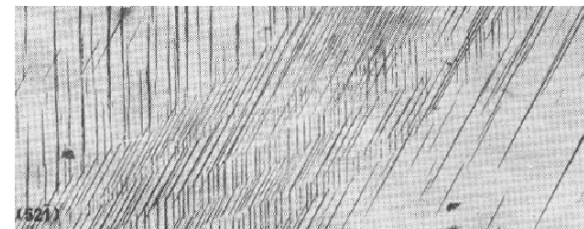
Latent hardening & heterogeneous slip



(Saimoto, 1963)



(Ramussen and Pedersen, 1980)



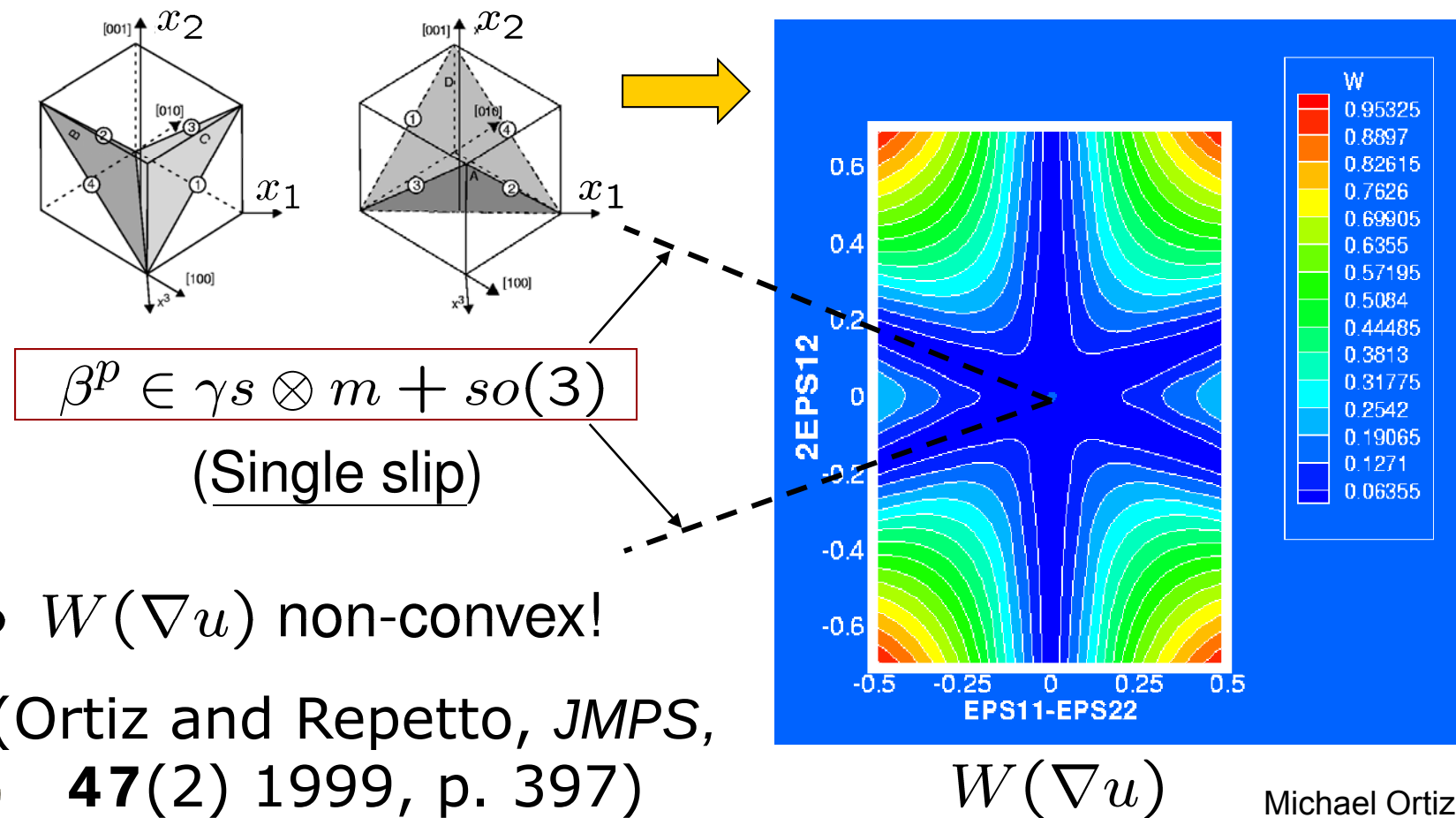
(Jin and Winter, 1984)

- **Latent hardening:** *“These results prove the reality of latent-hardening, in the sense that the slip lines of one system experience difficulty in breaking through the active slip lines of the other one”* (Piercy, G. R., Cahn, R. W., and Cottrell, A. H., *Acta Metallurgica*, **3** (1955) 331-338).



Crystal plasticity – Non-convexity

- Example: FCC crystal deforming on $(1\bar{1}0)$ -plane

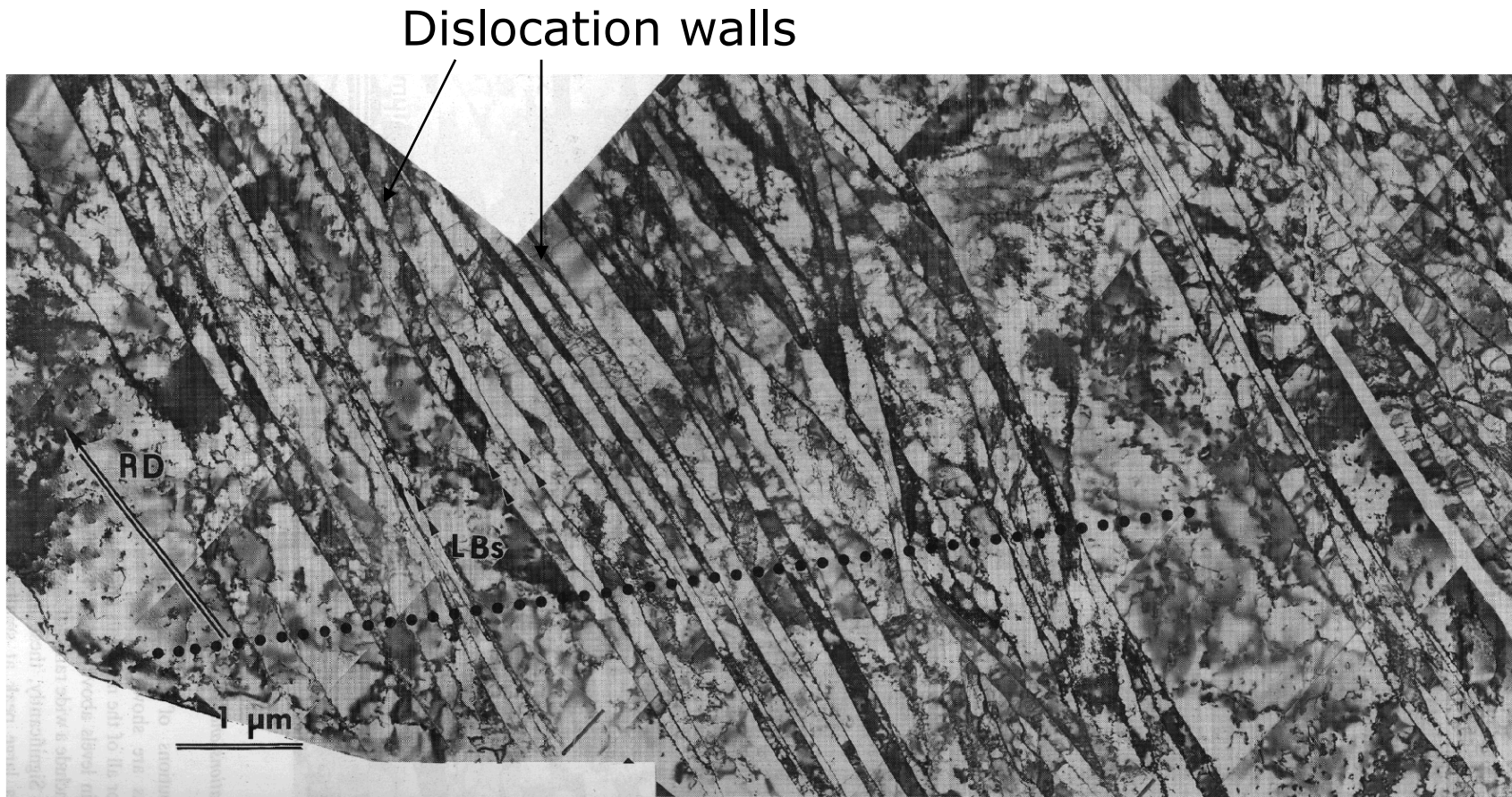


- $W(\nabla u)$ non-convex!

(Ortiz and Repetto, *JMPS*,
47(2) 1999, p. 397)



Subgrain dislocation structures



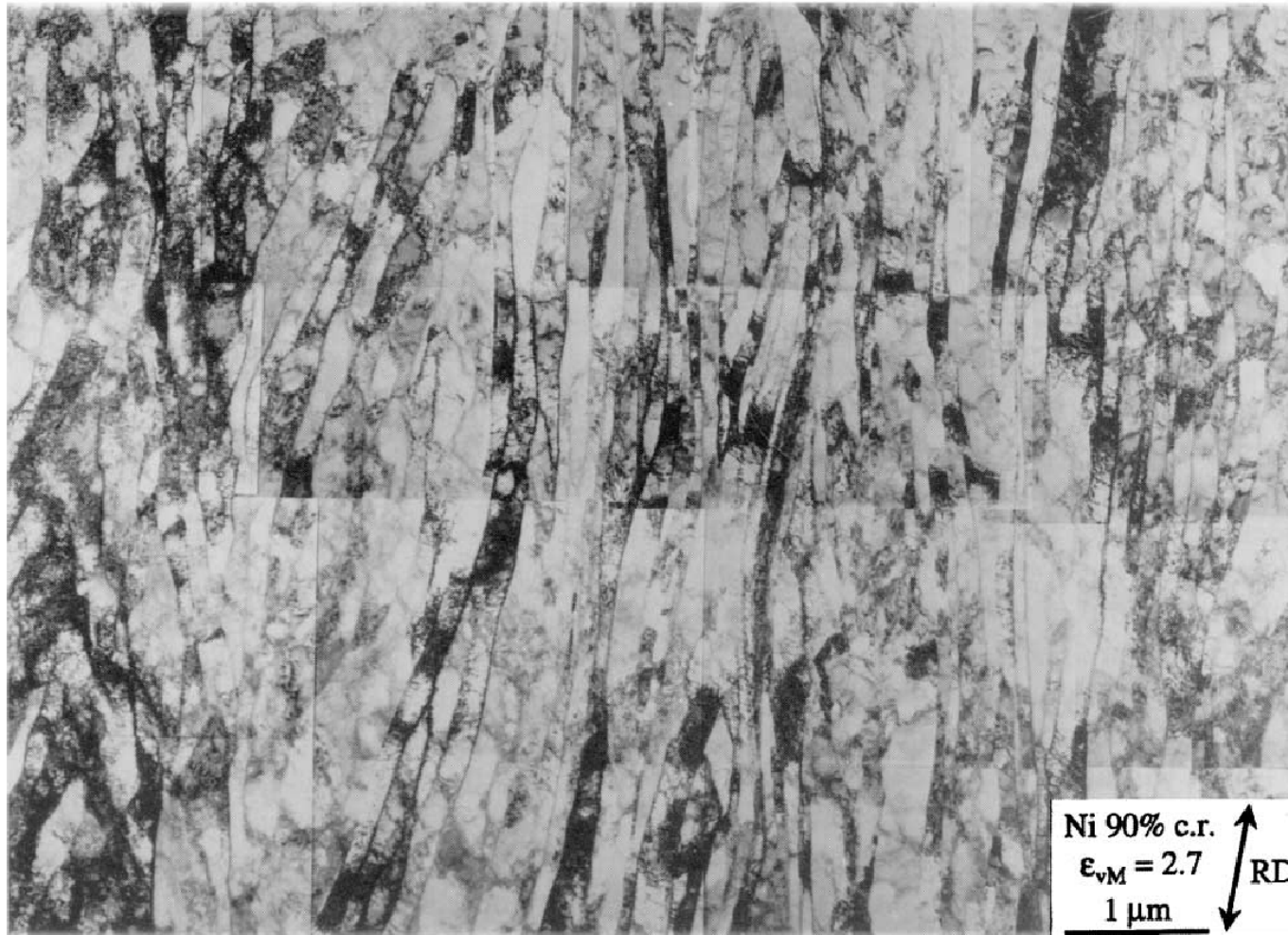
Lamellar dislocation structure in 90 % cold-rolled Ta

(DA Hughes and N Hansen, Acta Materialia,
44 (1) 1997, pp. 105-112)



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Subgrain dislocation structures

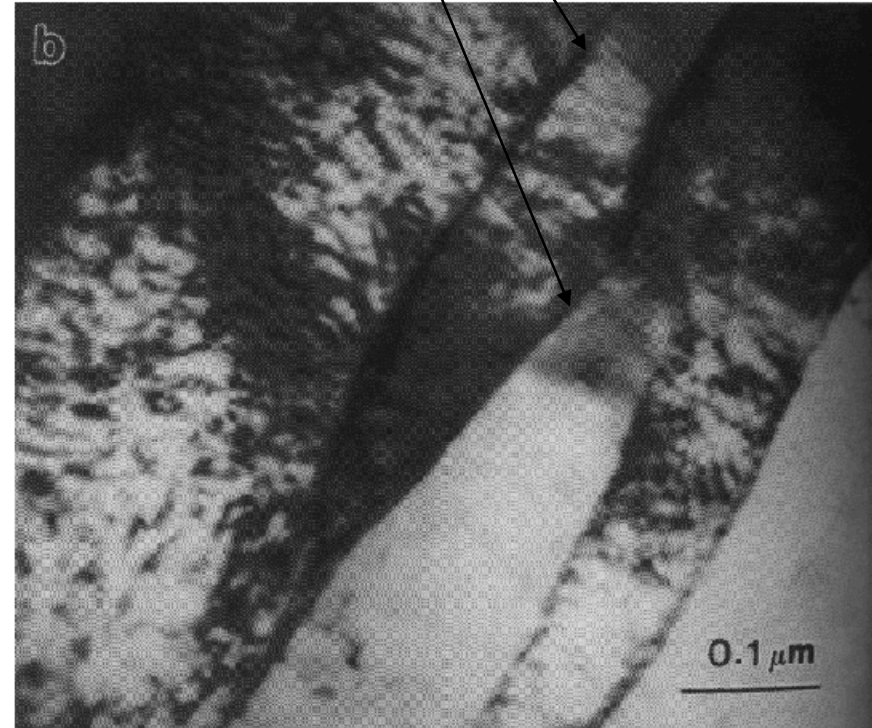
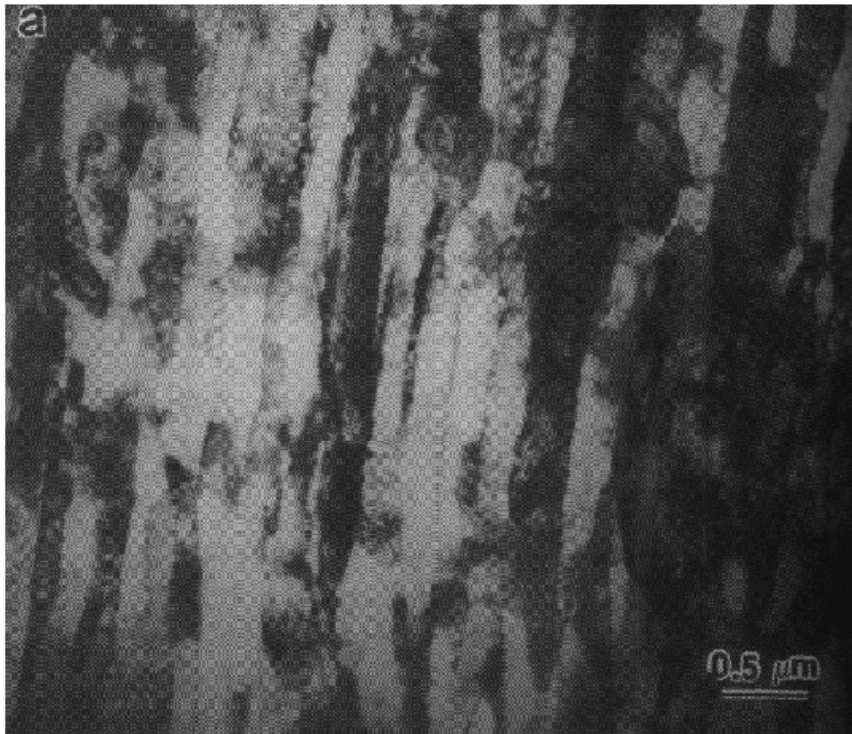


Pure nickel cold rolled to 90 %
Hansen *et al.* Mat. Sci. Engin. A317 (2001)

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Subgrain dislocation structures

Dislocation walls



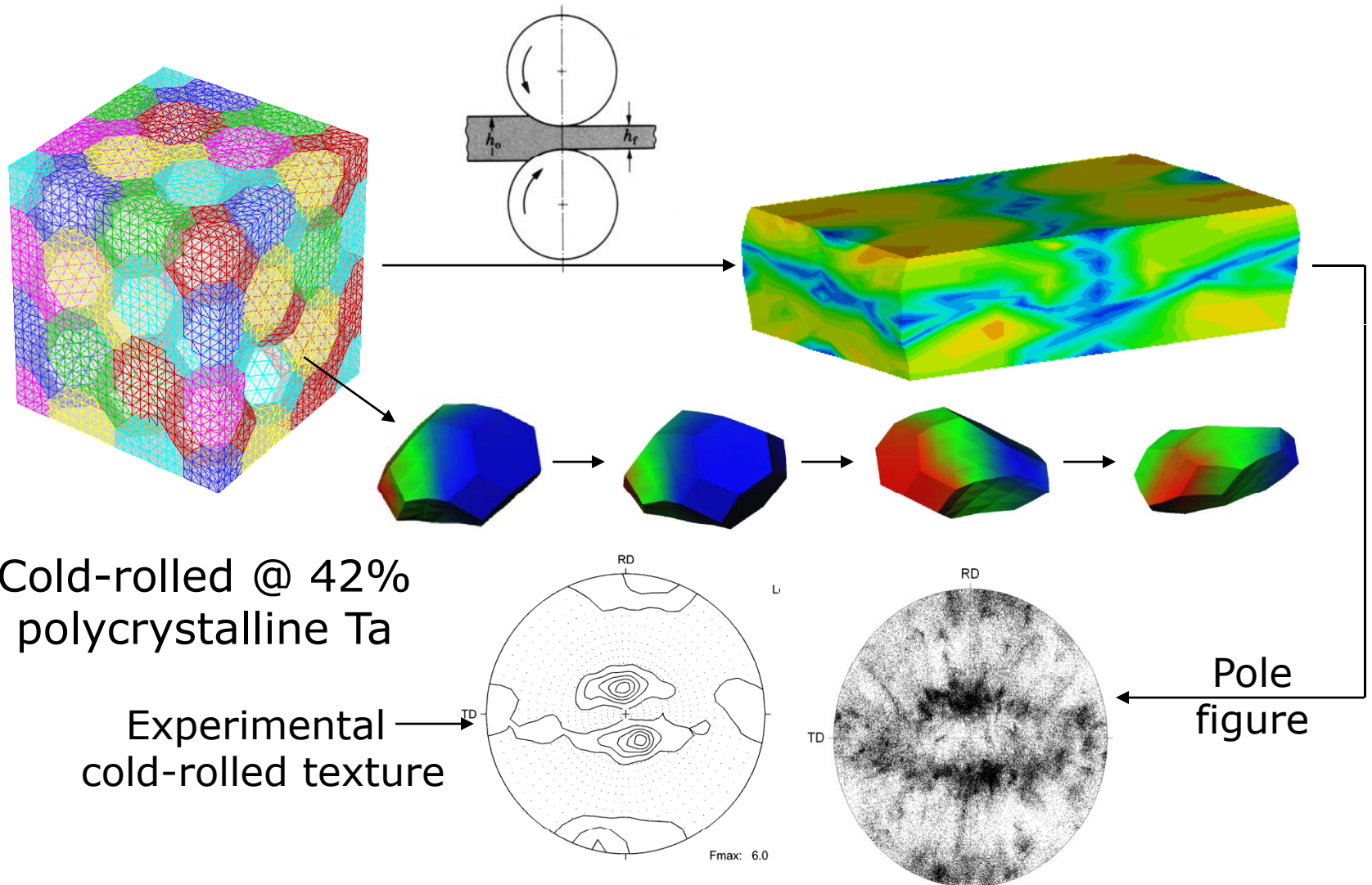
Lamellar structures in shocked Ta

(MA Meyers et al., Metall. Mater. Trans.,
26 (10) 1995, pp. 2493-2501)



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Polycrystals – Limitations of DNS

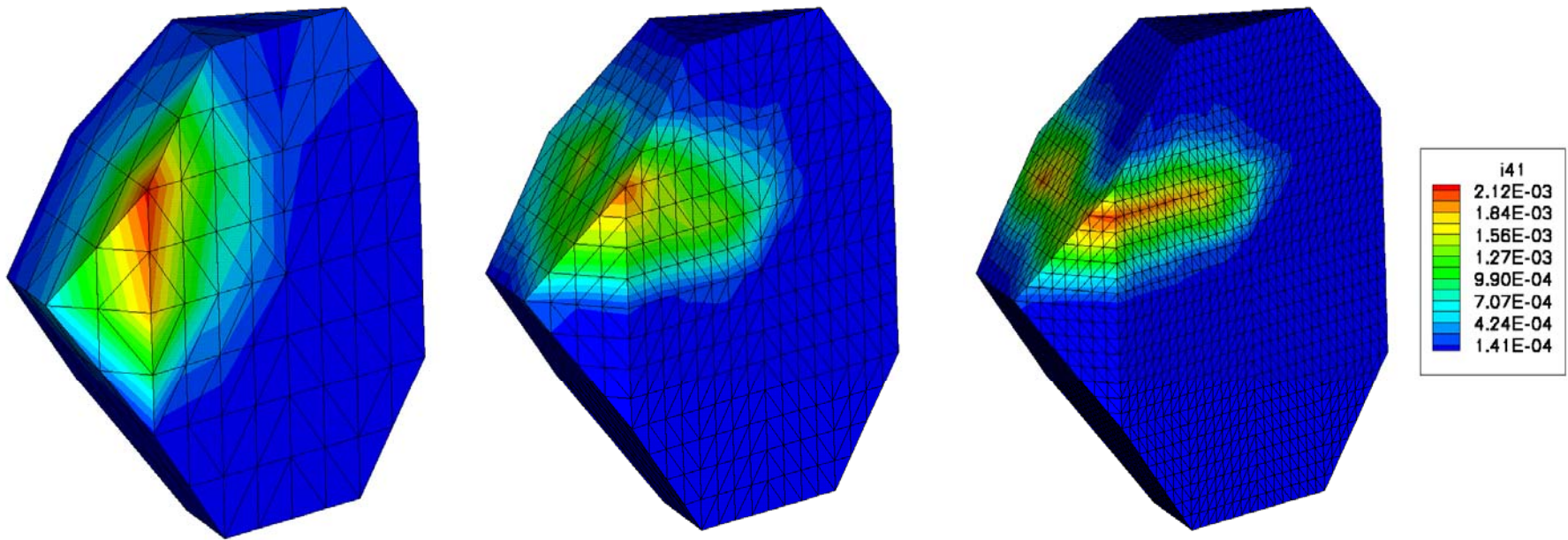


(Zhao, Z. *et al.*, *Acta Mater.*, **55** (2007) 2361-2373)

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Polycrystals – Limitations of DNS

Convergence of DNS of coarse-grained polycrystals:



Coarse mesh
192 elmts/grain

Intermediate mesh
1536 elmts/grain

Fine mesh
12288 el/grain



Cold-rolled @ 42% polycrystalline Ta
(Zhao, Z. *et al.*, *Acta Mater.*, **55** (2007) 2361-2373)

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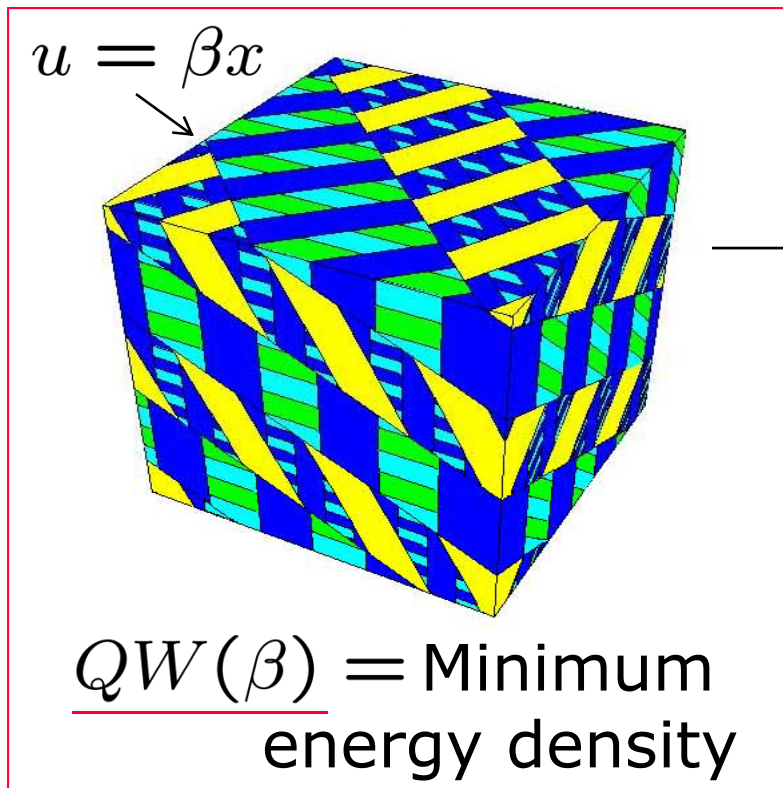
Subgrain dislocation structures

- Strong latent hardening and geometrical softening give rise to subgrain dislocation microstructures almost universally...
- Subgrain dislocation structures beat uniform multiple slip in general, soften the macroscopic response of the crystal, lead to scaling behavior
- Microstructures are much too fine to be resolved numerically by direct numerical simulation
- How to build microstructure into finite element calculations? → Multiscale analysis!

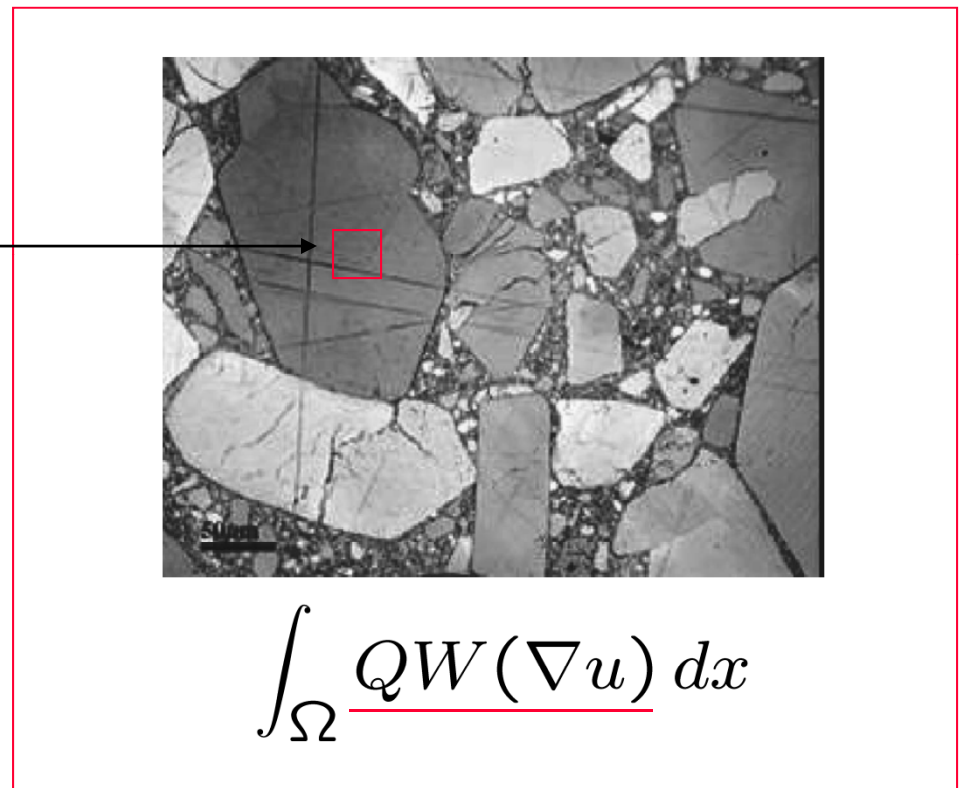


Separation of scales - Relaxation

- $W(Du) \equiv$ Unrelaxed energy density (non-convex)



Relaxation



Relaxed problem



Separation of scales - Relaxation

- Relaxation yields the softest possible macroscopic behavior that can be attained by the formation of microstructure
- All microstructures are accounted for by the relaxed problem (no physics lost)
- Optimal microstructures can be reconstructed from the solution of the relaxed problem (no loss of information)
- Important for HE initiation: Average response is not enough, need to know extremes of deformation (Hot spots!)

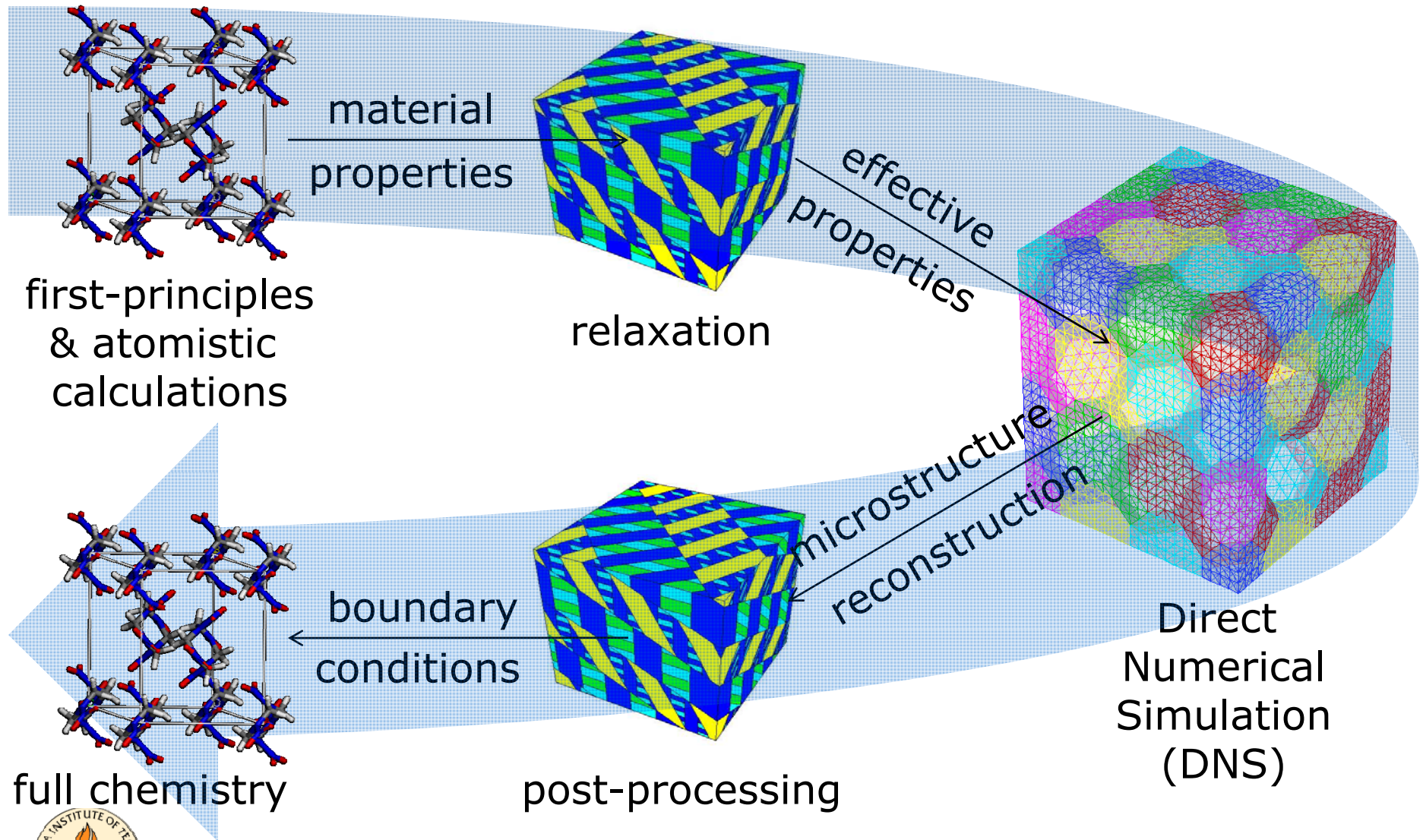


Relaxation – Fast Multiscale Models

- Fast Multiscale Models: Use explicitly relaxed constitutive relation (when available) to represent sub-grid behavior (at element level)
- Much faster than concurrent multiscale calculations (on-the-fly generation of sub-grid microstructures, e.g., by sequential lamination)
- Elements equipped with optimal microstructures, exhibit optimal effective behavior
- Convergence of approximations in the sense of Gamma convergence (e.g., Conti, S., Hauret, P. and Ortiz, M., *SIAM Multiscale Model. Simul.*, **6** (2007) 135-157)



Relaxation – Fast Multiscale Models

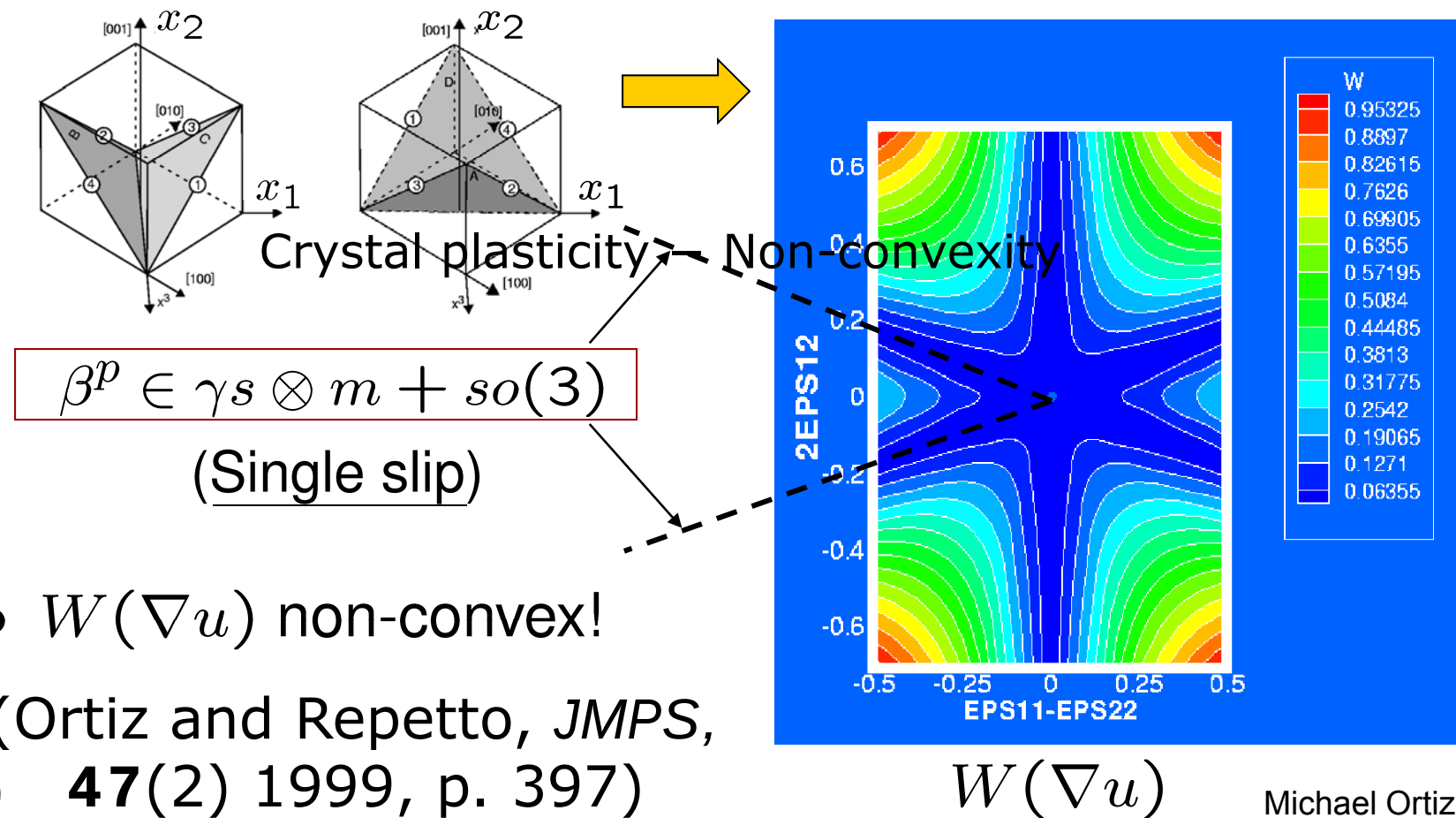


FMM scheme for polycrystalline HE

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Application to crystal plasticity

- Example: FCC crystal deforming on $(1\bar{1}0)$ -plane



- $W(\nabla u)$ non-convex!

(Ortiz and Repetto, *JMPS*,
47(2) 1999, p. 397)



Crystal plasticity – Relaxation

- Let: $U(\Omega) = \{u \in BD(\Omega, \mathbb{R}^3) : \operatorname{div} u \in L^2(\Omega)\}$
- Regression function: $W^\infty(\beta) = \lim_{t \rightarrow \infty} \frac{1}{t} W^{**}(t\beta)$

Theorem (Conti and Ortiz, ARMA '05) *Suppose that the set of slip systems is complete. Then, the relaxation of $I(u)$ with respect to the strong L^1 topology is: $J(u) =$*

$$\begin{cases} \int_{\Omega} W^{**}(\epsilon(u)) dx + \int_{\Omega} W^\infty \left(\frac{E_s u}{|E_s u|} \right) d|E_s u|, & \text{if } u \in U(\Omega) \\ +\infty, & \text{otherwise.} \end{cases}$$



Crystal plasticity – Relaxation

- Proof: Match upper & lower bounds, $W^{\text{qc}} = W^{**}$.
- Lower bound: $J(u)$ convex functional of measure Eu , $J(u) \leq I(u)$.

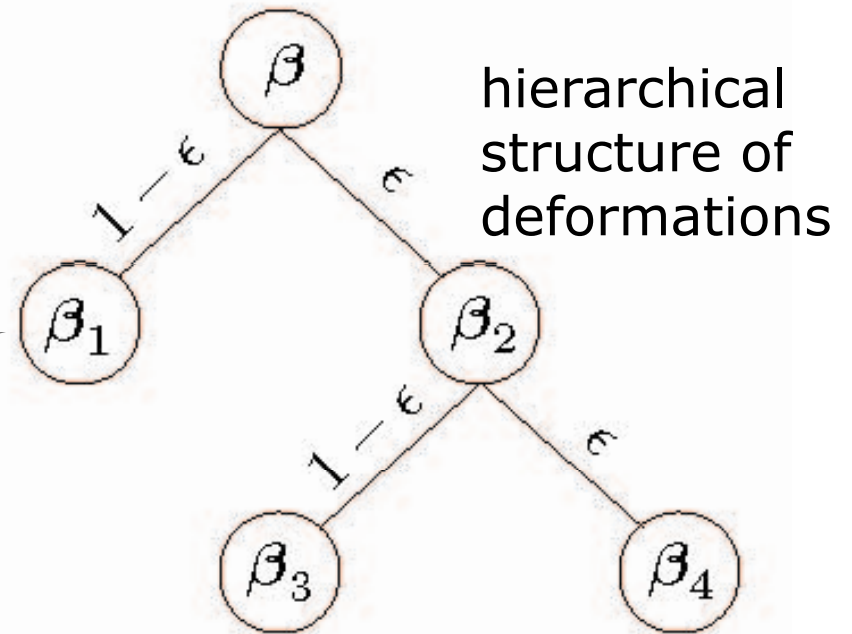
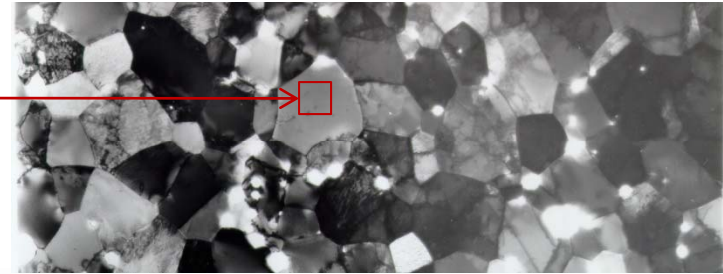
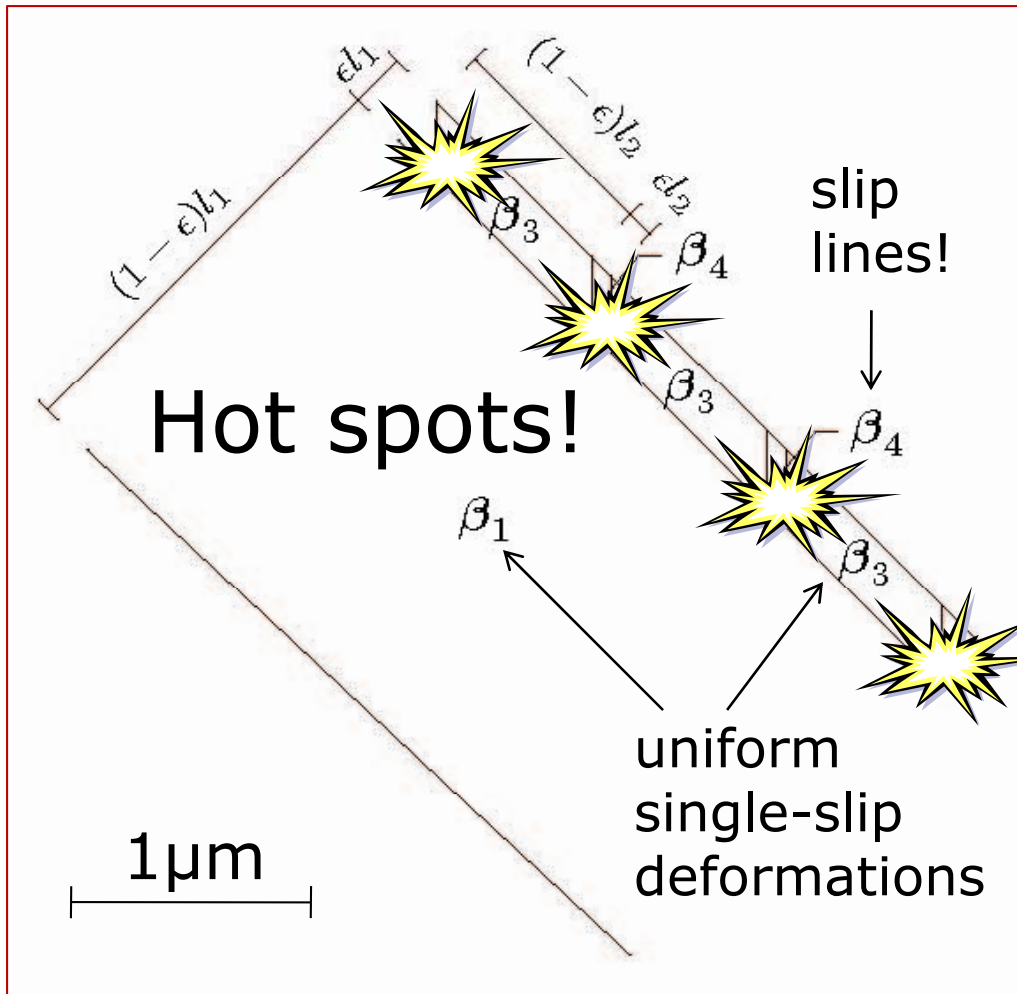
Lemma *Let $\mathcal{S}$ be a complete set of slip systems. For any $\beta \in \mathbb{R}^{3 \times 3}$ and any $\epsilon > 0$ there is a laminate ν (of finite order) such that*

$$\langle \nu, \text{Id} \rangle = \beta \quad \text{and} \quad \langle \nu, W \rangle \leq W^{**}(\beta) + \epsilon.$$

- Some of the deformations in the laminate may become unbounded as $\epsilon \rightarrow 0$ and become slip lines in the limit.



Crystal plasticity – Relaxation

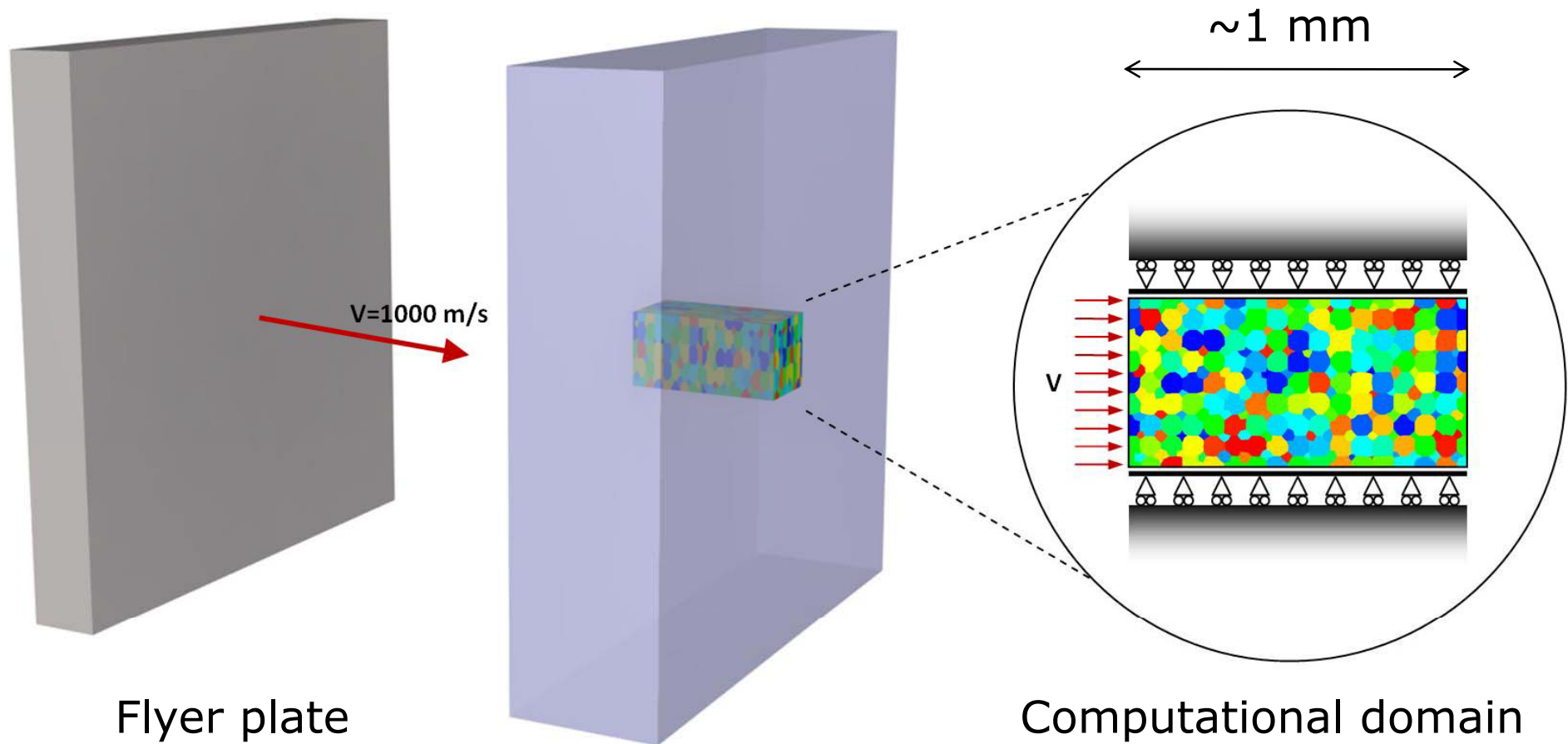


Optimal microstructure construction in double slip

(Conti, S. and Ortiz, M., *Arch. Rat. Mech. Anal.*,
176 (2005) 103-147)

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Fast Multiscale Models – HE detonation



Flyer plate

HE target plate

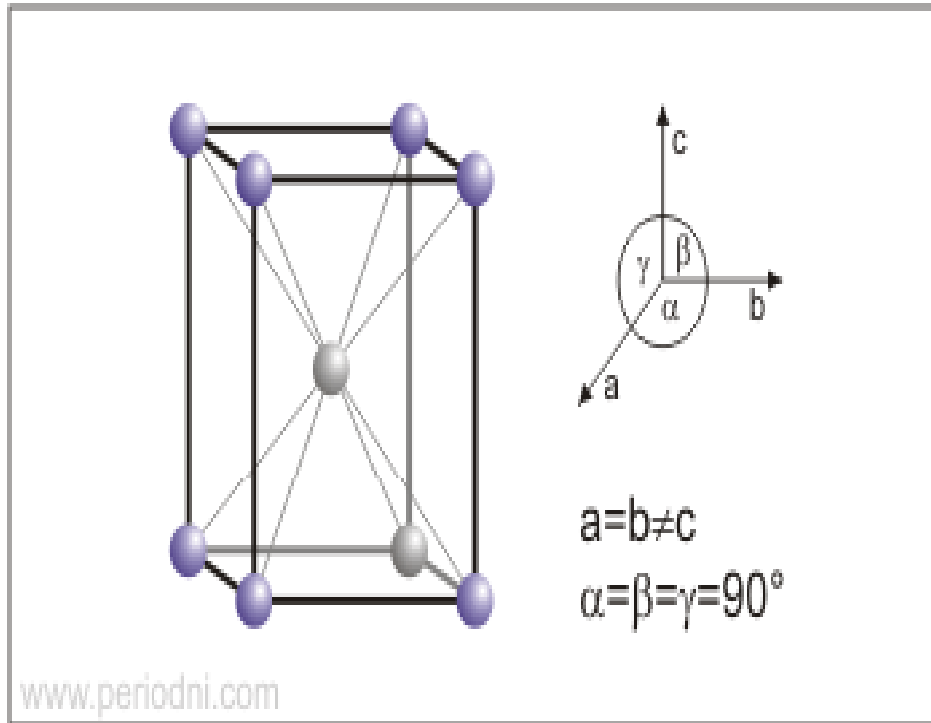
Computational domain

Plate-impact configuration



PETN – Elastic constants

Body Centered Tetragonal Lattice



$a=b=9.380\text{\AA}$ and $c=6.710\text{\AA}$

- Elastic Constants(GPa):
(Winey and Gupta, 2001)

$$\begin{array}{ll} C_{11}=17.22 & C_{33}=12.17 \\ C_{44}=5.04 & C_{66}=3.95 \\ C_{12}=5.44 & C_{13}=7.99 \end{array}$$

- Elastic constants assumed to decrease linearly with temperature, vanish at melting:

$$C_{ij}(\theta, p) = \frac{\theta - \theta_{\text{melt}}(p)}{\theta_0 - \theta_{\text{melt}}(p)}$$

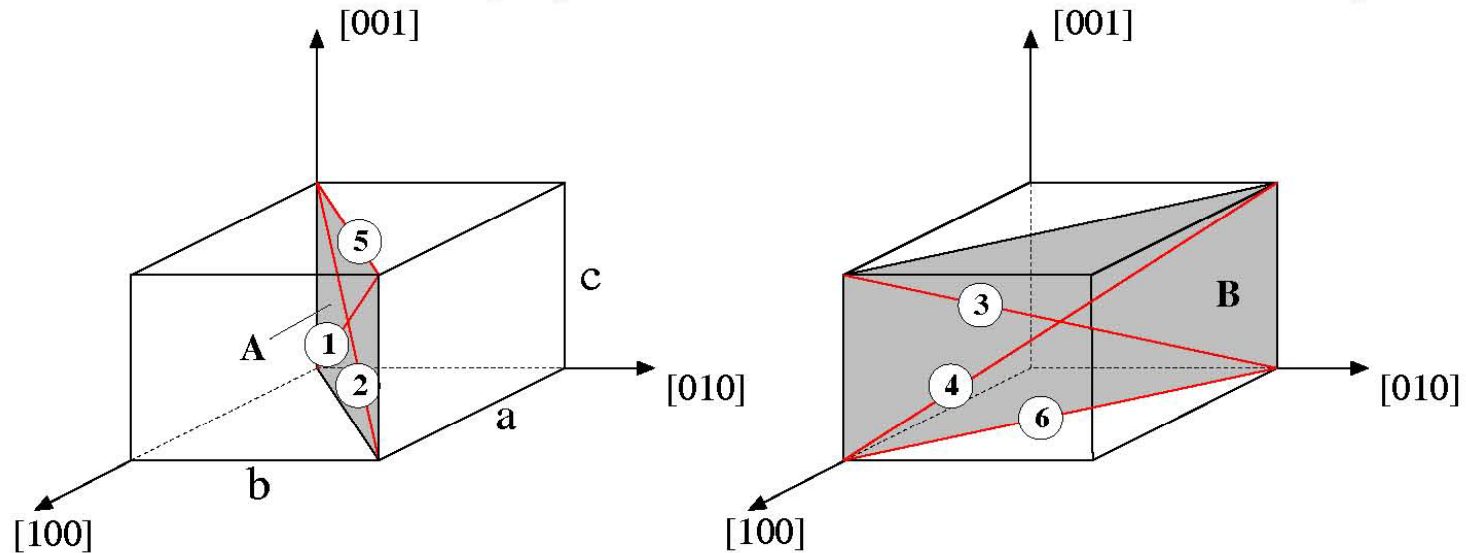
- Menikoff and Sewell (2002): $\theta_{\text{melt}}(p) = \theta_{\text{melt}}(p_0) \left(1 + a \frac{\Delta V}{V_0} \right)$

where $a = 2(\Gamma - 1/3)$, $\Gamma \sim 1.2$ = Grüneisen constant



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PETN – Slip systems



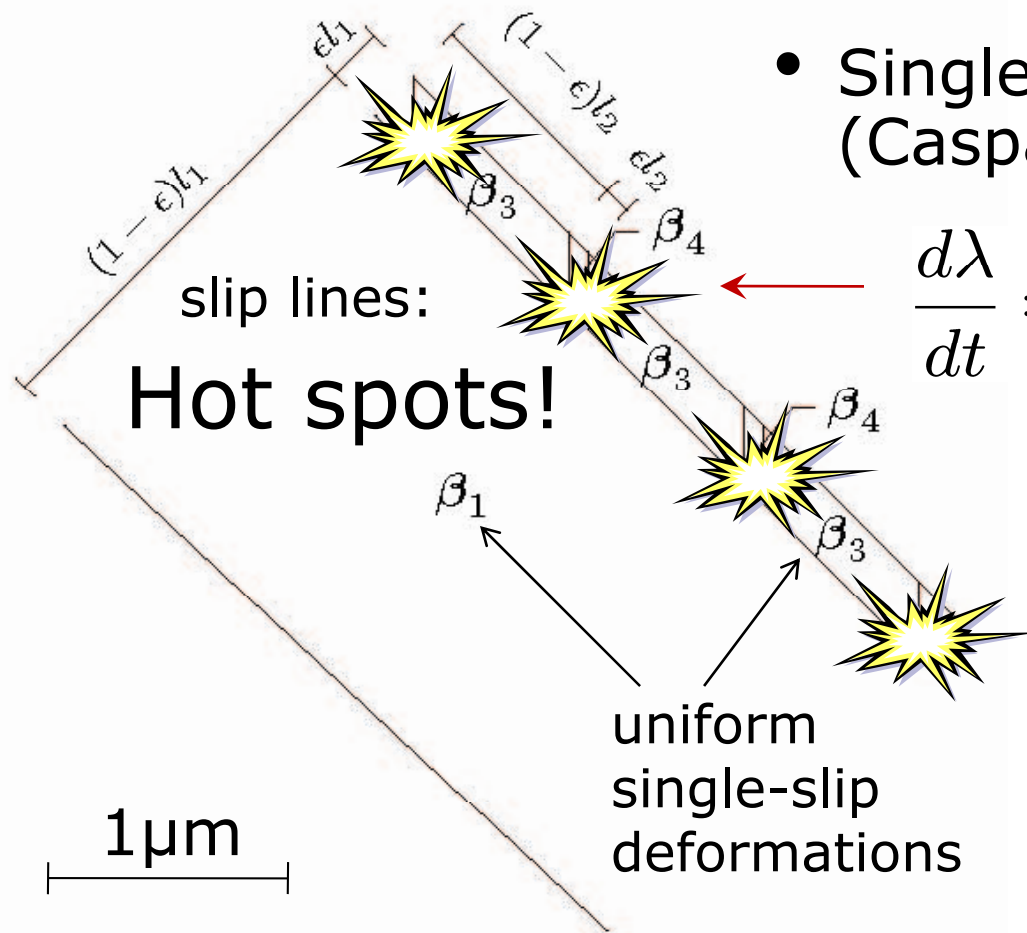
$$a = b = 9.380\text{\AA} \quad c = 6.710\text{\AA}$$

- $\tau_c(\theta)$ fitted to data of Amuzu *et al.* (1976) and:

Slip System	B3	B4	A1	A2	B6	A5
s^a	$\pm[1\bar{1}1]$	$\pm[1\bar{1}\bar{1}]$	$\pm[111]$	$\pm[11\bar{1}]$	$\pm[1\bar{1}0]$	$\pm[\bar{1}\bar{1}0]$
m^a	(110)	(110)	(1 $\bar{1}$ 0)	(1 $\bar{1}$ 0)	(110)	(1 $\bar{1}$ 0)
τ_c [GPa]	1.0	1.0	1.0	1.0	2.0	2.0



PETN – Chemistry



- Single-step reaction kinetics (Caspar *et al.*, 1998):

$$\frac{d\lambda}{dt} = Z(1 - \lambda)\exp\left(-\frac{ER}{\theta}\right)$$

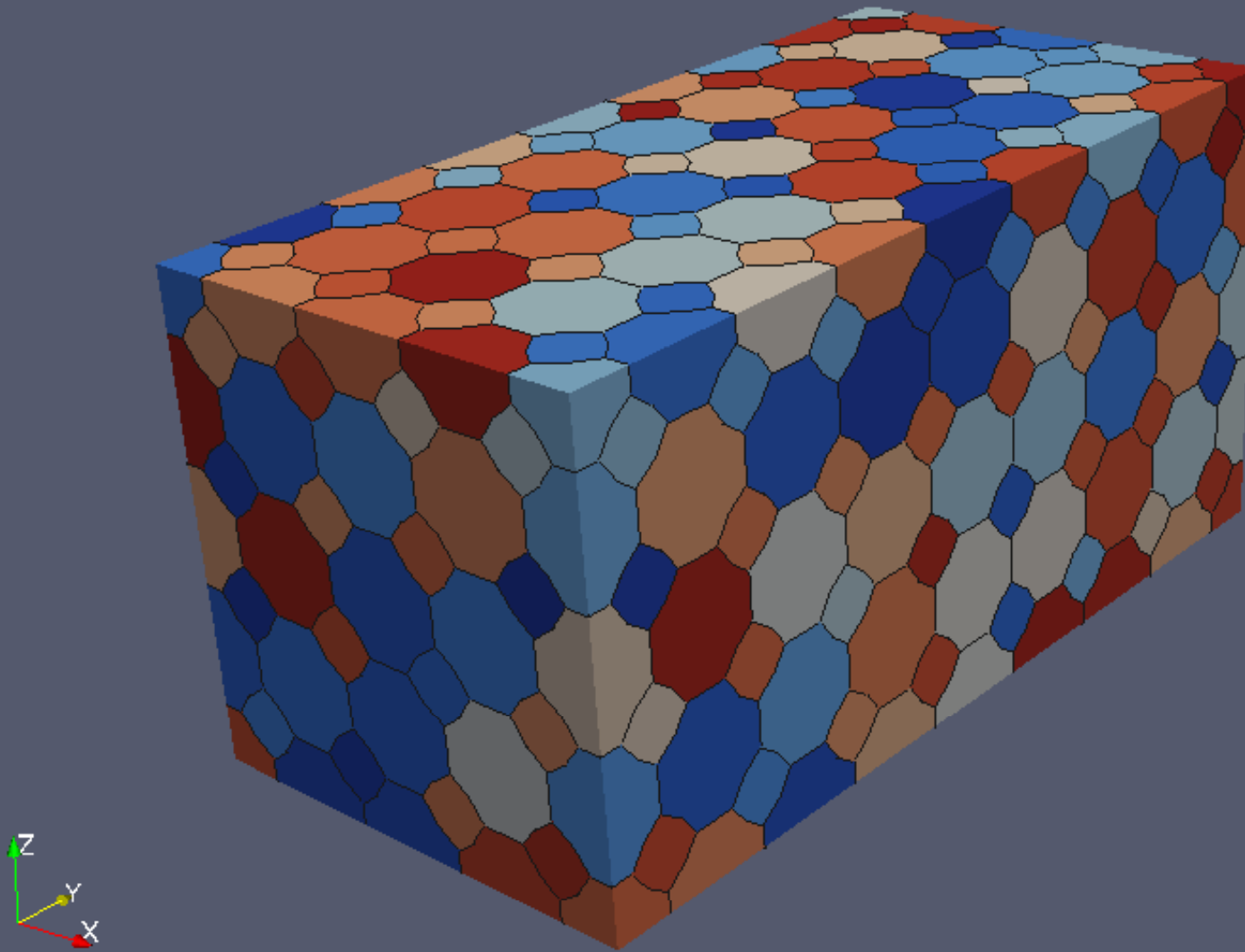
- Activation energy E and rate constant Z from Rogers (1975):

R	8.314 J/mol/K
E	196.742×10^3 J/mol
Z	6.3×10^{19} s ⁻¹

- Temperature computed assuming adiabatic heating, full conversion of plastic work to heat, heat capacity

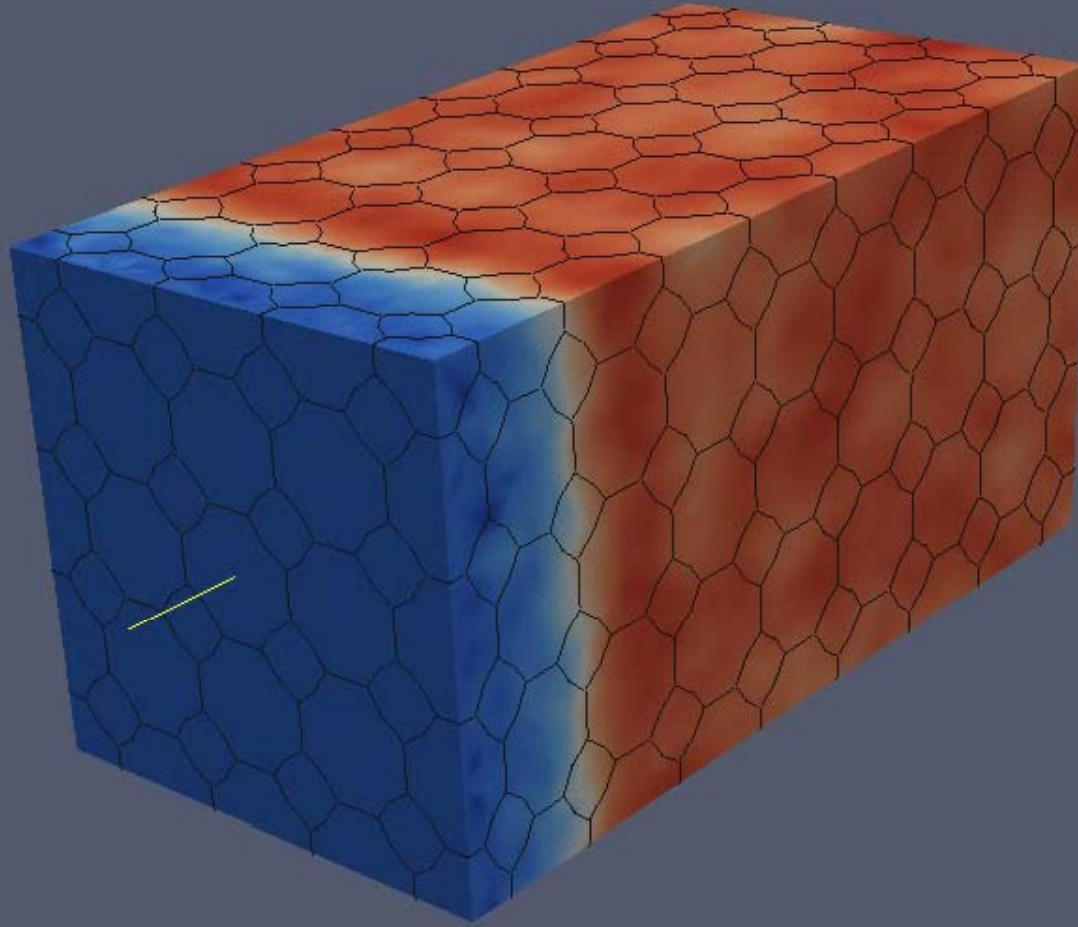


High-Explosives Detonation Initiation

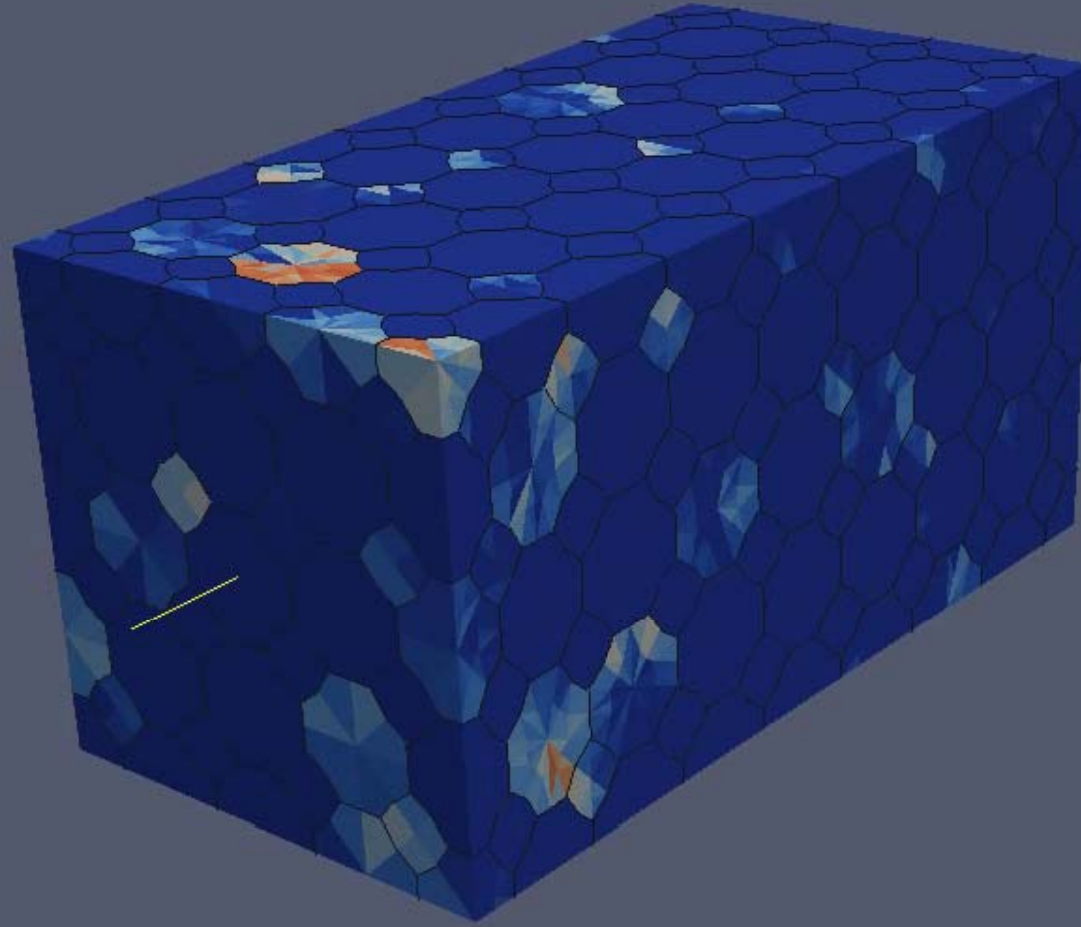


Polycrystal model and grain boundaries

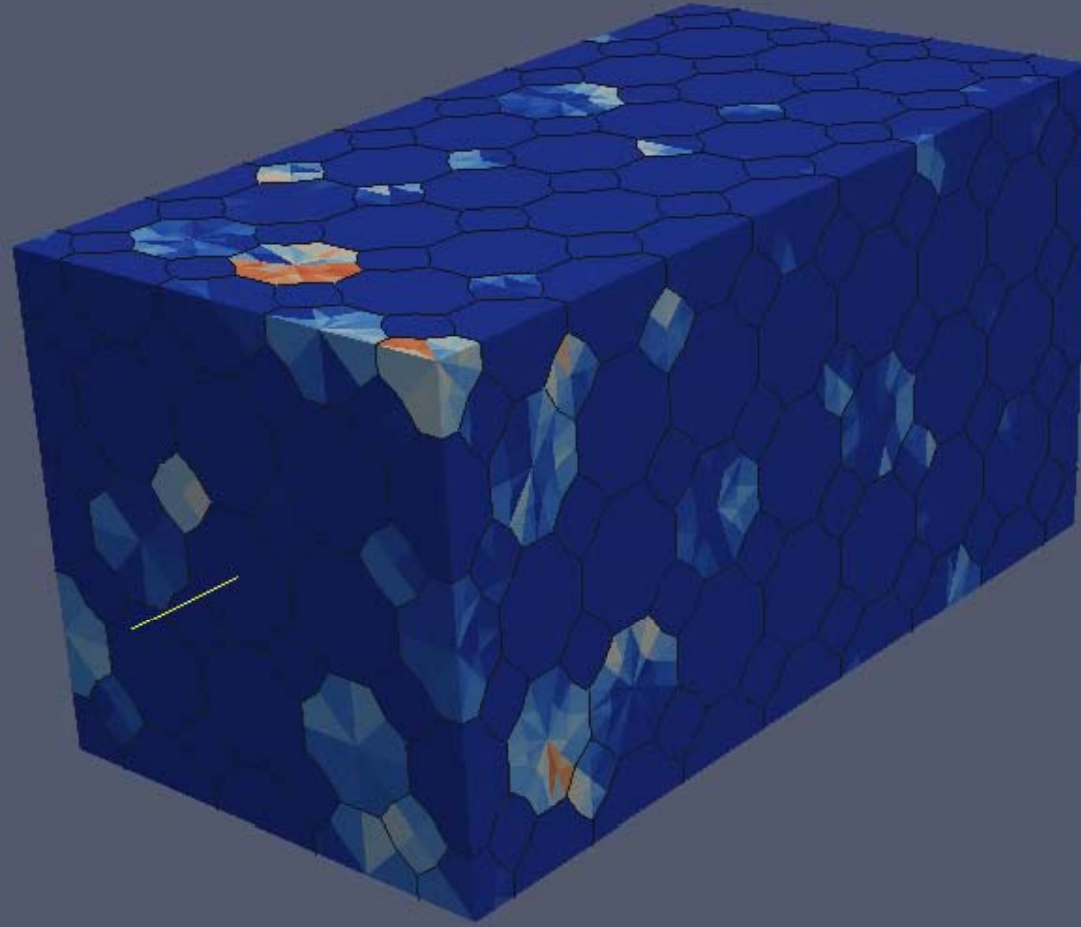
PETN plate impact - Velocity



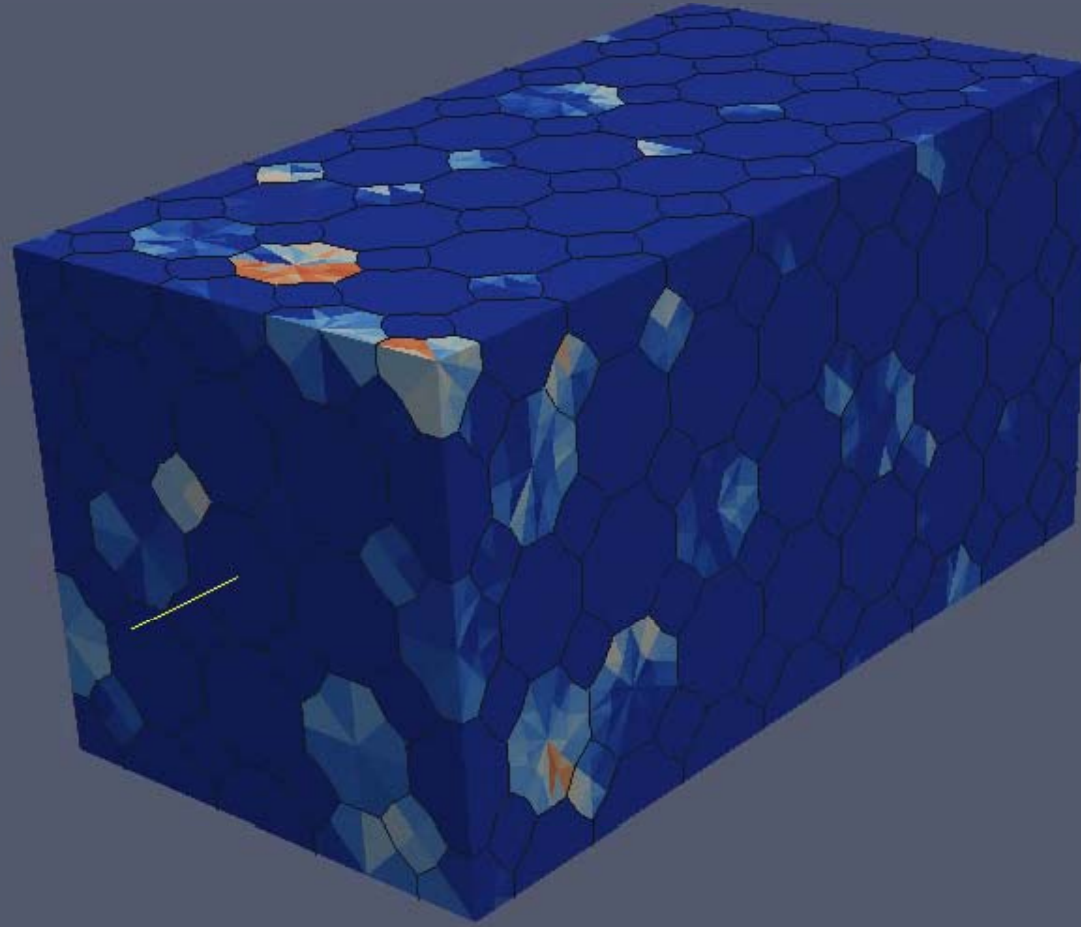
PETN plate impact - temperature



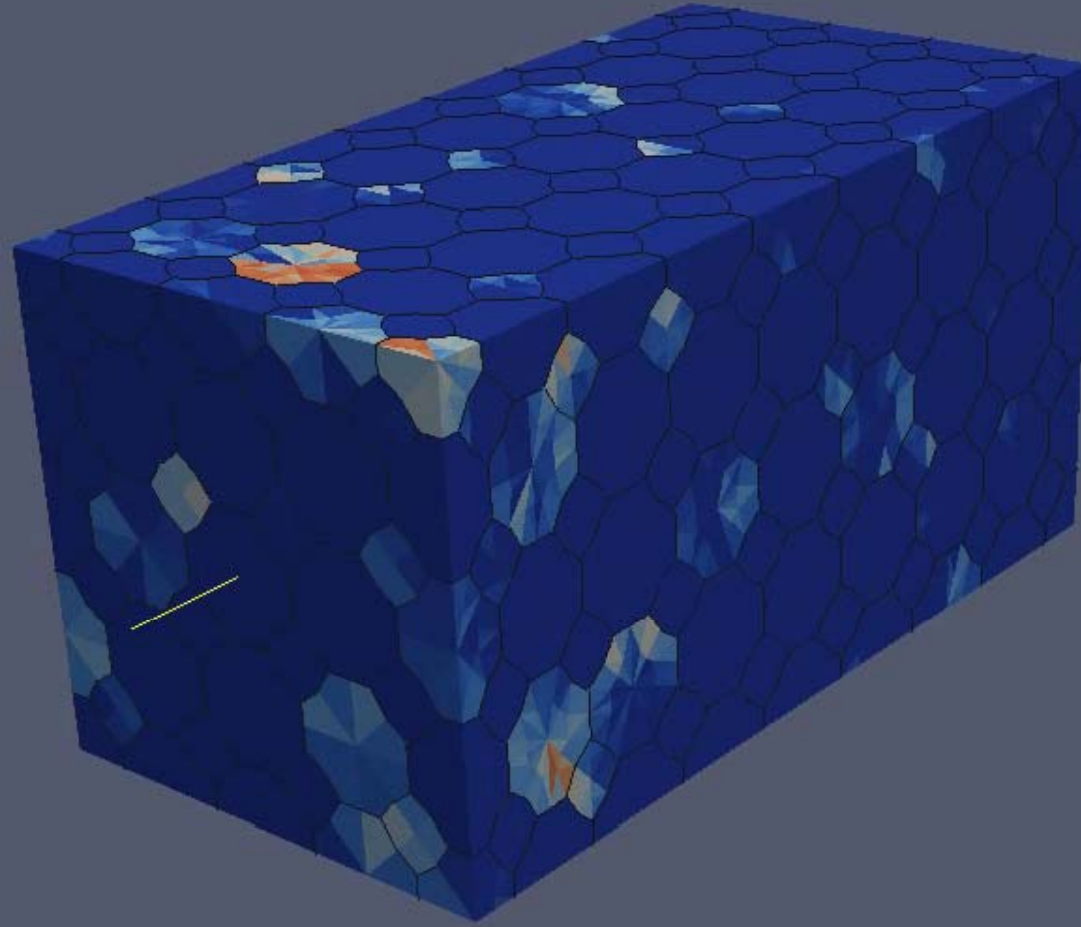
PETN plate impact - temperature



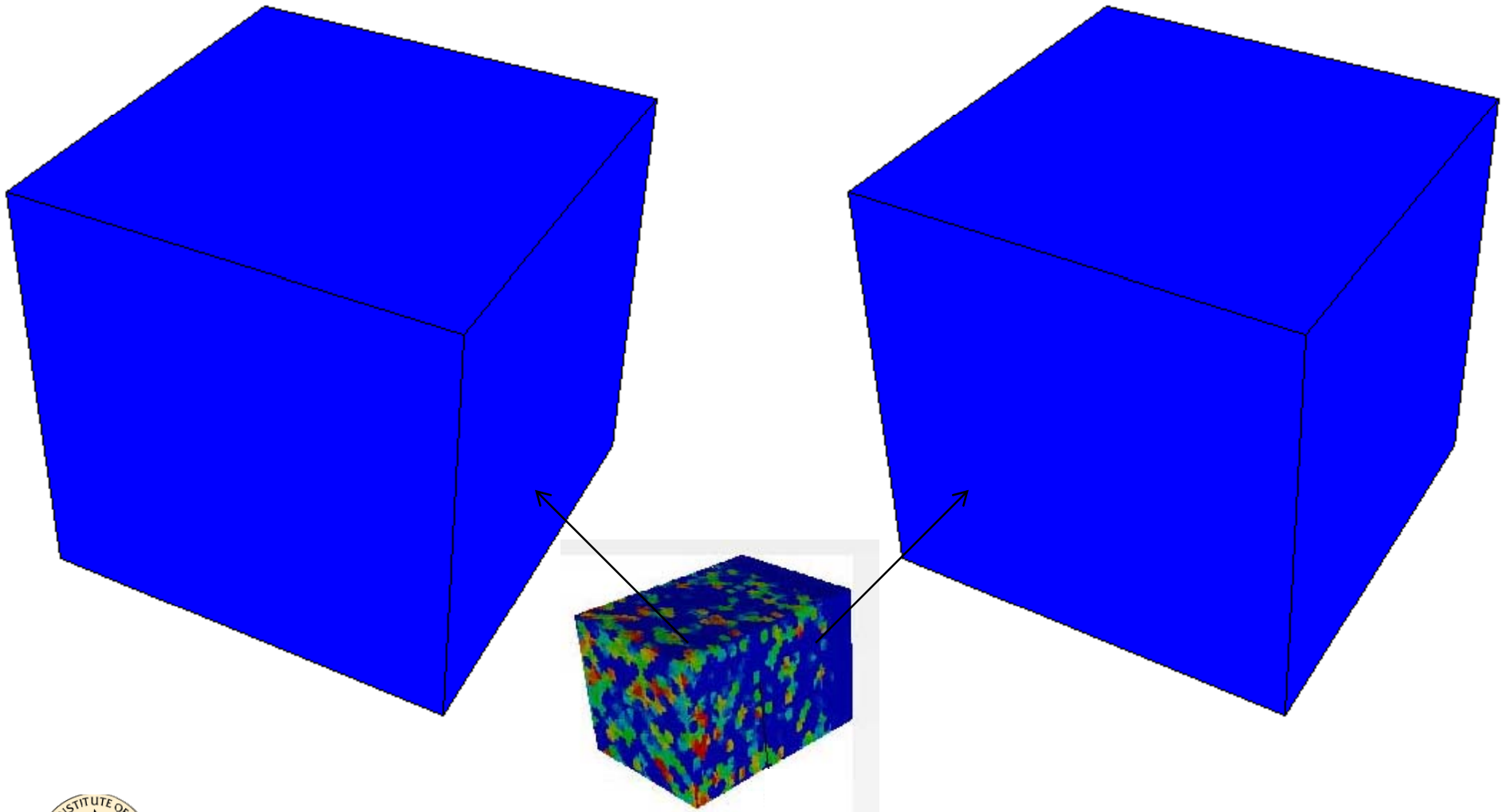
PETN plate impact - temperature



PETN plate impact - temperature



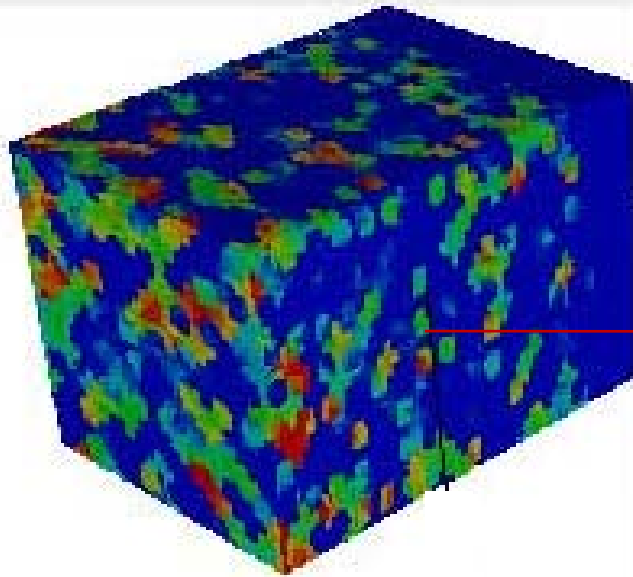
PETN plate impact – Subgrain microstructures



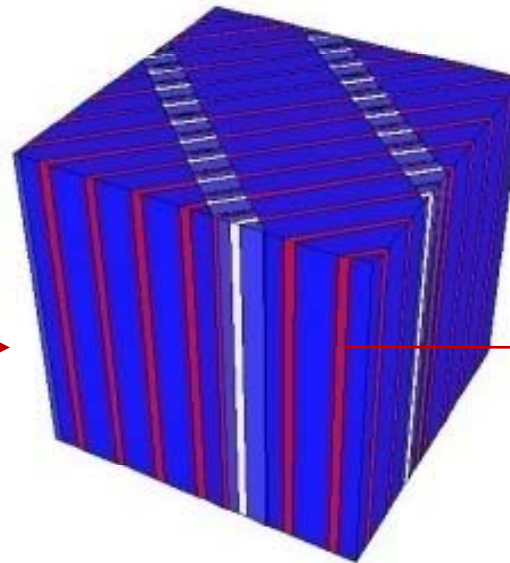
Microstructure evolution at selected material points

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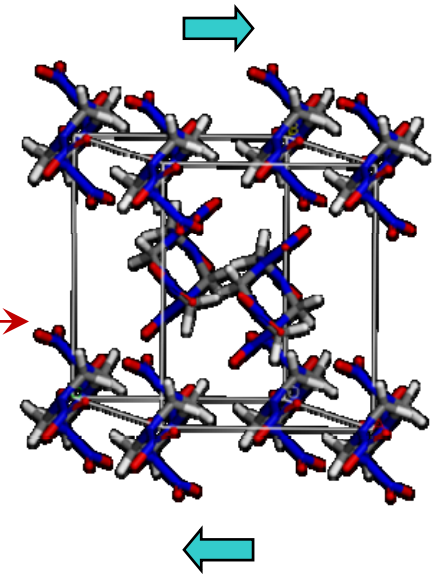
PETN plate impact – Hot-spot analysis



direct numerical
simulation of
polycrystalline
PETN



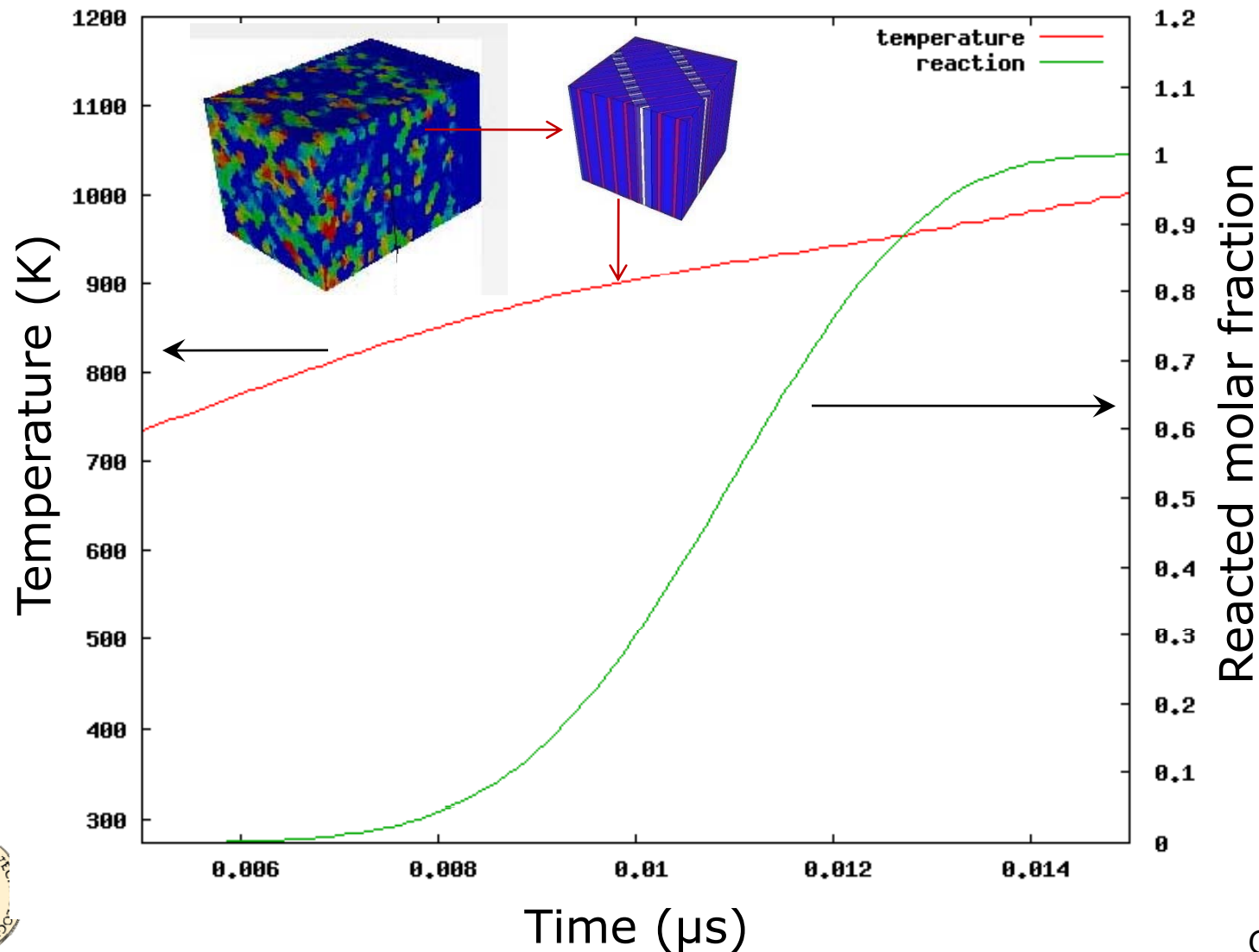
reconstructed
microstructure
at selected
material points



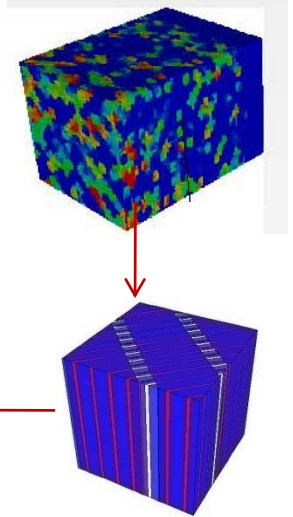
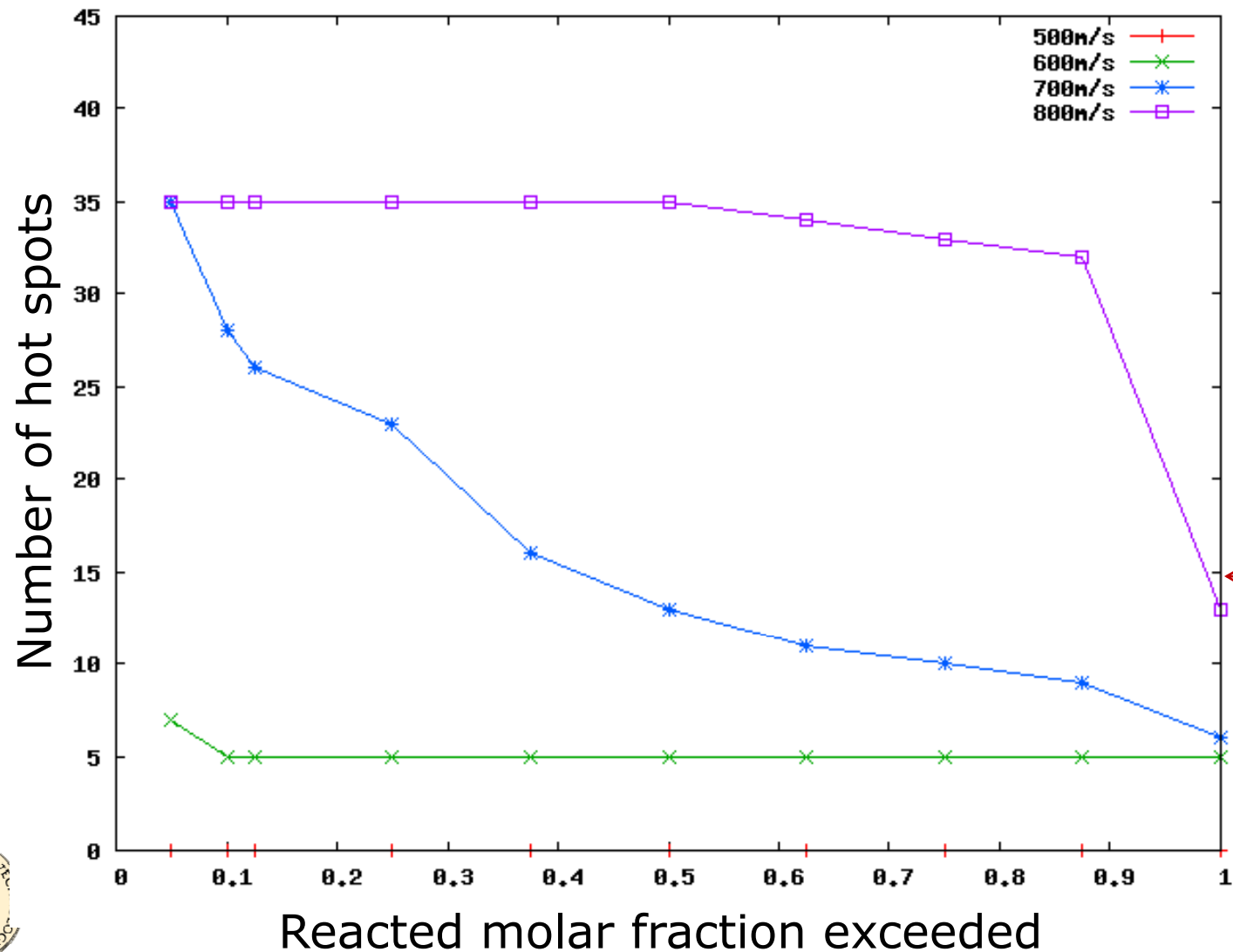
chemical analysis
of hot-spots with
B.C. from
microstructure



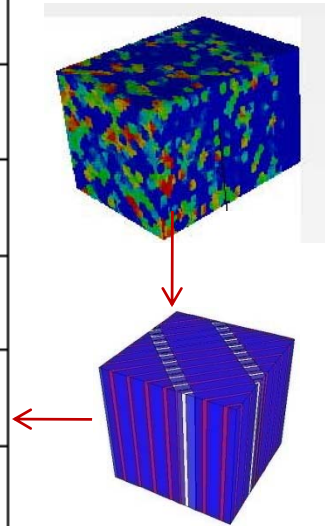
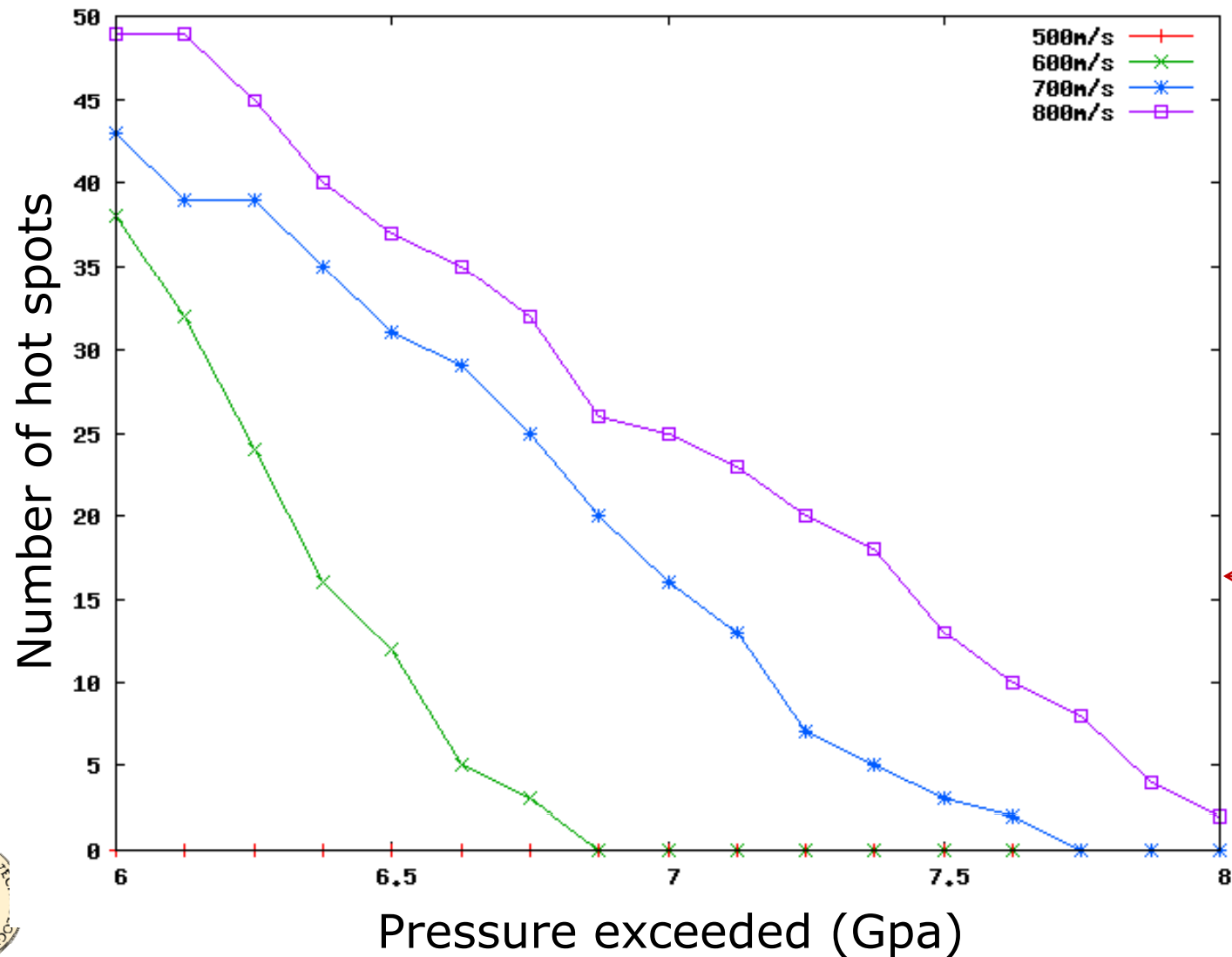
PETN plate impact - temperature and reaction evolution at selected hot spot



PETN plate impact - Number of hot spots

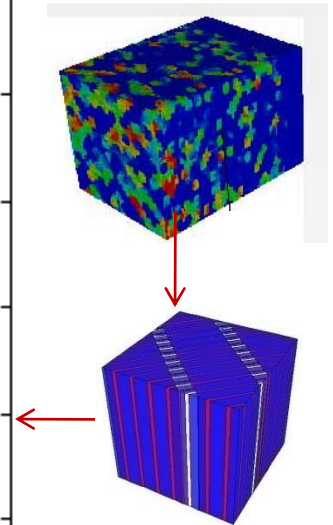
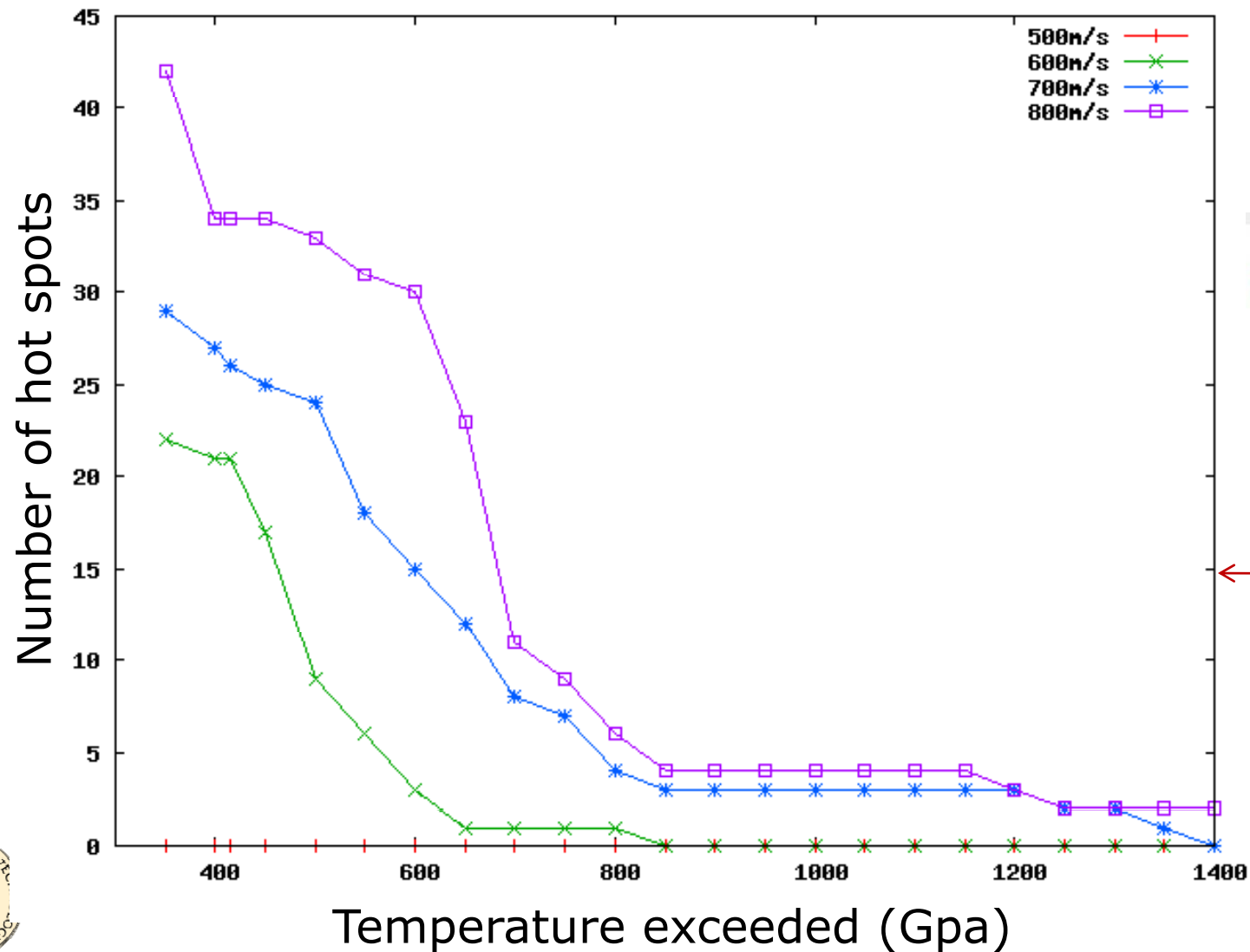


PETN plate impact - Number of hot spots



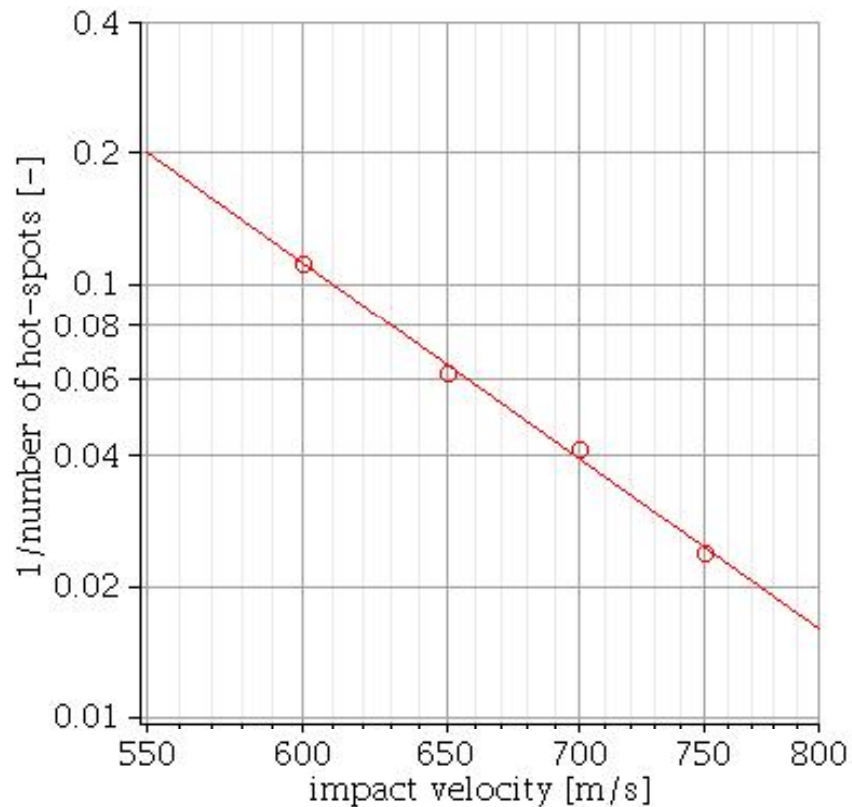
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PETN plate impact - Number of hot spots

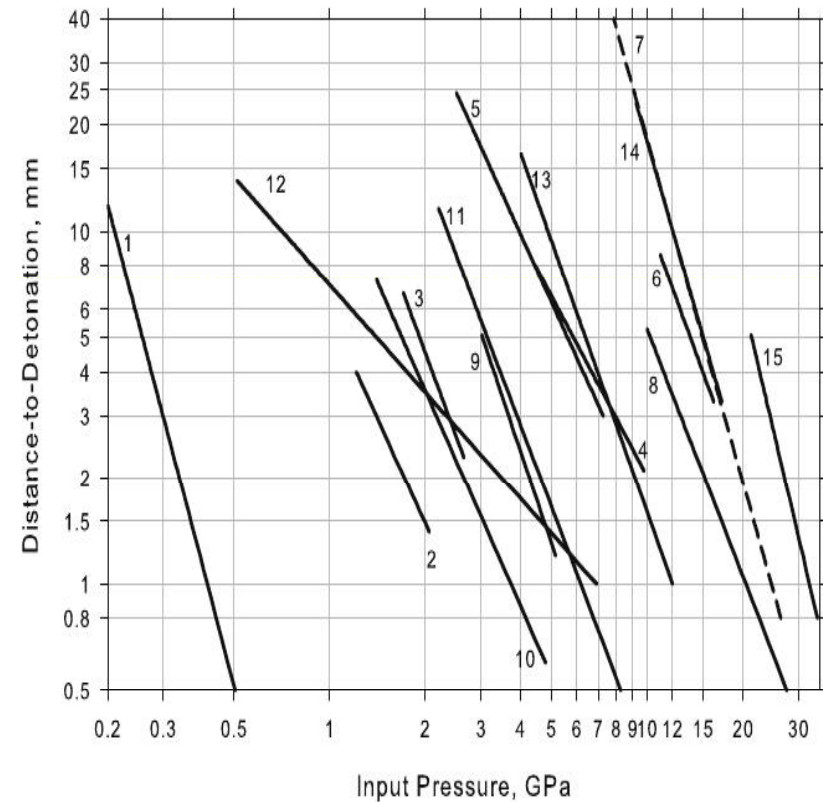


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PETN plate impact – pop-plots



Multiscale model



Sheffield and Engelke
[2009]

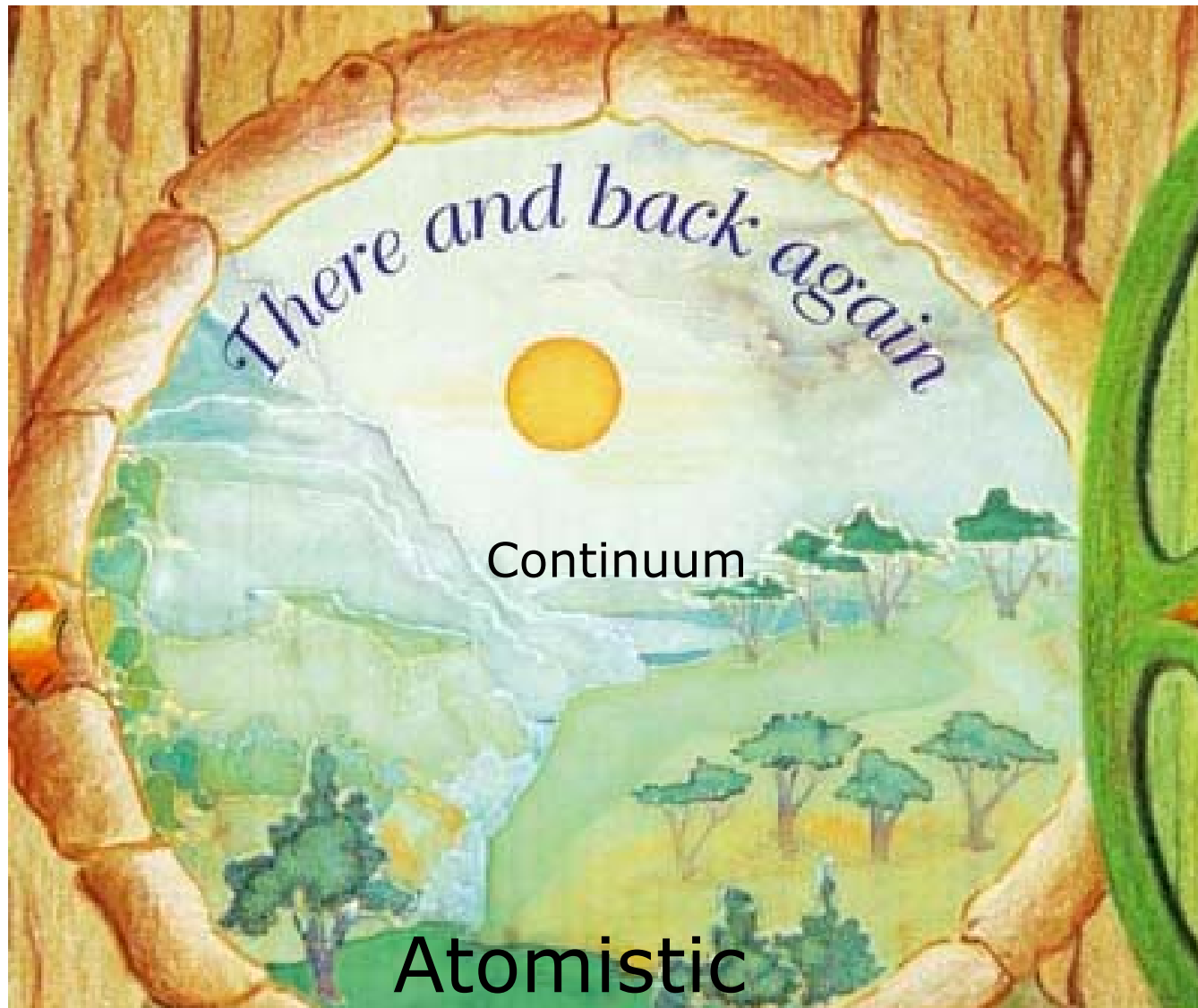


Concluding remarks

- Multiscale scheme bridges:
 - *Macroscopic scale*
 - *Polycrystalline structure*
 - *Subgrain heterogeneous slip*
- Calculations are based on relaxed model → Can simulate large samples over long times
- Subgrain deformation microstructures reconstructed *a posteriori* → B.C. for detailed atomistic calculations including chemistry
- Limitations of present capability:
 - *Static relaxation: Need relaxation theory that accounts for kinetics and inertia*
 - *Linearized kinematics: Need relaxation of crystal plasticity at large strains*

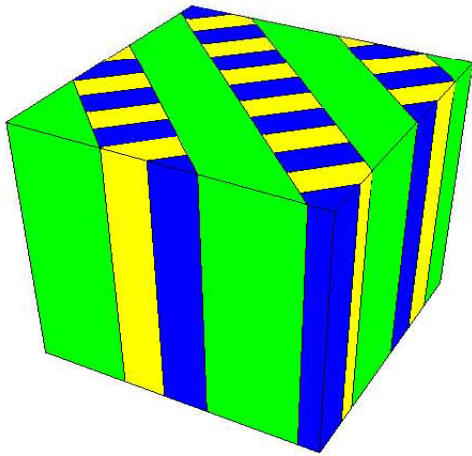


Atomistic to Continuum (and back again)

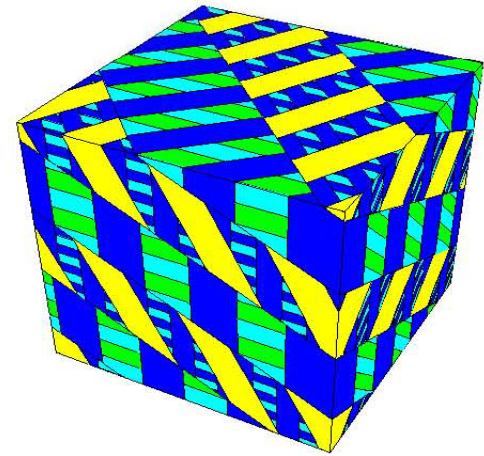


Relaxation – Fast multiscale models

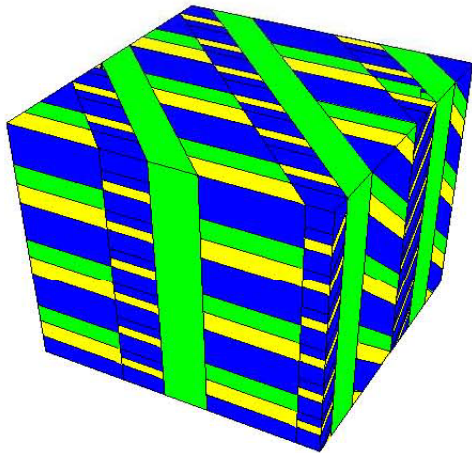
rank 2/2, $|\gamma|_{\infty} = 0.0025$



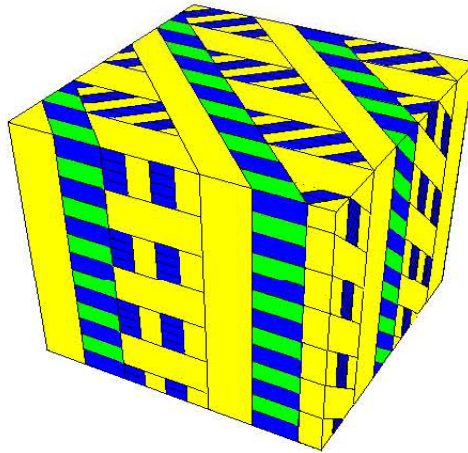
rank 4/14, $|\gamma|_{\infty} = 0.43$



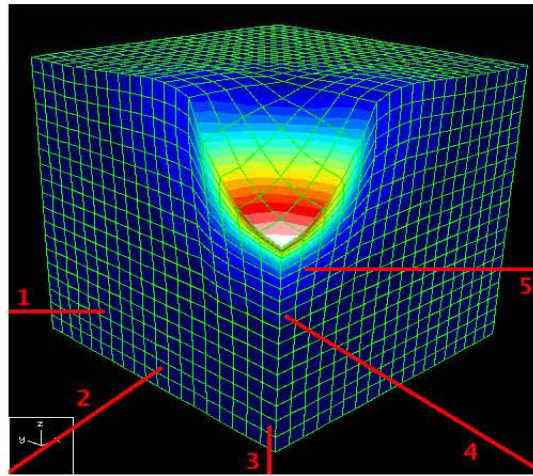
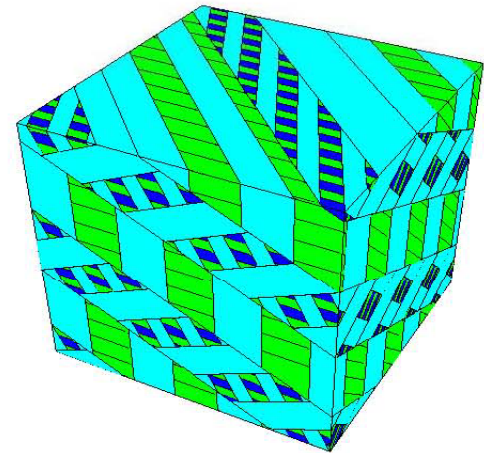
rank 4/12, $|\gamma|_{\infty} = 0.02$



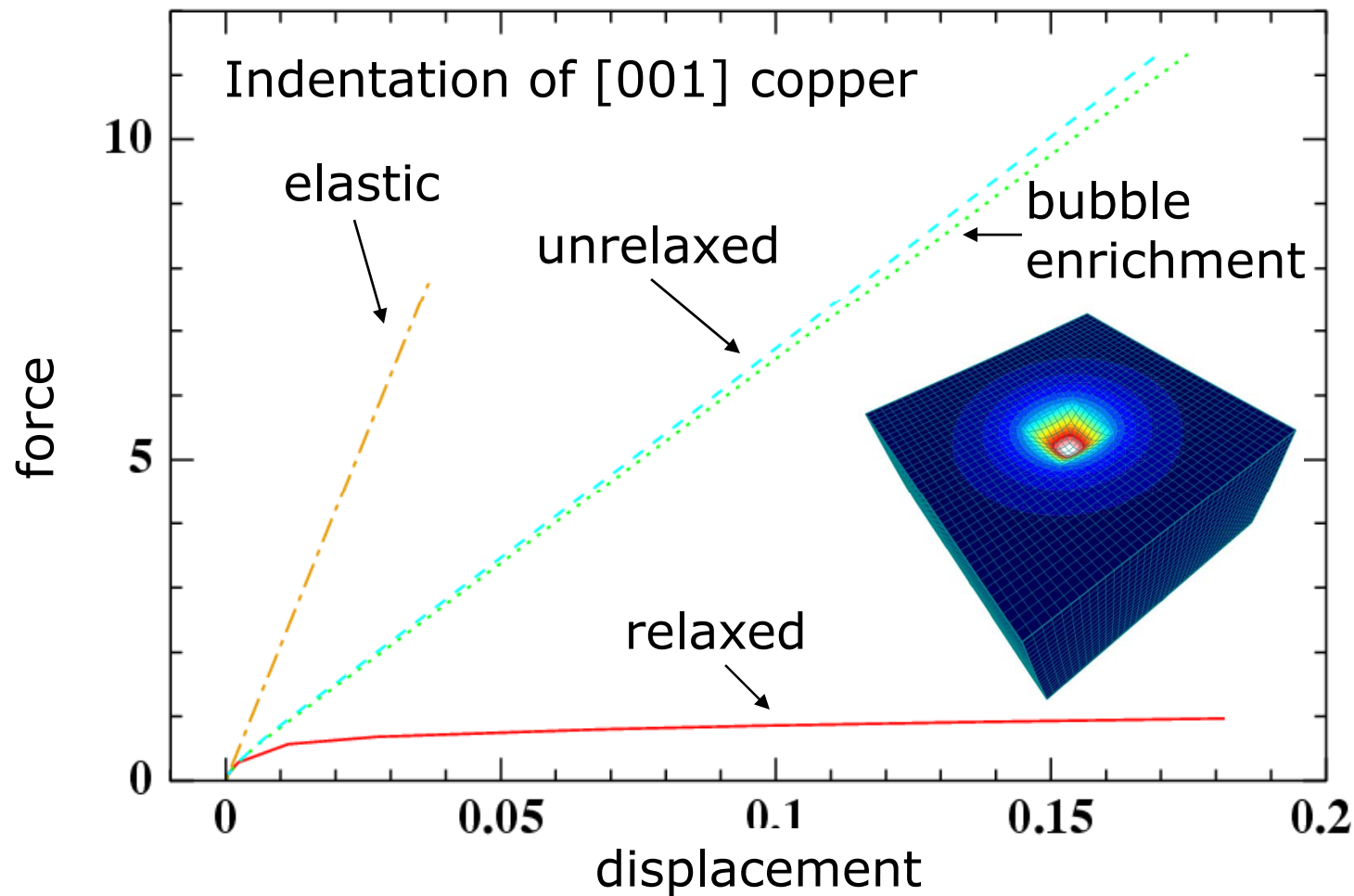
rank 4/6, $|\gamma|_{\infty} = 0.026$



rank 4/16, $|\gamma|_{\infty} = 0.21$



Relaxation – Fast multiscale models



(S Conti, P Hauret and M Ortiz, *SIAM Multiscale Model. Simul.* **6**(1), 2007, pp. 135–157)

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